



# Algorithms Theory

11 - Shortest Paths

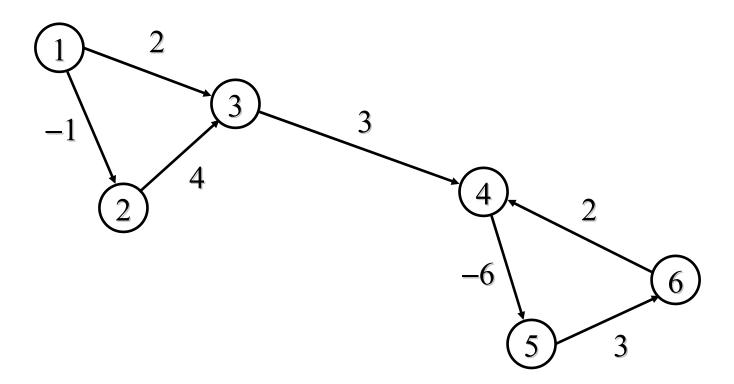
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Directed graph G = (V, E)

Cost function  $c: E \rightarrow R$ 







Cost of a path  $P = v_0, v_1, \dots, v_l$  from u to v:

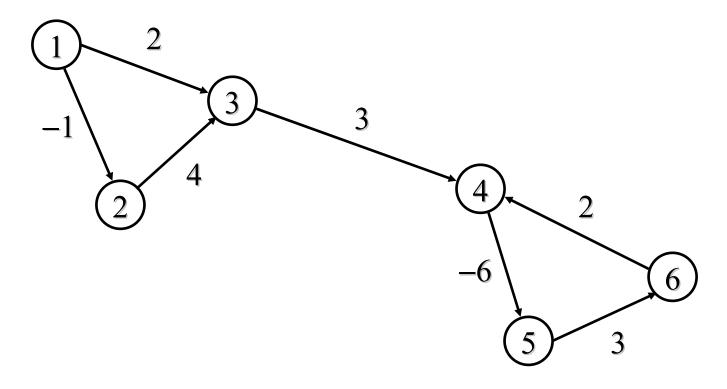
$$c(P) = \sum_{i=0}^{l-1} c(v_i, v_{i+1})$$

Distance between *u* and *v* (not always defined):

 $dist(v, w) = \inf \{ c(P) \mid P \text{ is a path from } u \text{ to } v \}$ 

## Example





$$dist(1,2) =$$

$$dist(1,3) =$$

$$dist(3,4) =$$



## 2. Single-source shortest paths problem

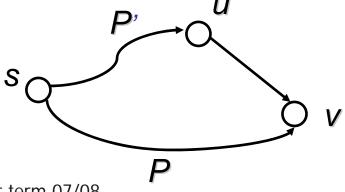
**Input:** network  $G = (V, E, c), c : E \rightarrow R$ , vertex s

**Output:** dist(s, v) for all  $v \in V$ 

**Observation:** The function *dist* satisfies the triangle inequality.

For any edge  $(u,v) \in E$ :

$$dist(s,v) \leq dist(s,u) + c(u,v)$$



P =shortest path from s to v

P' =shortest path from s to u





1. Overestimate the function *dist* 

$$dist(s,v) = \begin{cases} 0 & \text{if } v = s \\ \infty & \text{if } v \neq s \end{cases}$$

2. While there exists an edge e = (u, v) with

$$dist(s,v) > dist(s,u) + c(u,v)$$

set  $dist(s,v) \leftarrow dist(s,u) + c(u,v)$ 

## Generic algorithm



```
    DIST[s] ← 0;
    for all v ∈ V\{s} do DIST[v] ← ∞ endfor;
    while ∃ e = (u,v) ∈ E with DIST[v] > DIST[u] + c(u,v) do
    Choose such an edge e = (u,v);
    DIST[v] ← DIST[u] + c(u,v);
```

#### Questions:

6. endwhile;

- 1. How can we check in line 3 if the triangle inequality is violated?
- 2. Which edge shall we choose in line 4?

### Solution



Maintain a set *U* of all those vertices that might have an outgoing edge violating the triangle inequality.

- Initialize  $U = \{s\}$
- Add vertex *v* to *U* whenever DIST[*v*] decreases.

- 1. Check if the triangle inequality is violated:  $U \neq \emptyset$ ?
- 2. Choose a vertex from *U* and restore the triangle inequality for all outgoing edges (relaxation).

## Refined algorithm



```
1. DIST[s] \leftarrow 0;
2. for all v \in V \setminus \{s\} do DIST[v] \leftarrow \infty endfor;
3. U \leftarrow \{s\};
4. while U \neq \emptyset do
        Choose a vertex u \in U and delete it from U;
6.
         for all e = (u, v) \in E do
            if DIST[v] > DIST[u] + c(u,v) then
7.
                 DIST[v] \leftarrow DIST[u] + c(u,v);
8.
                 U \leftarrow U \cup \{v\};
9.
             endif;
10.
11.
         endfor;
12. endwhile;
```





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**Lemma 1:** For each vertex  $v \in V$  we have  $DIST[v] \ge dist(s, v)$ .

**Proof:** (by contradiction)

Let v be the first vertex for which the relaxation of an edge (u,v) yields DIST[v] < dist(s,v).

#### Then:

 $DIST[u] + c(u,v) = DIST[v] < dist(s,v) \le dist(s,u) + c(u,v)$ 

## Important properties



#### Lemma 2:

- a) If  $v \notin U$ , then for all  $(v, w) \in E$ : DIST[w]  $\leq$  DIST[v] + c(v, w)
- b) Let  $s = v_0$ ,  $v_1$ , ...,  $v_l = v$  be a shortest path from s to v. If DIST[v] > dist(s, v), then there exists  $v_i$ ,  $0 \le i \le l-1$ , with  $v_i \in U$  and DIST[ $v_i$ ] =  $dist(s, v_i)$ .
- c) If G has no negative-cost cycles and DIST[v] > dist(s, v) for any  $v \in V$ , then there exists a  $u \in U$  with DIST[u] = dist(s, u).
- d) If in line 5 we always choose  $u \in U$  with DIST[u] = dist(s,u), then the while-loop is executed only once per vertex.

## Efficient implementations



Line 5: How can we find a vertex  $u \in U$  with DIST[u] = dist(s,u)?

This is not known in general, but for some important special cases.

- Nonnegative networks (only non-negative edge costs)
   Dijkstra's algorithm
- Networks without negative-cost cycles
   Bellman-Ford algorithm
- Acyclic networks

## 3. Non-negative networks

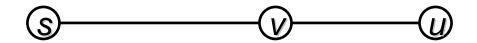


5'. Choose a vertex  $u \in U$  with minimum DIST[u] and delete it from U.

**Lemma 3:** Using 5' we have DIST[u] = dist(s,u).

**Proof:** By Lemma 2b) there is a vertex  $v \in U$  on the shortest path from s to u with DIST[v] = dist(s, v).

$$DIST[u] \leq DIST[v] = dist(s,v) \leq dist(s,u)$$



## Implementing *U* as priority queue



The elements of the form (key, inf) are the pairs (DIST[v], v).

Empty(Q): Is Q empty?

Insert(Q, key, inf): Inserts (key,inf) into Q.

DeleteMin(Q): Returns the element with minimum key and deletes it from Q.

DecreaseKey(Q, element, j): Decreases the value of element's key to the new value j, provided that j is less than the former key.

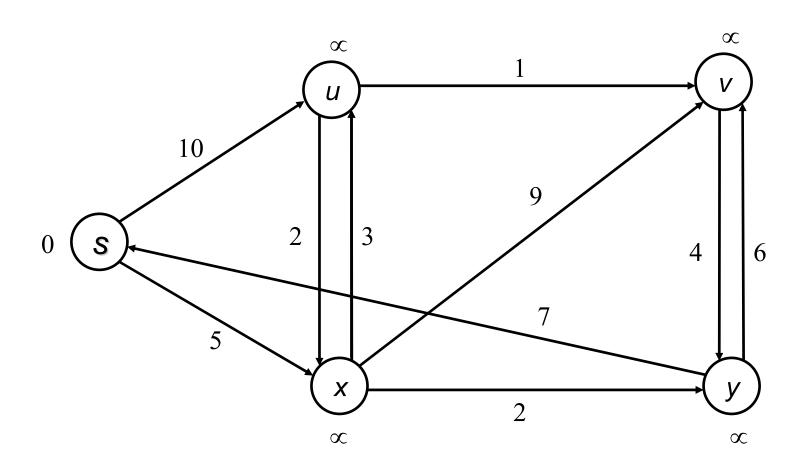
## Dijkstra's algorithm



```
1. DIST[s] \leftarrow 0; Insert(U, O, s);
2. for all v \in V \setminus \{s\} do DIST[v] \leftarrow \infty; Insert(U, \infty, v); endfor;
3. while \neg \text{Empty}(U) do
       (d,u) \leftarrow \text{DeleteMin}(U);
    for all e = (u, v) \in E do
           if DIST[v] > DIST[u] + c(u,v) then
6.
                  DIST[v] \leftarrow DIST[u] + c(u,v);
7.
                  DecreaseKey(U, v, DIST[v]);
8.
9.
           endif;
        endfor;
10.
11. endwhile;
```

# Example





## Running time



O(
$$n(T_{\text{Insert}} + T_{\text{Empty}} + T_{\text{DeleteMin}}) + mT_{\text{DecreaseKey}} + m + n)$$

#### Fibonacci heaps:

 $T_{\text{Insert}}$ : O(1)

 $T_{\text{DeleteMin}}$ : O(log n) amortized

 $T_{\text{DecreaseKey}}$ : O(1) amortized

$$O(n \log n + m)$$



## 4. Networks without negative-cost cycles

Implement *U* as a queue.

**Lemma 4:** Each vertex *v* is inserted into *U* at most *n* times.

**Proof:** Suppose that DIST[v] > dist(s, v) and v is appended at U for the i-th time. Then, by Lemma 2c) there exists  $u_i \in U$  with DIST[ $u_i$ ] =  $dist(s, u_i)$ .

Vertex  $u_i$  is deleted from U before v and will never be appended at U again.

Vertices  $u_1$ ,  $u_2$ ,  $u_3$ , ... are pairwise distinct.

## Bellman-Ford algorithm



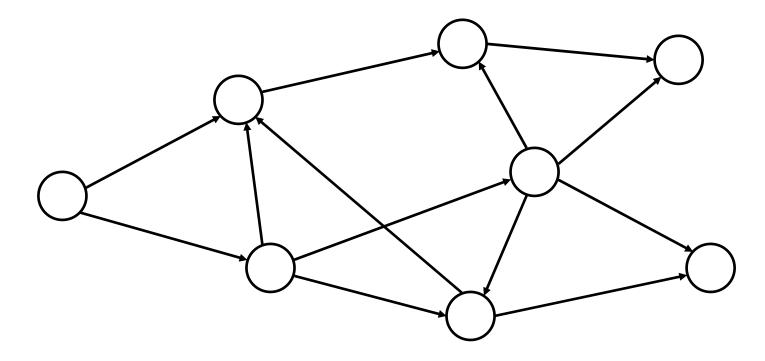
```
1. DIST[s] \leftarrow 0; A[s] \leftarrow 0;
2. for all v \in V \setminus \{s\} do DIST[v] \leftarrow \infty; A[v] \leftarrow 0; endfor;
3. U \leftarrow \{s\};
4. while U \neq \emptyset do
5.
        Choose the first vertex u in U and delete it from U; A[u] \leftarrow A[u]+1;
         if A[u] > n then return "negative-cost cycle";
6.
        for all e = (u, v) \in E do
7.
            if DIST[v] > DIST[u] + c(u,v) then
8.
                 DIST[v] \leftarrow DIST[u] + c(u,v);
9.
10.
                  U \leftarrow U \cup \{v\};
11.
             endif;
12.
         endfor;
13. endwhile;
```





Topological sorting: num:  $V \rightarrow \{1, ..., n\}$ 

such that for all  $(u,v) \in E$ : num(u) < num(v)



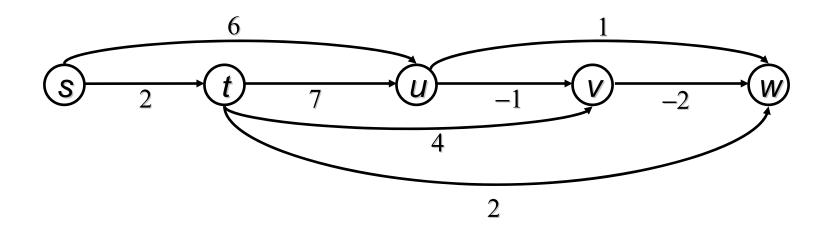
## Algorithm for acyclic graphs



```
1. Sort G = (V, E, c) topologically;
2. DIST[s] \leftarrow 0;
3. for all v \in V \setminus \{s\} do DIST[v] \leftarrow \infty; endfor;
4. U \leftarrow \{ v \mid v \in V \text{ with } \text{num}(v) < n \};
5. while U \neq \emptyset do
        Choose the vertex u \in U with minimum num;
    for all e = (u, v) \in E do
            if DIST[v] > DIST[u] + c(u,v) then
8.
                 DIST[v] \leftarrow DIST[u] + c(u,v);
10.
            endif;
11.
        endfor;
12. endwhile;
```

# Example





### Correctness



**Lemma 5:** When the *i*-th vertex  $u_i$  is deleted from U, then DIST[ $u_i$ ] =  $dist(s, u_i)$ .

**Proof:** Induction on i.

i = 1: ok

i > 1: Let  $s = v_1, v_2, \dots, v_l, v_{l+1} = u_i$  be a shortest path from s to  $u_i$ .

 $v_{l}$  is deleted from U before  $u_{i}$ .

Then, by induction hypothesis: DIST[ $v_i$ ] =  $dist(s, v_i)$ .

After  $(v_i, u_i)$  has been relaxed:

 $DIST[u_i] \leq DIST[v_i] + c(v_i, u_i) = dist(s, v_i) + c(v_i, u_i) = dist(s, u_i)$