

6 Hashing

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The dictionary problem



Different approaches to the dictionary problem:

- Previously: Structuring the set of **currently stored** keys: **lists, trees, graphs, ...**
- Structuring the complete universe of all **possible** keys: **hashing**

Hashing describes a special way of storing the elements of a set by **breaking down the universe of possible keys**.

The **position of the data element** in the memory is given by computing a so called hash value directly from the **key**.

Hashing



Dictionary problem:

Lookup, insertion, deletion of data sets (keys)

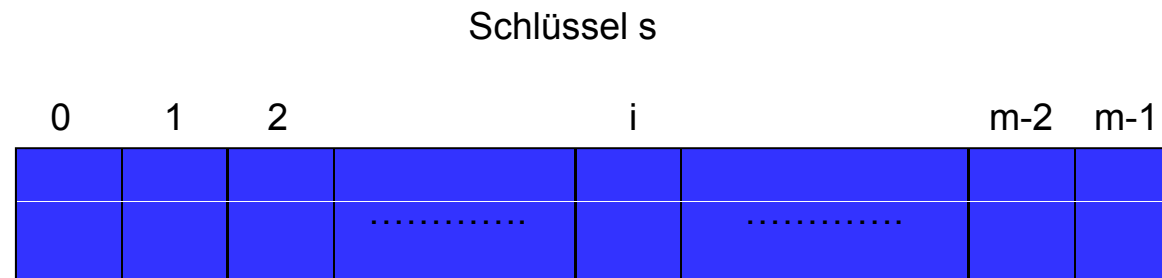
Place of data set d : computed from the key s of d

→ no comparisons

→ constant time

Data structure: linear field (array) of size m

Hash table



The memory is divided in m containers (buckets) of the same size.

Hash tables - examples



Examples:

- Compilers
i int 0x87C50FA4
j int 0x87C50FA8
x double 0x87C50FAC
name String 0x87C50FB2
...
- Environment variables (key, attribute) list
EDITOR=emacs
GROUP=mitarbeiter
HOST=vulcano
HOSTTYPE=sun4
LPDEST=hp5
MACHTYPE=sparc
...
- Executable programs
PATH=~ /bin:/usr/local/gnu/bin:/usr/local/bin:/usr/bin:/bin:

Implementation in Java



```
class TableEntry {
    private Object key,value;
}
abstract class HashTable {
    private TableEntry[] tableEntry;
    private int capacity;
    // Konstruktor
    HashTable (int capacity) {
        this.capacity = capacity;
        tableEntry = new TableEntry [capacity];
        for (int i = 0; i <= capacity-1; i++)
            tableEntry[i] = null;
    }
    // the hash function
    protected abstract int h (Object key);
    // insert element with given key and value (if not there already)
    public abstract void insert (Object key Object value);
    // delete element with given key (if there)
    public abstract void delete (Object key);
    // locate element with given key
    public abstract Object search (Object key);
} // class hashTable
```

Hashing - problems



1. Size of the hash table
Only a small subset S of all possible keys (the **universe**) U actually occurs
2. Calculation of the address of a data set
 - keys are not necessarily integers
 - index depends on the size of hash table

In Java:

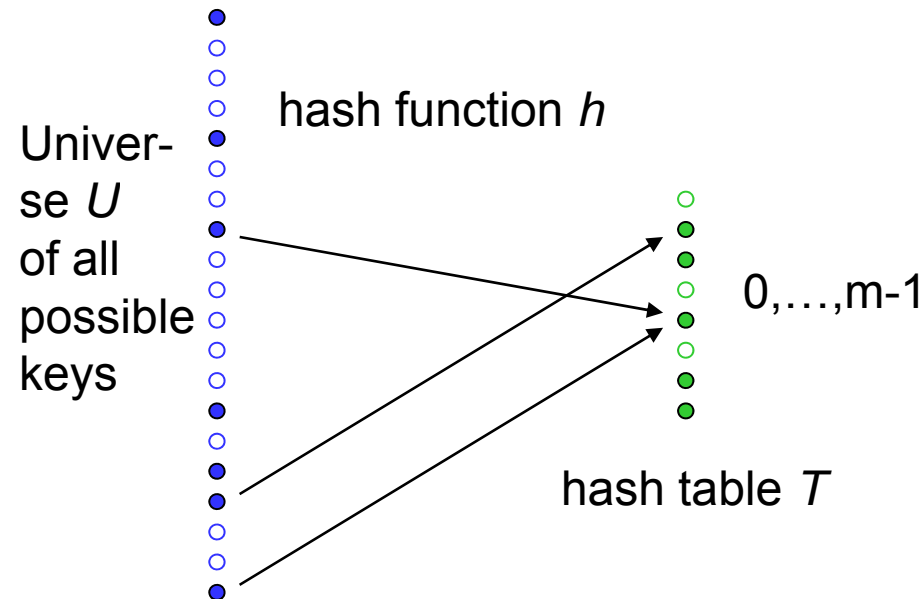
```
public class Object {  
    ...  
    public int hashCode() {...}  
    ...  
}
```

The universe U should be distributed as **evenly** as possible to the numbers $-2^{31}, \dots, 2^{31}-1$.

Hash function (1)



Set of keys S



$$(H(u) \subseteq [-2^{31}, 2^{31}])$$

$h(s) =$ **hash address**

$h(s) = h(s') \Leftrightarrow s$ and s' are **synonyms** with respect to h
address collision

Hash function (2)

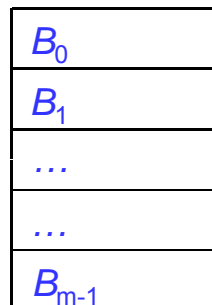


Definition: Let U be a universe of possible keys and $\{B_0, \dots, B_{m-1}\}$ a set of m buckets for storing elements from U . Then a **hash function**

$$h : U \rightarrow \{0, \dots, m - 1\}$$

maps each key $s \in U$ to a *value* $h(s)$
(and the corresponding element to the bucket $B_{h(s)}$).

- The indices of the buckets also called **hash addresses**, the complete set of buckets is called **hash table**.



Address collisions



- A **hash function** h calculates for each key s the index of the associated bucket.
- It would be ideal if the mapping of a data set with key s to a bucket $h(s)$ was **unique (one-to-one)**: insertion and lookup could be carried out in **constant time** ($O(1)$).
- In reality, there will be **collisions**: several elements can be mapped to the same **hash address**. Collisions have to be addressed (in one way or another).

Hashing methods



Example for U : all names in Java with length $\leq 40 \rightarrow |U| = 62^{40}$

If $|U| > m$: address collisions are inevitable

Hashing methods:

1. Choice of a hash function that is as “good” as possible
2. Strategy for resolving address collisions

Load factor α : $\alpha = \frac{\text{\# of stored keys}}{\text{size of hash table}} = \frac{|S|}{m} = \frac{n}{m}$

Assumption: table size m is fixed

Requirements for good hash functions



Requirements

- A **collision** occurs if the bucket $B_{h(s)}$ for a newly inserted element with key s is not empty.
- A hash function h is called **perfect** for a set S of keys if no collisions occur for S .
- If h is perfect and $|S| = n$, then $n \leq m$.
The **load factor** of the hash table is $n/m \leq 1$.
- A hash function is **well chosen** if
 - the load factor is as high as possible,
 - for many sets of keys the # of collisions is as small as possible,
 - it can be computed efficiently.

Example of a hash function



Example: hash function for strings

```
public static int h (String s){  
    int k = 0, m = 13;  
    for (int i=0; i < s.length(); i++)  
        k += (int)s.charAt (i);  
    return ( k%m );  
}
```

The following hash addresses are generated for $m = 13$.

| key s | $h(s)$ |
|---------|--------|
| Test | 0 |
| Hallo | 2 |
| SE | 9 |
| Algo | 10 |

The greater the choice of m , the more perfect h becomes.

Probability of collision (1)



Choice of the hash function

- The requirements **high load factor** and **small number of collisions** are in conflict with each other. We need to find a suitable compromise.
- For the set S of keys with $|S| = n$ and buckets B_0, \dots, B_{m-1} :
 - for $n > m$ conflicts are inevitable
 - for $n < m$ there is a (residual) probability $P_K(n, m)$ for the occurrence of at least one collision.

How can we find an estimate for $P_K(n, m)$?

- For any key s the probability that $h(s) = j$ with $j \in \{0, \dots, m - 1\}$ is:
 $P_K[h(s) = j] = 1/m$, provided that there is an equal distribution.
- We have $P_K(n, m) = 1 - P_{\neg K}(n, m)$,
if $P_{\neg K}(n, m)$ is the probability that storing of n elements in m buckets leads to no collision.

Probability of collision (2)



On the probability of collisions

- If n keys are distributed sequentially to the buckets B_0, \dots, B_{m-1} (with equal distribution), each time we have $P[h(s) = j] = 1/m$.
- The probability $P(i)$ for no collision in step i is $P(i) = (m - (i - 1))/m$
- Hence, we have

$$P_K(n, m) = 1 - P(1) * P(2) * \dots * P(n) = 1 - \frac{m(m-1)\dots(m-n+1)}{m^n}$$

For example, if $m = 365$, $P(23) > 50\%$ and $P(50) \approx 97\%$ (“birthday paradox”)

Common hash functions



Hash functions used in practice:

- see: D.E. Knuth: *The Art of Computer Programming*
- For $U = \text{integer}$ the [divisions-residue method] is used:
$$h(s) = (a \times s) \bmod m \quad (a \neq 0, a \neq m, m \text{ prime})$$
- For strings of characters of the form $s = s_0 s_1 \dots s_{k-1}$ one can use:

$$h(s) = \left(\left(\sum_{i=0}^{k-1} B^i s_i \right) \bmod 2^w \right) \bmod m$$

e.g. $B = 131$ and $w = \text{word width (bits) of the computer}$ ($w = 32$ or $w = 64$ is common).

Simple hash functions



Choice of the hash function

- simple and quick computation
- even distribution of the data (example: compiler)

(Simple) division-residue method

$$h(k) = k \bmod m$$

How to choose of m ?

Examples:

a) m even $\rightarrow h(k)$ even $\iff k$ even

Problematic if the last bit has a meaning (e.g. 0 = female, 1 = male)

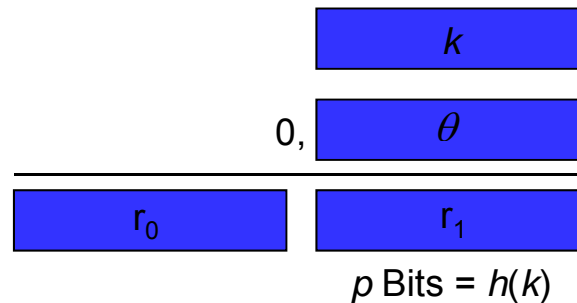
b) $m = 2^p$ yields the p lowest dual digits of k

Rule: Choose m prime, and m is not a factor of any $r^i +/ - j$, where i and j are small, non-negative numbers and r is the radix of the representation.

Multiplicative method (1)



- Choose constant $\theta, 0 < \theta < 1$
- 1. Compute $k\theta \bmod 1 = k\theta - \lfloor k\theta \rfloor$
- 2. $h(k) = \lfloor m(k\theta \bmod 1) \rfloor$
- Choice of m is uncritical, choose $m = 2^p$:
- Computation of $h(k)$:



Multiplicative method (2)



- Example:

$$\theta = \frac{\sqrt{5}-1}{2} \approx 0.1680339$$

$$k = 123456$$

$$m = 10000$$

$$\begin{aligned} h(k) &= \lfloor 10000(123456 * 0.1680339... \text{mod } 1) \rfloor \\ &= \lfloor 10000(76300.41151... \text{mod } 1) \rfloor \\ &= \lfloor 41.151... \rfloor = 41 \end{aligned}$$

- Of all numbers $0 \leq \theta \leq 1$, $\frac{\sqrt{5}-1}{2}$ leads to the most even distribution.

Universal hashing



- **Problem:** if h is fixed \rightarrow there are $S \subseteq M$ with many collisions
- **Idea of universal hashing:**
Choose hash function h **randomly**

- H finite set of hash functions

$$h \in H : U \rightarrow \{0, \dots, m - 1\}$$

- **Definition:** H is **universal**, if for arbitrary $x, y \in U$:

$$\frac{|\{h \in H : h(x) = h(y)\}|}{|H|} \leq \frac{1}{m}$$

- Hence: if $x, y \in U$, H universal, $h \in H$ picked randomly

$$\Pr_H (h(x) = h(y)) \leq \frac{1}{m}$$

A universal class of hash functions



Assumptions:

- $|U| = p$ (p prime) and $U = \{0, \dots, p-1\}$
- Let $a \in \{1, \dots, p-1\}$, $b \in \{0, \dots, p-1\}$ and $h_{a,b} : U \rightarrow \{0, \dots, m-1\}$ be defined as follows

$$h_{a,b} = ((ax+b) \bmod p) \bmod m$$

Then:

The set

$$H = \{h_{a,b} \mid 1 \leq a < p, 0 \leq b < p\}$$

is a **universal class of hash functions**.

Universal hashing – example



Hash table T of size 3, $|U| = 5$

Consider the 20 functions (set H):

| | | | |
|-------|--------|--------|--------|
| $x+0$ | $2x+0$ | $3x+0$ | $4x+0$ |
| $x+1$ | $2x+1$ | $3x+1$ | $4x+1$ |
| $x+2$ | $2x+2$ | $3x+2$ | $4x+2$ |
| $x+3$ | $2x+3$ | $3x+3$ | $4x+3$ |
| $x+4$ | $2x+4$ | $3x+4$ | $4x+4$ |

each (mod 5) (mod 3)

and the keys 1 und 4

We get:

$$(1 \cdot 1 + 0) \bmod 5 \bmod 3 = 1 = (1 \cdot 4 + 0) \bmod 5 \bmod 3$$

$$(1 \cdot 1 + 4) \bmod 5 \bmod 3 = 0 = (1 \cdot 4 + 4) \bmod 5 \bmod 3$$

$$(4 \cdot 1 + 0) \bmod 5 \bmod 3 = 1 = (4 \cdot 4 + 0) \bmod 5 \bmod 3$$

$$(4 \cdot 1 + 4) \bmod 5 \bmod 3 = 0 = (4 \cdot 4 + 4) \bmod 5 \bmod 3$$

Possible ways of treating collisions



Treatment of collisions:

- Collisions are treated differently in different methods.
- A data set with key s is called a **colliding element** if bucket $B_{h(s)}$ is already taken by another data set.
- What can we do with colliding elements?
 1. **Chaining**: Implement the buckets as linked lists. Colliding elements are stored in these lists.
 2. **Open Addressing**: Colliding elements are stored in other vacant buckets. During storage and lookup, these are found through so-called **probing**.