

Fast Computing in Networks with Limited Bandwidth

Ph.D Candidate:
Dennis **Olivetti**

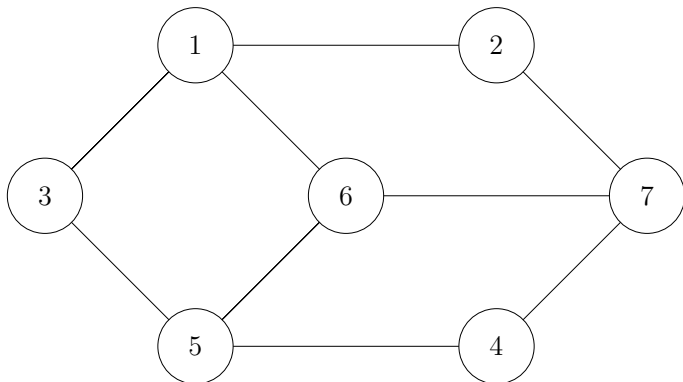
Supervisor:
Prof. Pierre **Fraigniaud**



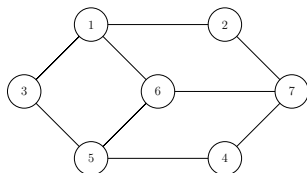
Outline

- CONGEST Model
- Subgraph Detection
- Core-Periphery Networks
- Bandwidth Tradeoffs

Distributed Computing



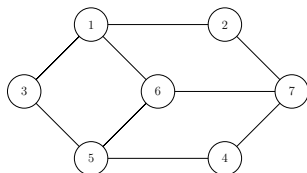
CONGEST model



- Synchronous

- ▶ All nodes start the computation at the same round
- ▶ The computation proceeds in phases
- ▶ At each phase each node can send a different message to each neighbor

CONGEST model

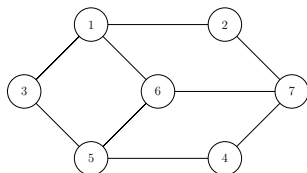


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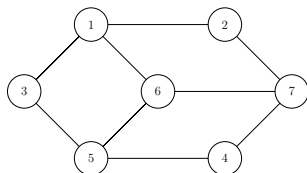
- Fault-free

CONGEST model



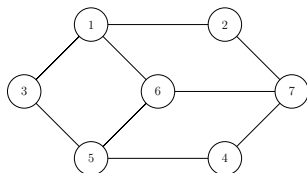
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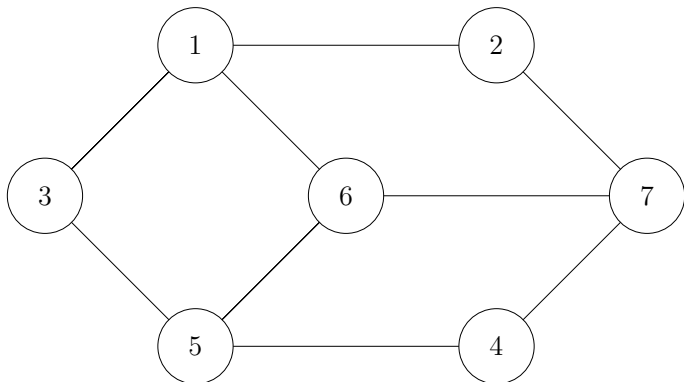
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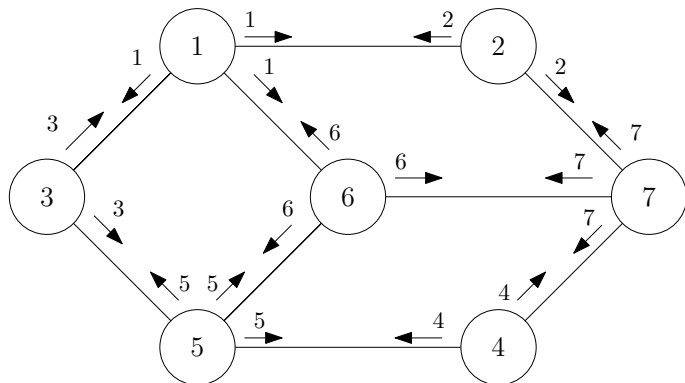


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- Complexity:
 - ▶ Number of rounds
 - ▶ Number of messages

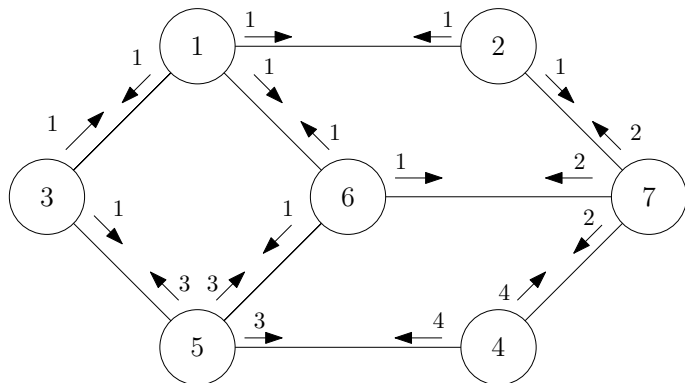
Example: Finding a leader



Example: Finding a leader



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Example: Finding a leader

- Time complexity: $\Theta(\textit{diameter})$
- Message complexity: $\Theta(\textit{edges} \cdot \textit{diameter})$

Complexities

Complexity	Problem
$\Theta(1)$	Checking a coloring
$\Theta(\log^* n)$ ^{1,2}	Coloring a ring
$O(\log n)$ ³	Approximating a maximal matching
$\tilde{\Theta}(\sqrt{n} + \text{diameter})$ ^{4,5}	MST, SSSP approximation
$\Theta(n / \log n)$ ⁶	Diameter, APSP
$\tilde{O}(n^{5/4})$ ⁷	Weighted APSP
$\Omega(n^2 / \log^2 n)$ ⁸	Maximum independent set
$\Theta(n^2)$ ⁸	Checking a non trivial automorphism

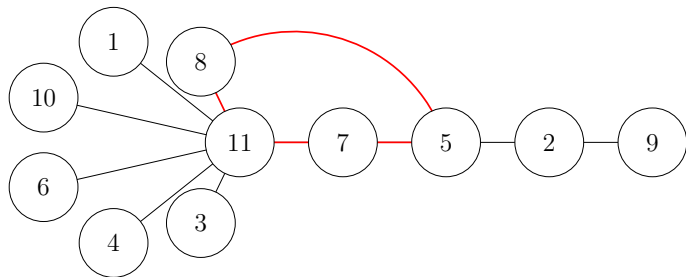
¹[Linial '92] ²[Cole, Vishkin '86] ³[Israeli, Itai '86] ⁴[Kutten, Peleg '98]

⁵[Becker, Karrenbauer, Krinninger, Lenzen '16]

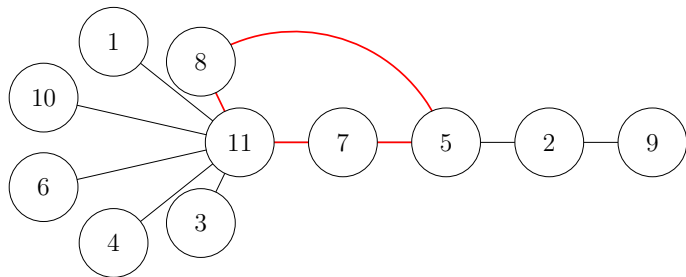
⁶[Hua, Fan, Qian, Ai, Li, Shi, Jin '16] ⁷[Huang, Nanongkai, Saranurak '17]

⁸[Censor-Hillel, Khoury, Paz '17]

Example: Congestion



Example: Congestion

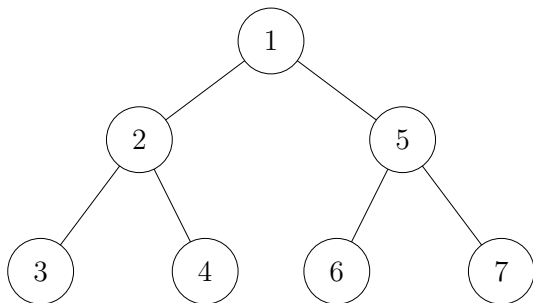


C_4 -detection requires $\tilde{\Theta}(\sqrt{n})$. [Drucker, Kuhn, Oshman, PODC'14]

Subgraph detection

Given a graph pattern H :

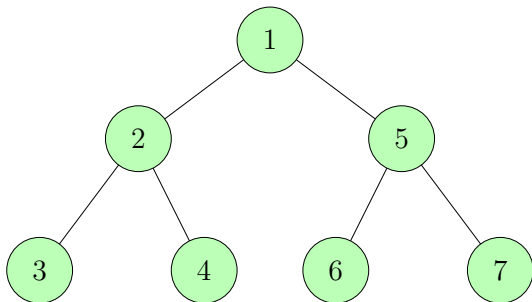
- if G does not contain H as subgraph, all nodes accept;
- otherwise, at least one node rejects.



Subgraph detection

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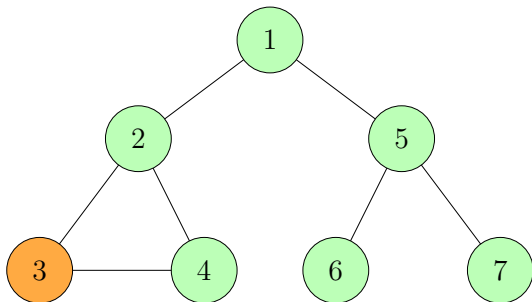
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- C_k detection ($k \geq 4$) requires $\tilde{\Omega}(ex(n, C_k)/n)$ rounds, where $ex(n, H)$ is the maximal possible number of edges of an n -node graph G such that G does not contain H as subgraph. [Drucker, Kuhn, Oshman, PODC'14]

Subgraph detection

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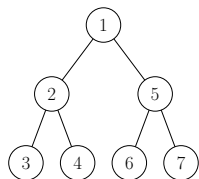
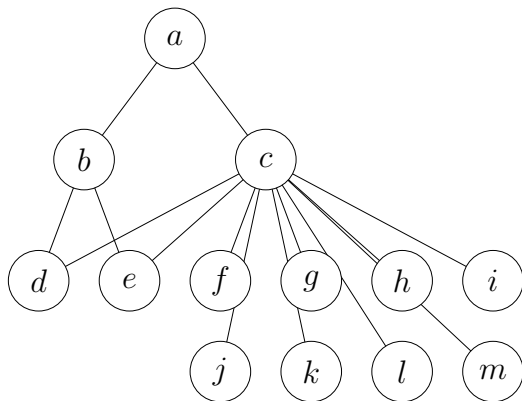
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- For every k -node graph H , H -detection requires $\tilde{O}(n^{1-2/k})$ rounds, if the communication graph is a clique. [Dolev, Lenzen, Peled, DISC'12]

Which patterns are detectable efficiently?

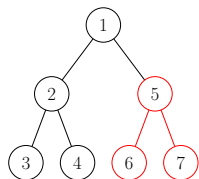
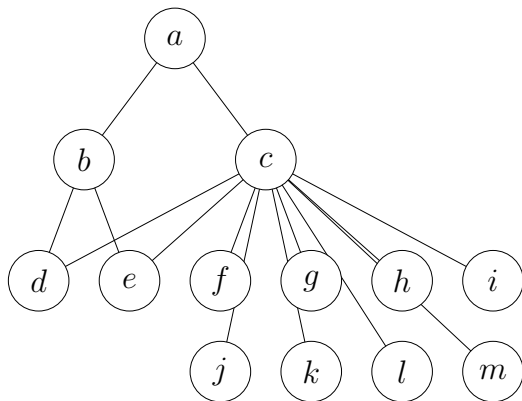
Theorem [Fraigniaud, Montealegre, O., Rapaport, Todinca, DISC'17]

For every tree T of constant size, there exists a deterministic algorithm performing in $O(1)$ rounds in the CONGEST model for detecting whether the given input network contains T as a subgraph.

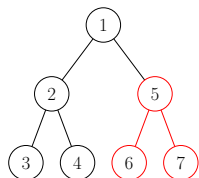
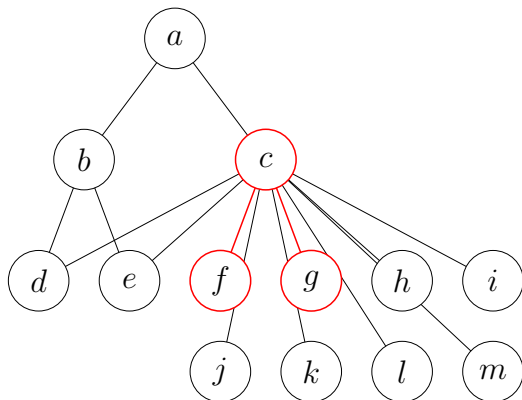
Tree Detection



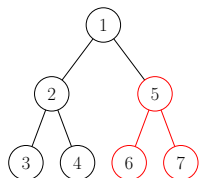
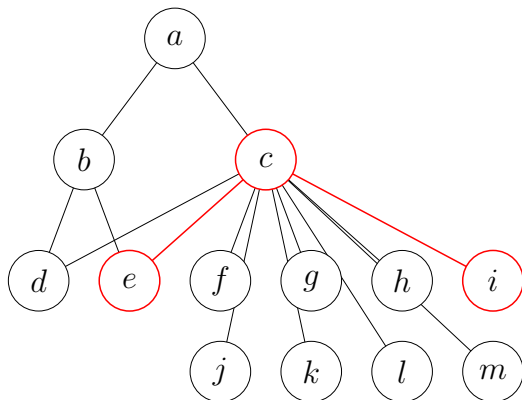
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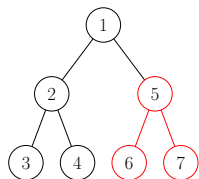
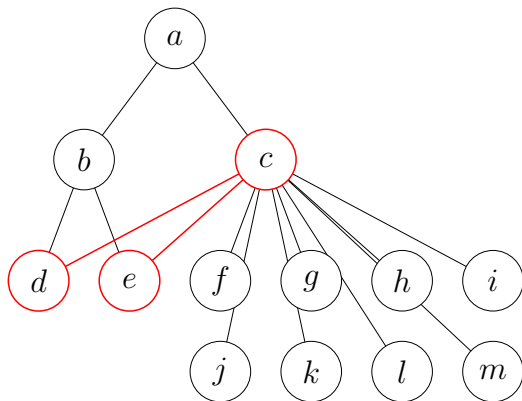
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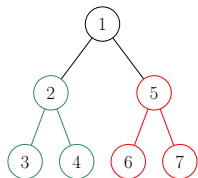
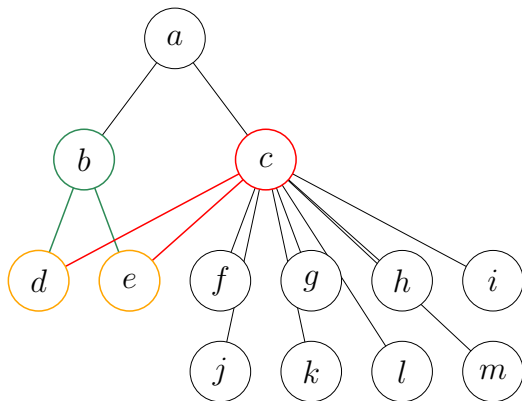
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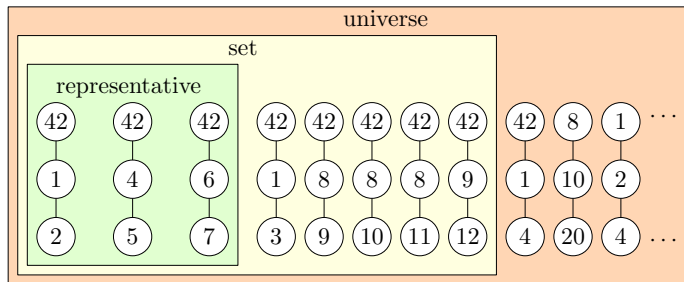
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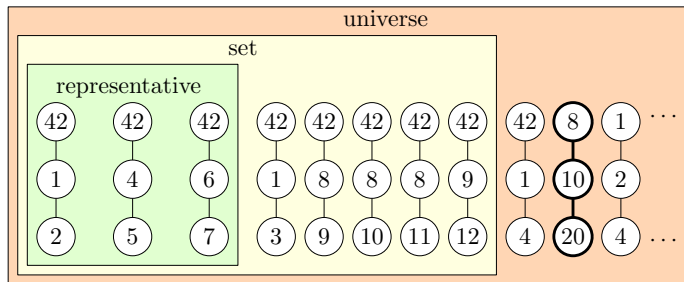
Tree Detection



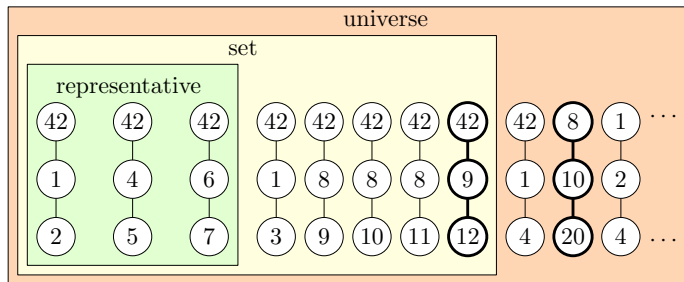
Representative Sets



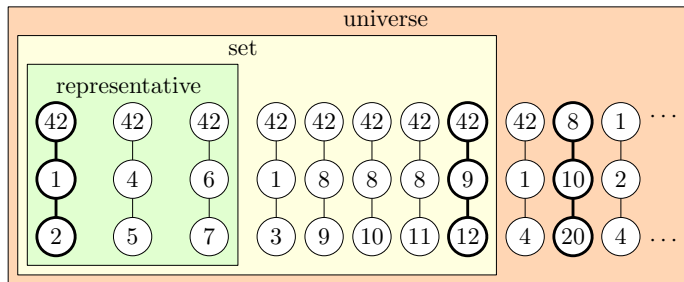
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Representative Sets



Representative Sets

Lemma [Erdős, Hajnal, Moon '64]

Let V be a set of size n , and consider two integer parameters p and q . For any set $F \subseteq \mathcal{P}(V)$ of subsets of size at most p of V , there exists a *compact* (p, q) -representation of F , i.e., a subset \hat{F} of F satisfying:

- 1 For each set $C \subseteq V$ of size at most q , if there is a set $L \in F$ such that $L \cap C = \emptyset$, then there also exists $\hat{L} \in \hat{F}$ such that $\hat{L} \cap C = \emptyset$;
- 2 The cardinality of \hat{F} is at most $\binom{p+q}{p}$, for any $n \geq p + q$.

Breaking the lower bounds

Pattern detection:

- We want to detect more patterns, efficiently.
- There are polynomial lower bounds.
- We need to relax the problem.

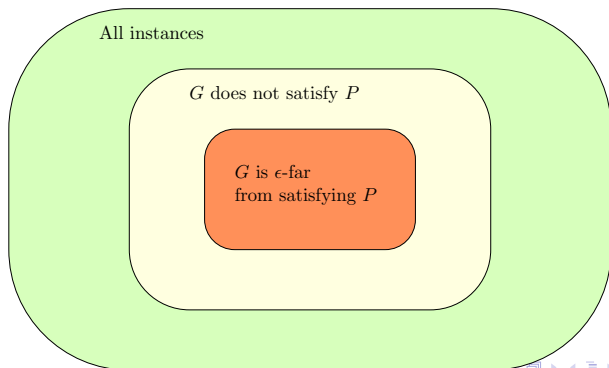
Possible ways:

- Allow more bandwidth.
- Assume that the communication graph is a clique.
- Allow some error.

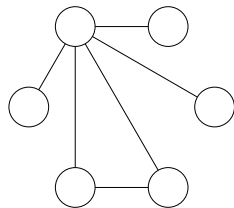
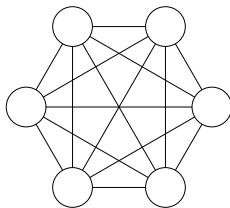
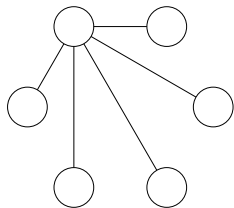
Distributed property testing

Let $G = (V, E)$, $n = |V|$, $m = |E|$. Let ϵ be a small constant in $(0, 1)$. A distributed tester for a graph property P is a distributed randomized algorithm A that satisfies the following conditions:

- G satisfies $P \Rightarrow$ every node outputs “accept”
- G is ϵ -far from satisfying $P \Rightarrow$
 $\Pr[\text{at least one node outputs “reject”}] \geq \frac{2}{3}$



Distributed property testing



How to measure how far is a graph from satisfying a property?

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Dense model

A graph is ϵ -far from satisfying a property if at least ϵn^2 edges should be added or removed from G in order to make the property hold.

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There exist two distinct models:

Dense model

A graph is ϵ -far from satisfying a property if at least ϵn^2 edges should be added or removed from G in order to make the property hold.

Sparse model

A graph is ϵ -far from satisfying a property if at least ϵm edges should be added or removed from G in order to make the property hold.

State of the art

[Censor-Hillel, Fischer, Schwartzman, Vasudev '16]

Any ϵ -tester for the dense model (for a non-disjointed property) that makes q queries can be converted to a distributed ϵ -tester that requires $O(q^2)$ rounds in the distributed setting.

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[Censor-Hillel, Fischer, Schwartzman, Vasudev '16]

- Triangle freeness can be tested in $O(1/\epsilon^2)$
- Cycle freeness can be tested $O(\log n/\epsilon)$
- Cycle freeness requires at least $\Omega(\log n)$
- Bipartiteness can be tested in in $O(\text{poly}(\log \frac{n}{\epsilon}/\epsilon))$ in bounded degree graphs

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[Fraigniaud, Rapaport, Salo, Todinca '16]

- H -freeness can be tested in constant time for any H s.t.
 $|V(H)| \leq 4$

Which patterns are detectable efficiently?

Theorem [Fraigniaud, O., SPAA'17]

There exists an ϵ -tester for C_k freeness, for any constant $k \geq 3$, that requires $O(\frac{1}{\epsilon})$ rounds in the CONGEST model.

*[Three Notes on Distributed Property Testing, Even, Fischer, Fraigniaud, Gonen, Levi, Medina, Montealegre, O., Oshman, Rapaport, Todinca]

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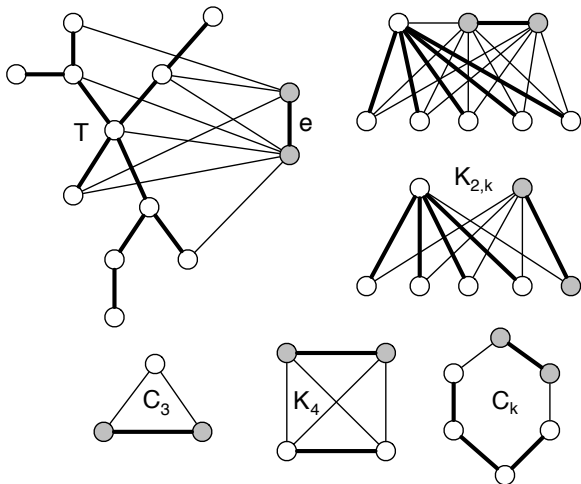
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Theorem [Fraigniaud, Montealegre, O., Rapaport, Todinca, DISC'17]*

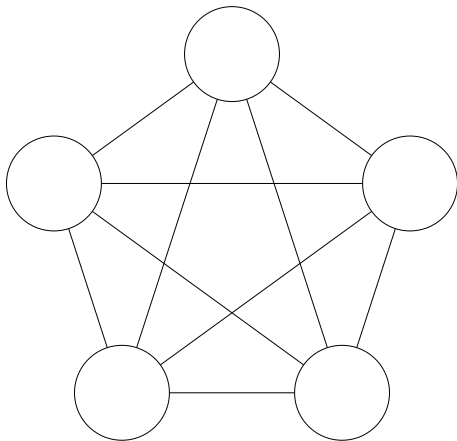
There exists an ϵ -tester for H freeness, for any graph H of constant size composed by a tree, an edge, and arbitrary connections between the endpoints of the edge and the nodes of the tree, that requires $O(\frac{1}{\epsilon})$ rounds in the CONGEST model.

*[Three Notes on Distributed Property Testing, Even, Fischer, Fraigniaud, Gonen, Levi, Medina, Montealegre, O., Oshman, Rapaport, Todinca]

Tree + 1 edge



Open Problem



Congested clique

If we assume that the communication graph is a clique we can solve many problems very efficiently:

- C_4 detection in $O(1)$ ¹ rounds.
- MST in $O(1)$ ² rounds.
- Matrix multiplication, APSP approximation, triangle and 4-cycle counting, girth computing in $O(n^{0.158})$ ² rounds.

¹[Censor-Hillel, Kaski, Korhonen, Lenzen, Paz, Suomela '15]

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This model is very powerful:

- No lower bounds are known.
- It can simulate some powerful classes of circuits.³

The number of edges is quadratic in the number of nodes, it may be hard to build it in practice.

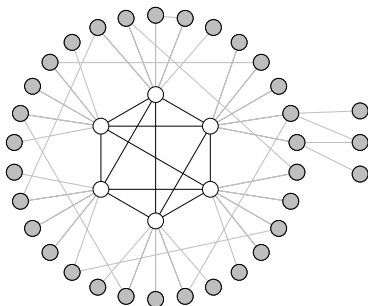
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Core-periphery networks

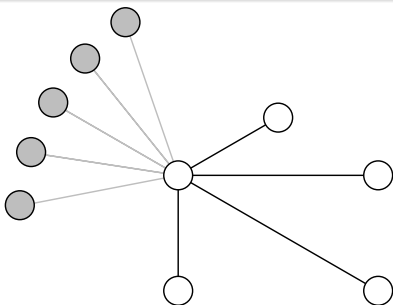
- A novel network architecture for parallel and distributed computing, inspired by social networks and complex systems, proposed by [Avin, Borokhovich, Lotker, Peleg '14].
- A core-periphery network $G = (V, E)$ has its node set partitioned into a *core* C and a *periphery* P , and satisfies the following axioms:

- ▶ Core boundary
- ▶ Clique emulation
- ▶ Periphery-core convergecast



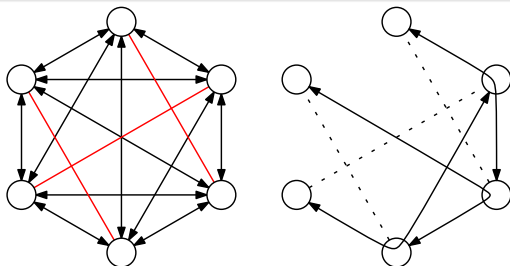
Axiom 1: Core boundary

For every node $v \in C$, $\deg_C(v) \simeq \deg_P(v)$, where, for $S \subseteq V$ and $v \in V$, $\deg_S(v)$ denotes the number of neighbors of v in S .



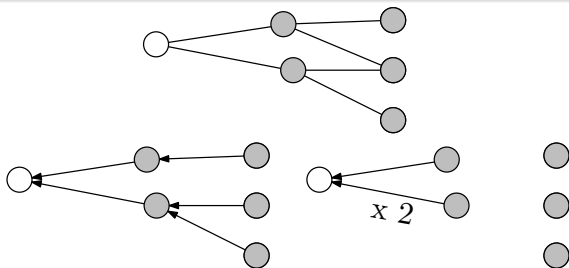
Axiom 2: Clique emulation

The core can emulate the clique in a constant number of rounds in the CONGEST model. That is, there is a communication protocol running in a constant number of rounds in the CONGEST model such that, assuming that each node $v \in C$ has a message $M_{v,w}$ on $O(\log n)$ bits for every $w \in C$, then, after $O(1)$ rounds, every $w \in C$ has received all messages $M_{v,w}$, for all $v \in C$.

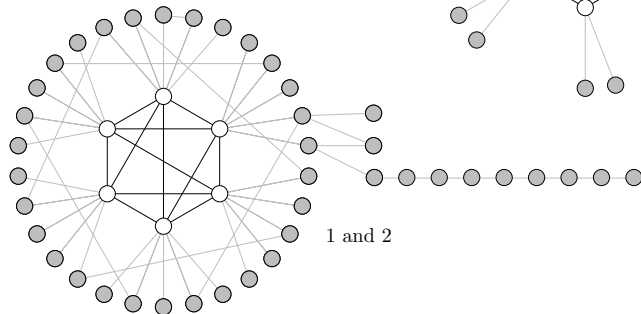
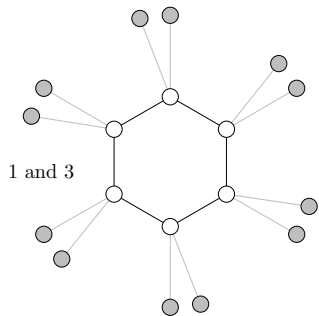
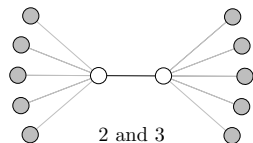


Axiom 3: Periphery-core convergecast

There is a communication protocol running in a constant number of rounds in the CONGEST model such that, assuming that each node $v \in P$ has a message M_v on $O(\log n)$ bits, then, after $O(1)$ rounds, for every $v \in P$, at least one node in the core has received M_v .



Not Core-Periphery Networks



Core-Periphery in Practice

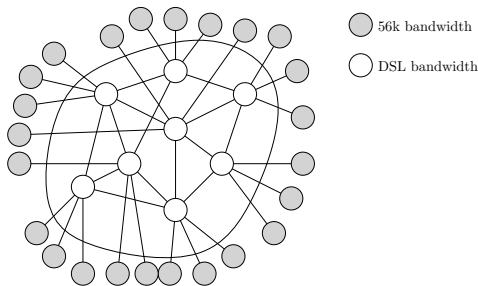
Many file sharing networks:

- Centralized:
 - ▶ eDonkey
 - ▶ OpenNap
- Distributed:
 - ▶ Kademlia
 - ▶ WinMX
 - ▶ Gnutella
(Bearshare, Limewire, ...)
 - ▶ Bittorrent

Core-Periphery in Practice

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 - ▶ Bittorrent



Which graphs can satisfy Axiom 2 efficiently?

- Nodes should be able to perform an all-to-all communication efficiently
- We want the graph as sparse as possible

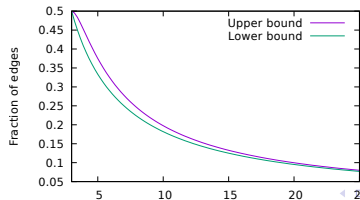
Tradeoff between edges and rounds

Theorem [Balliu, Fraigniaud, Lotker, O., SIROCCO'16]

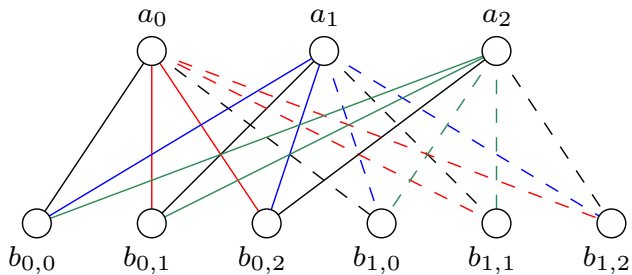
Let $n \geq 1$, and $k \geq 3$. There is an n -node graph with $\frac{k-2}{(k-1)^2} n^2$ edges that can emulate the n -node clique in k rounds. Also, there is an n -node graph with $\frac{1}{3}n^2$ edges that can emulate the n -node clique in 2 rounds.

Theorem [Balliu, Fraigniaud, Lotker, O., SIROCCO'16]

Let $n \geq 1$, $k \in \{1, \dots, n-1\}$, and let G be an n -node graph that can emulate the n -node clique in k rounds. Then G has at least $\frac{n(n-1)}{k+1}$ edges.



Proof idea



Random graphs

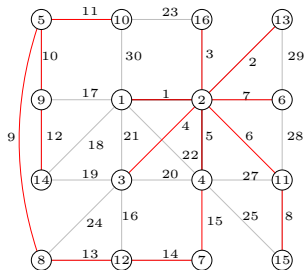
Theorem [Balliu, Fraigniaud, Lotker, O., SIROCCO'16]

Let $c \geq 0$, $n \geq 1$, $\alpha = \sqrt{(3+c)e/(e-2)}$ where e is the base of the natural logarithm, and $p \geq \alpha\sqrt{\ln n/n}$. For $G \in \mathcal{G}_{n,p}$,
 $\Pr[G \text{ can emulate } K_n \text{ in } O(\min\{\frac{1}{p^2}, np\}) \text{ rounds}] \geq 1 - O(\frac{1}{n^{1+c}})$

The power of Core-Periphery networks

- Matrix transposition in $O(k)$ rounds, where k is the number of nonzero entries.
- Vector by matrix multiplication in $O(k)$ rounds.
- Matrix multiplication in $O(k^2)$ rounds.
- Rank finding in $O(1)$ rounds.
- Median finding in $O(1)$ rounds.
- Mode finding in $O(1)$ rounds.
- Number of distinct values $O(1)$ rounds.
- MST in $O(\log^2 n)$ rounds.

Minimum Spanning Tree



MST in the Congest model:

- $D = 1$:
 $O(1)$ ¹ randomized,
 $O(\log \log n)$ ² deterministic
- $D = 2$:
 $O(\log n)$ ³ deterministic
- $D \geq 3$: $\Omega(\sqrt[3]{n})$ ³
- Core-Periphery ($D \approx 4$):
 $O(\log^2 n)$ ⁴ randomized

¹[Jurdzinski, Nowicki '17] ²[Lotker, Patt-Shamir, Pavlov, Peleg '05]

³[Lotker, Patt-Shamir, Peleg '06] ⁴[Avin, Borokhovich, Lotker, Peleg '14]

Minimum Spanning Tree

Theorem [Balliu, Fraigniaud, Lotker, O., SIROCCO'16]

There exists a deterministic algorithm that solves the MST construction task in $O(\log n)$ rounds in Core-Periphery networks.

Open problem

In the Congested Clique we can construct a MST in $O(1)$ rounds, can we construct a MST in Core-Periphery networks in $o(\log n)$?

The CONGEST_B model

Typically, messages are chosen to be $B = O(\log n)$ bits:

- MST can be constructed in $O(\sqrt{n} \log^* n + D)$ ¹ rounds
- SSSP can be approximated in $\tilde{O}(\epsilon^{-O(1)}(\sqrt{n} + D))$ ²
- APSP can be computed in $O(n / \log n)$ ³

Typically, lower bounds depend on B:

- MST and SSSP require $\Omega(\sqrt{n/B})$ ⁴
- APSP requires $\Omega(n/B)$ ^{5,6}

¹[Kutten, Peleg '98]

²[Becker, Karrenbauer, Krinninger, Lenzen '16]

³[Hua, Fan, Qian, Ai, Li, Shi, Jin '16]

⁴[Das Sarma, Holzer, Kor, Korman, Nanongkai, Pandurangan, Peleg, Wattenhofer '10]

⁵[Abboud, Censor-Hillel, Khoury '16]

⁶[Frischknecht, Holzer, Wattenhofer '12]

The CONGEST_B model

How the complexity of existing algorithms scale when more bandwidth is allowed?

Results

There exists an algorithm that solves the APSP problem in $\tilde{O}(n/B + D)$ rounds.

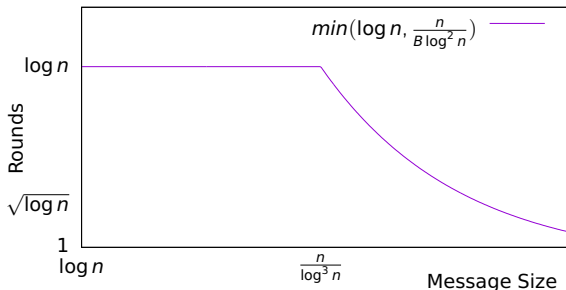
There exists an algorithm that constructs a MST in $\tilde{O}(D + \sqrt{\frac{n}{B}})$ rounds

There exists an algorithm that finds a $(1 + \epsilon)$ -approximation of the SSSP problem in $\tilde{O}(\epsilon^{-O(1)}(\sqrt{\frac{n}{B}} + D))$ rounds.

Results

There is a problem such that:

- It can be solved in $O(\log n)$ rounds with $B = O(\log n)$.
- In order to solve it in less than $\frac{\log n}{2}$ rounds, messages must be of size at least $B = \tilde{\Omega}(n)$.



Remarks

- In practice, one may prefer to use more bandwidth in order to decrease the latency.
- Different problems scale differently with the bandwidth.
- In some cases more bandwidth does not help.
- It makes sense to analyze algorithms for the whole spectrum of bandwidths.

Open problems

- Analyze more algorithms
- Find common patterns

Thank you