



# **Algorithms Theory**

# 04 - Treaps

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# The dictionary problem



**Given:** Universe (U, <) of keys with a total order

**Goal:** Maintain set  $S \subseteq U$  under the following operations

- Search(x, S): Is  $x \in S$ ?
- Insert(x,S): Insert x into S if not already in S.
- Delete(*x*,*S*): Delete *x* from *S*.

# Extended set of operations



- Minimum(S): Return smallest key.
- Maximum(S): Return largest key.
  - Output elements of S in increasing order of key.
- Union $(S_1, S_2)$ : Merge  $S_1$  and  $S_2$ .

List(S):

ullet

Condition:  $\forall x_1 \in S_1$ ,  $x_2 \in S_2$ :  $x_1 < x_2$ 

• Split( $S, x, S_1, S_2$ ): Split S into  $S_1$  and  $S_2$ .

 $\forall x_1 \in S_1, x_2 \in S_2$ :  $x_1 \leq x$  and  $x < x_2$ 

# **Known solutions**



• Binary search trees



Drawback: Sequence of insertions may lead to a linear list a, b, c, d, e, f

• **Height balanced trees:** AVL trees, (a,b)-trees Drawback: Complex algorithms or high memory requirements. Approach for randomized search trees



If *n* elements are inserted in random order into a binary search tree, the expected depth is  $1.39 \log n$ .

Idea: Each element x is assigned a priority chosen uniformly at random  $prio(x) \in R$ 

The goal is to establish the following property.

(\*) The search tree has the structure that would result if elements were inserted in the order of their priorities.

# Treaps (Tree + Heap)



Definition: A treap is a binary tree.

Each node contains one element x with  $\underline{\text{key}(x) \in U}$  and  $\underline{\text{prio}(x) \in R}$ . The following properties hold.

Search tree property

For each element x:



- elements y in the left subtree of x satisfy: key(y) < key(x)
- elements y in the right subtree of x satisfy : key(y) > key(x)
- Heap property

For all elements x, y: If y is a child of x, then prio(y) > prio(x). All priorities are pairwise distinct.





### Example



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**Lemma:** For elements  $x_1, ..., x_n$  with key( $x_i$ ) and prio( $x_i$ ), there exists a unique treap. It satisfies property (\*).

#### **Proof:**

*n*=1: ok *n*>1:

#### Search for an element





# Search for element with key k



1 v := root;

- 2 while  $v \neq nil$  do
- 3 **case** key(v) = k: stop; "element found" (successful search)
- 4 key(v) < k : v := RightChild(v);

5 
$$\operatorname{key}(v) > k : v := \operatorname{LeftChild}(v);$$

6 endcase;



8 "element not found" (unsuccessful search)

Running time: O(# elements on the search path)



# Analysis of the search path



Elements  $x_1, \ldots, x_n$ x<sub>i</sub> has *i*-th smallest key Let *M* be a subset of the elements.

 $P_{min}(M)$  = element in M with lowest priority

$$\begin{array}{c} \begin{array}{c} \lambda_{1}, \ldots, \lambda_{m}, \ldots, \lambda_{m} \\ \hline \\ \textbf{Lemma:} \\ \textbf{a) Let } i < m. \quad \underbrace{x_{i} \text{ is ancestor of } x_{m}}_{\textbf{b) Let } \text{m} < i. \quad x_{i} \text{ is ancestor of } x_{m} \\ \end{array} \begin{array}{c} \begin{array}{c} \hline \\ \textbf{figstarrow} \\ \textbf{fig$$

b)



#### Analysis of the search path



**Proof:** a) (Let *i*<*m*. 
$$x_i$$
 is ancestor of  $x_m$  iff  $P_{min}(\{x_i,...,x_m\}) = x_i$ )  
"=" Let  $\widehat{x_i} = P_{min}(\{x_i,...,x_m\})$ . Show:  $x_i = x_j$   
Suppose:  $x_i \neq x_j$   
(myindus the Scasch path when  $x_j$  is insuched.  
As before any  $x_e \in \{x_i,...,x_m\}$  treates the same search path  
as  $x_j$   
 $x_j$  is an center of  $x_e$ 

$$\begin{array}{c} \underline{\text{Case 1: }} x_{j} = x_{m} \implies X \text{ m in an arter of } X_{l} \implies X \text{ m in an arter of } X_{l} \implies X \text{ m in an arter of } X_{l} \implies X \text{ m in an arter of } X_{l} \implies X \text{ m in an arter of } X_{l} \implies X_{l} \implies$$

## Analysis of the 'Search' operation



Let *T* be a treap with elements  $x_1, ..., x_n$   $x_i$  has *i*-th smallest key *n*-th Harmonic number:  $H_n = \sum_{k=1}^n 1/k \cong l_m n$ Lemma:  $\underbrace{\sum_{k=1}^n k_m + l_m}_{m + l_m - m + 1} = O(l_m n)$   $m \leq n$ 

(2) Unsuccessful search : Let  $\underline{m}$  be the number of keys that are smaller than the search key k. The expected number of nodes on the search path is  $H_m + H_{n-m}$ .  $\neq O(log_u)$ 

#### Analysis of the 'Search' operation



**Proof:** Part 1 fuccinful search  $\overrightarrow{X_{m,i}} = \begin{cases} 1 & x_i \text{ is ancestor of } x_m \\ 0 & \text{otherwise} \end{cases}$ 



 $X_{m} = \# \text{ nodes on the path from the root to } x_{m} (\text{incl. } x_{m})$   $\sum_{i=1}^{\infty} \sum_{i=n}^{\infty} x_{m,i} = X_{m,m} + \sum_{i < m} x_{m,i} + \sum_{i < m} x_{m,i}$   $X_{m} = 1 + \sum_{i < m} X_{m,i} + \sum_{i > m} X_{m,i}$   $\lim_{i < m} \int f \text{ expectation}$   $E[X_{m}] = 1 + E\left[\sum_{i < m} X_{m,i}\right] + E\left[\sum_{i > m} X_{m,i}\right]$   $= A + \sum_{i < m} \mathbb{E}[X_{m,i}] + \sum_{i > m} \mathbb{E}[X_{m,i}] = A + \sum_{i < m} \mathbb{E}[X_{m,i}] + \sum_{i > m} \mathbb{E}[X_{m,i}] = A + \sum_{i < m} \mathbb{E}[X_{m,i}] = A + \sum_{i < m} \mathbb{E}[X_{m,i}] + \sum_{i > m} \mathbb{E}[X_{m,i}] = A + \sum_{i < m} \mathbb{E}[X_{m,i}] = A + \sum$ 

Analysis of the 'Search' operation  

$$\begin{array}{c}
1 \\
\hline i < m; \\
Fr \left[ x_{i} = P_{min} \left( \left\{ x_{i}, \dots, x_{m} \right\} \right) \right] = \frac{1}{1\left\{ x_{i}, \dots, x_{m} \right\} \right]} = \frac{1}{m - i + 1}$$

$$\begin{array}{c}
II \ Lem haa \\
E[(X_{m,i})] = \operatorname{Prob}[x_{i} \text{ is ancestor of } x_{m}] = \frac{1}{(m - i + 1)}
\end{array}$$

All elements in  $\{x_i, ..., x_m\}$  have the same probability of being the one with the smallest priority.

Prob[
$$P_{min}(\{x_i,...,x_m\}) = x_i$$
] = 1/(*m*-*i*+1)

$$(i > m:)$$
  
 $E[X_{m,i}] = 1/(i - m + 1)$ 



### Analysis of the 'Search' operation



#### Part 2 follows analogously

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# Inserting a new element x



- 1. Choose prio(x).
- 2. Search for the position of *x* in the tree.



#### **Rotations**





The rotations maintain the search tree property and restore the heap property.