



# **Algorithm Theory**

# 06 – Amortized Analysis

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## Amortization



- Consider a sequence a<sub>1</sub>, a<sub>2</sub>, ..., a<sub>n</sub> of
   *n* operations performed on a data structure *D*
- $T_i$  = execution time of  $a_i$
- $T = T_1 + T_2 + \dots + T_n$  total execution time
- The execution time of a single operation can vary within a large range, e.g. in 1,...,n, but the worst case does not occur for all operations of the sequence.
- Average execution time of an operation is small, even though a single operation can have a high execution time.

## Analysis of algorithms



- Best case
- Worst case
- Average case
- Amortized worst case

What is the average cost of an operation in a worst case sequence of operations?

## Amortization



### Idea:

- Pay more for inexpensive operations
- Use the credit to cover the cost of expensive operations

#### **Three methods:**

- 1. Aggregate method
- 2. Accounting method
- 3. Potential method





## 1. Aggregate method: binary counter

### Incrementing a binary counter: determine the bit flip cost

<b>Counter value</b>	Cost
00000	
00001	1
00010	2
00011	1
00100	3
00101	1
00110	2
00111	
01000	
01001	
01010	
01011	
01100	
01101	
	Counter value           00000           00001           00010           00011           00100           00101           00101           00101           00101           00101           00101           01000           01101           01001           01001           01001           01001           01010           01011           01010           01011           01010           01011           01100           01101

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## 2. The accounting method



### **Observation:**

In each increment exactly one 0 flips to 1.

### Idea:

Pay two cost units for flipping a 0 to a 1

 $\rightarrow$  each 1 has one cost unit deposited in the banking account

## The accounting method



Operation	Counter value
	00000
1	0 0 0 0 <mark>1</mark>
2	0 0 0 <mark>1 0</mark>
3	0 0 0 1 <mark>1</mark>
4	0 0 <mark>1 0 0</mark>
5	0 0 1 0 <mark>1</mark>
6	0 0 1 <mark>1 0</mark>
7	0 0 1 1 <mark>1</mark>
8	01000
9	0 1 0 0 <mark>1</mark>
10	0 1 0 <mark>1 0</mark>

## 3. The potential method



### Potential function $\boldsymbol{\phi}$

Data structure  $D \rightarrow \phi(D)$ 

 $t_i$  = actual cost of the *i*-th operation

 $\phi_i$  = potential after execution of the *i*-th operation (=  $\phi(D_i)$ )

 $a_i$  = amortized cost of the *i*-th operation

### **Definition:**

$$a_i = t_i + \phi_i - \phi_{i-1}$$

## Example: binary counter



 $D_i$  = counter value after the *i*-th operation  $\phi_i = \phi(D_i) = \#$  of 1's in  $D_i$ 



## **Binary counter**



 $t_i$  = actual bit flip cost of operation *i*  $a_i$  = amortized bit flip cost of operation *i* 

$$a_i = (b_i + 1) + (B_{i-1} - b_i + 1) - B_{i-1}$$
$$= 2$$
$$\Longrightarrow \sum t_i \le 2n$$

## **Dynamic tables**



### **Problem:**

Maintain a table supporting the operations insert and delete such that

- the table size can be adjusted dynamically to the number of items
- the used space in the table is always at least a constant fraction of the total space
- the total cost of a sequence of n operations (insert or delete) is O(n).

Applications: hash table, heap, stack, etc.

Load factor  $\alpha_T$ : number of items stored in the table divided by the size of the table

## Implementation of 'insert'



class dynamic table {

```
int [] table;
```

int size;// size of the tableint num;// number of items

```
dynamicTable() { // initialization of an empty table
  table = new int [1];
  size = 1;
  num = 0;
  }
```

## Implementation of 'insert'



```
insert ( int x) {
   if (num == size ) {
        newTable = new int [2*size];
        for (i = 0; i < size; i++)
            insert table[i] into newTable;
        table = newTable;
        size = 2*size;
   }
   insert x into table;
   num = num + 1;
}
```

# Cost of *n* insertions into an initially empty table

 $t_i$  = cost of the *i*-th insert operation

### Worst case:

 $t_i = 1$  if the table is not full prior to operation *i*  $t_i = (i-1) + 1$  if the table is full prior to operation *i*.

Thus *n* insertions incur a total cost of at most

$$\sum_{i=1}^{n} i = \Theta(n^2)$$

### Amortized worst case:

Aggregate method, accounting method, potential method

## Potential method



T table with

- k = T.num items
- s = T.size size

### **Potential function**

$$\phi(T) = 2 k - s$$

### Potential method



### **Properties**

- $\phi_0 = \phi(T_0) = \phi$  (empty table) = -1
- Immediately before a table expansion we have k = s, thus  $\phi(T) = k = s$ .
- Immediately after a table expansion we have k = s/2, thus  $\phi(T) = 2k - s = 0$ .
- For all  $i \ge 1$ :  $\phi_i = \phi(T_i) > 0$ Since  $\phi_n - \phi_0 \ge 0$ ,

$$\sum t_i \leq \sum a_i$$





 $k_i$  = # items stored in T after the *i*-th operation  $s_i$  = table size of T after the *i*-th operation

Case 1: *i*-th operation does not trigger an expansion

$$k_i = k_{i-1} + 1, \ s_i = s_{i-1}$$

$$a_{i} = 1 + (2k_{i} - s_{i}) - (2k_{i-1} - s_{i-1})$$
  
= 1 + 2(k\_{i} - k\_{i-1})  
= 3



### Case 2: *i*-th operation does trigger an expansion

$$k_i = k_{i-1} + 1, \ s_i = 2s_{i-1}$$

$$a_i = k_{i-1} + 1 + (2k_i - s_i) - (2k_{i-1} - s_{i-1})$$

## Inserting and deleting items



Now: Contract the table whenever the load becomes too small.

### Goal:

- (1) The load factor is bounded from below by a constant.
- (2) The amortized cost of a table operation is constant.

### **First approach**

- Expansion: as before
- Contraction: Halve the table size when a deletion would cause the table to become less than half full.

## "Bad" sequence of table operations



	Cost
<i>n/</i> 2 'insert' op. (table is full)	3 n/2
I: expansion	<i>n/</i> 2 + 1
D, D: contraction	<i>n/</i> 2 + 1
I, I: expansion	<i>- n/</i> 2 + 1
D, D: contraction	

Total cost of the sequence of operations:  $I_{n/2}$ ,  $I, D, D, I, I, D, D, \dots$  of length *n* is

Second approach



Expansion: Double the table size when an item is inserted into a full table.

**Contraction:** Halve the table size when a deletion causes the table to become less than 1/4 full.

**Property:** At any time the table is at least  $\frac{1}{4}$  full, i.e.  $\frac{1}{4} \le \alpha(T) \le 1$ 

What is the cost of a sequence of table operations?



Analysis of 'insert' and 'delete' operations

k = T.num, s = T.size,  $\alpha = k/s$ 

$$\phi(T) = \begin{cases} 2k - s, \text{ if } \alpha \ge 1/2\\ s/2 - k, \text{ if } \alpha < 1/2 \end{cases}$$



$$\phi(T) = \begin{cases} 2k - s, \text{ if } \alpha \ge 1/2\\ s/2 - k, \text{ if } \alpha < 1/2 \end{cases}$$

Immediately after a table expansion or contraction:

$$s = 2k$$
, thus  $\phi(T) = 0$ 

## Analysis of an 'insert' operation



- *i*-th operation:  $k_i = k_{i-1} + 1$
- Case 1:  $\alpha_{i-1} \ge \frac{1}{2}$
- Case 2:  $\alpha_{i-1} < \frac{1}{2}$ 
  - Case 2.1:  $\alpha_i < \frac{1}{2}$ Case 2.2:  $\alpha_i \ge \frac{1}{2}$

## Analysis of an 'insert' operation



Case 2.1:  $\alpha_{i-1} < \frac{1}{2}$ ,  $\alpha_i < \frac{1}{2}$  no expansion

Potential function 
$$\phi$$
  
 $\phi(T) = \begin{cases} 2k - s, \text{ if } \alpha \ge 1/2 \\ s/2 - k, \text{ if } \alpha < 1/2 \end{cases}$ 





Case 2.2:  $\alpha_{i-1} < \frac{1}{2}, \alpha_i \ge \frac{1}{2}$  no expansion

$$\phi(T) = \begin{cases} 2k - s, \text{ if } \alpha \ge 1/2\\ s/2 - k, \text{ if } \alpha < 1/2 \end{cases}$$



 $k_i = k_{i-1} - 1$ 

Case 1:  $\alpha_{i-1} < \frac{1}{2}$ 

Case 1.1: deletion does not trigger a contraction  $s_i = s_{i-1}$ 

$$\phi(T) = \begin{cases} 2k - s, \text{ if } \alpha \ge 1/2\\ s/2 - k, \text{ if } \alpha < 1/2 \end{cases}$$



$$k_i = k_{i-1} - 1$$

Case 1:  $\alpha_{i-1} < \frac{1}{2}$ 

Case 1.2:  $\alpha_{i-1} < \frac{1}{2}$  deletion does trigger a contraction

 $s_i = s_{i-1}/2$   $k_{i-1} = s_{i-1}/4$ 

$$\phi(T) = \begin{cases} 2k - s, \text{ if } \alpha \ge 1/2\\ s/2 - k, \text{ if } \alpha < 1/2 \end{cases}$$



Case 2:  $\alpha_{i-1} \ge \frac{1}{2}$  no contraction

 $s_i = s_{i-1}$   $k_i = k_{i-1} - 1$ 

Case 2.1:  $\alpha_i \ge \frac{1}{2}$ 

Potential function  $\phi$  $\phi(T) = \begin{cases} 2k - s, \text{ if } \alpha \ge 1/2 \\ s/2 - k, \text{ if } \alpha < 1/2 \end{cases}$ 



Case 2:  $\alpha_{i-1} \ge \frac{1}{2}$  no contraction

 $s_i = s_{i-1}$   $k_i = k_{i-1} - 1$ 

Case 2.2:  $\alpha_i < \frac{1}{2}$ 

Potential function  $\phi$  $\phi(T) = \begin{cases} 2k - s, \text{ if } \alpha \ge 1/2 \\ s/2 - k, \text{ if } \alpha < 1/2 \end{cases}$