



Chapter 4

Causality, Time, and Global States

Distributed Systems

SS 2019

*no exercise tutorial
on Wed, May 22*

Fabian Kuhn

Time in Distributed Systems

Goal: Establish a notion of time in (partially) asynchronous systems

Physical time:

- Establish an approximation of real time in a network
- Synchronize local clocks in a network
- Timestamp events (email, sensor data, file access times etc.)
- Synchronize audio and video streams
- Measure signal propagation delays (Localization)
- Wireless (TDMA, duty cycling)
- Digital control systems (ESP, airplane autopilot etc.)

Logical time:

- Determine an order on the events in a distributed system
- Establish a global view on the system

Logical Clocks

Goal: Assign a timestamp to all events in an asynchronous message-passing system

- Allows to give the nodes some notion of time
 - which can be used by algorithms
- **Logical clock values:** numerical values that increase over time and which are consistent with the observable behavior of the system
- The objective here is **not** to do clock synchronization:
Clock Synchronization: compute logical clocks at all nodes which simulate real time and which are tightly synchronized.
 - We will briefly talk about clock synchronization later...

Observable Behavior

Recall Executions / Schedules

- An exec. is an alternating sequence of configurations and events
- A schedule S is the sequence of events of an execution
 - Possibly including node inputs
- Schedule restriction for node v :

$S|v$:= "sequence of events seen by v "

Causal Shuffles

We say that a schedule S' is a **causal shuffle** of schedule S iff

$$\forall v \in V: \underline{S|v = S'|v}.$$

Observation: If S' is a causal shuffle of S , no node/process can distinguish between S and S' .

Causal Order

Logical clocks are based on a causal order of the events

- In the order, event e should occur **before** event e' if event e **provably occurs before** event e'
 - In that case, the clock value of e should be smaller than the one of e'

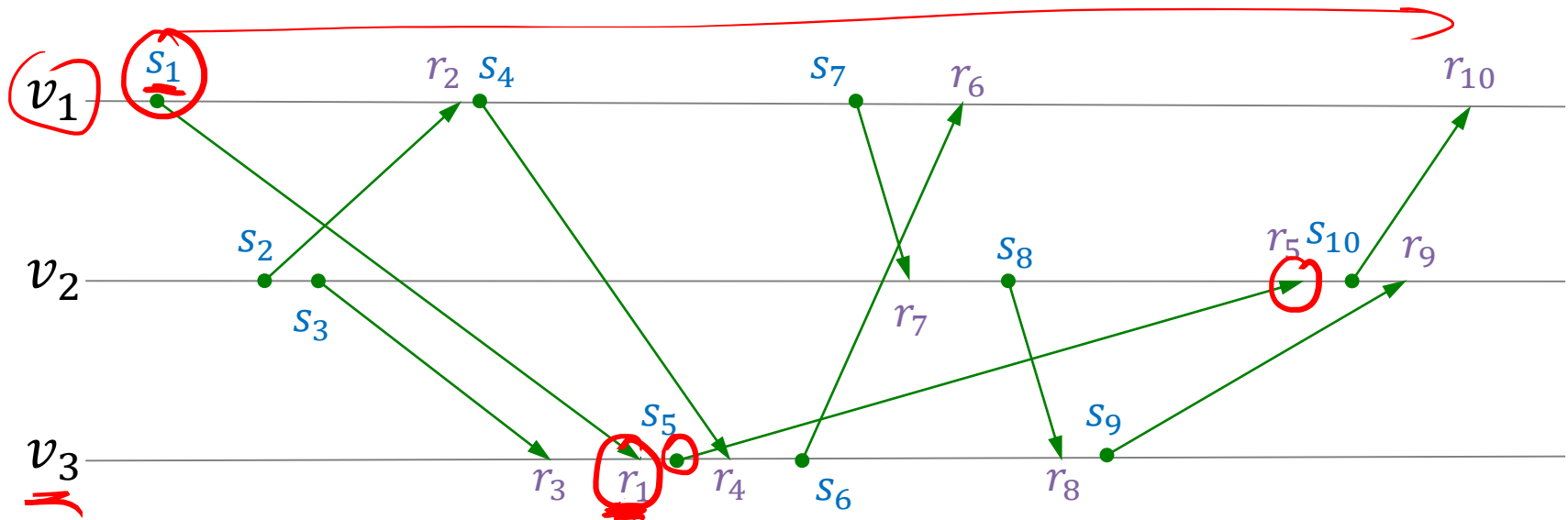
For a given schedule S :

- The distributed system cannot distinguish S from another schedule S' if and only if S' is a causal shuffle of S .
 - causal shuffle \Rightarrow no node can distinguish
 - no causal shuffle \Rightarrow some node can distinguish

Event e provably occurs before e' if and only if e appears before e' in all causal shuffles of S

Causal Shuffles / Causal Order Example

Schedule S



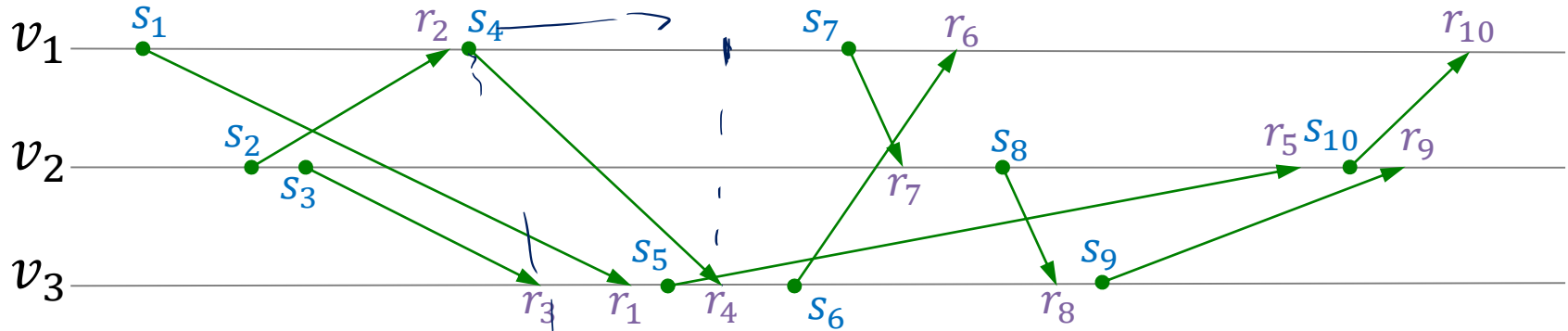
schedule $s_1, s_2, s_3, r_2, s_4, r_3, r_1, s_5$

$SI_{r_1} = s_1, r_2, s_4, s_7, r_6, r_{10}$

Causal Shuffles / Causal Order Example

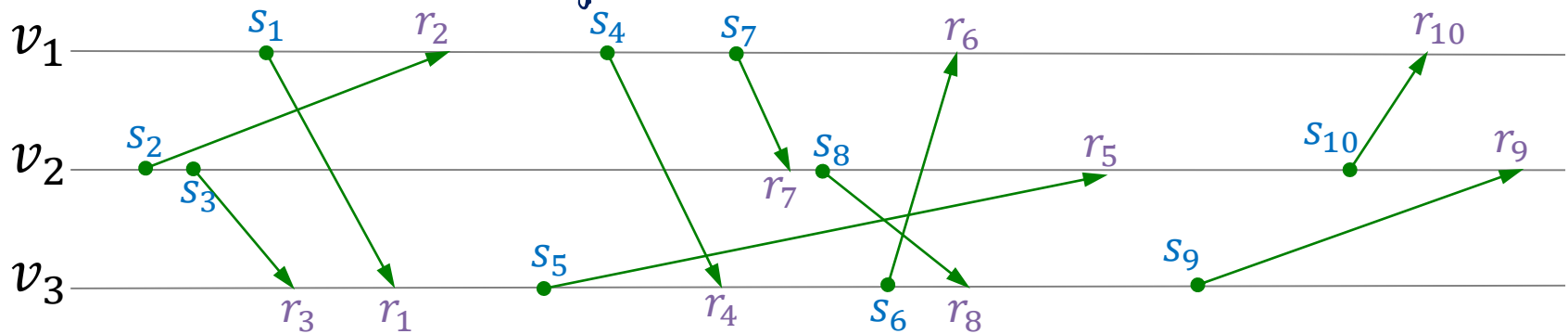
Schedule S

$s_1, s_2, s_3, r_2, s_4, s_5, r_3$



Some Causal Shuffle S'

$s_2, s_3, s_1, r_3, r_1, r_2, s_5, \dots$



Lamport's Happens-Before Relation

Assumption: message passing system, only send and receive events

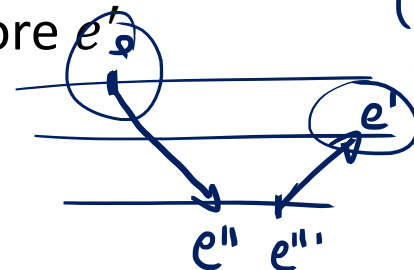
Consider two events e and e' occurring at nodes u and u'

- send event occurs at sending node, recv. event at receiving node
- let's define t and t' be the (real) times when e and e' occur

We know that **e provably occurs before e'** if

1. The events occur at the same node and e occurs before e'
2. Event e is a send event, e' the recv. event of the same message
3. There is an event e'' for which we know that provably, e occurs before e'' and e'' occurs before e' (transitivity)

$$e \rightarrow e'' \rightarrow e'$$



Lamport's Happens-Before Relation

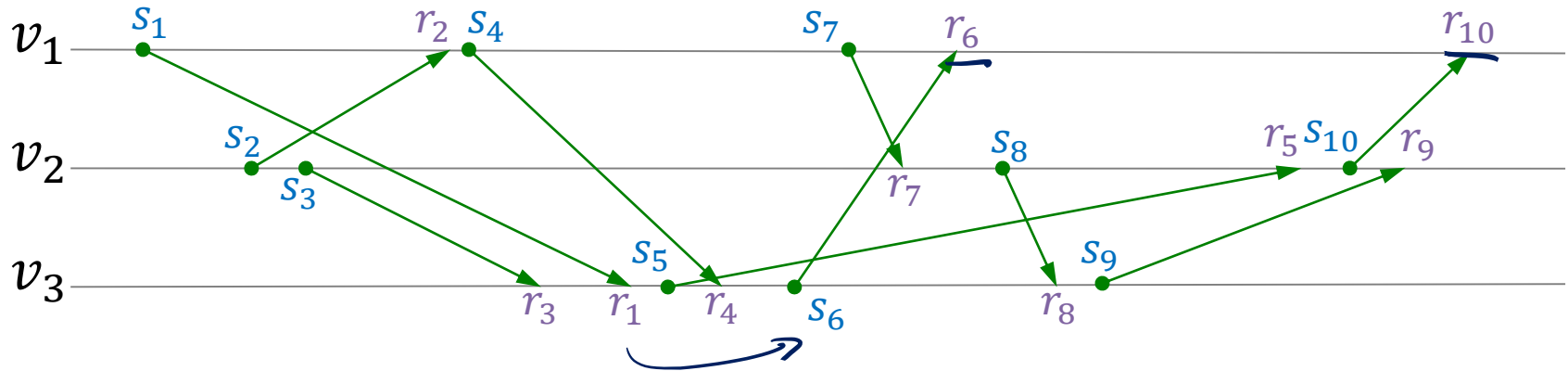
Definition: The happens-before relation \Rightarrow_S on a schedule S is a pairwise relation on the send/receive events of S and it contains

1. All pairs (e, e') where e precedes e' in S and e and e' are events of the same node/process.
2. All pairs (e, e') where e is a send event and e' the receive event for the same message.
3. All pairs (e, e') where there is a third event e'' such that

$$e \Rightarrow_S e'' \quad \wedge \quad e'' \Rightarrow_S e'$$
 - Hence, we take the transitive closure of the relation defined by 1. and 2.

Happens-Before Relation: Example

Schedule S



$$\forall i: s_i \Rightarrow_s r_i$$

$$s_1 \Rightarrow_s r_1, r_1 \Rightarrow_s s_6, s_6 \Rightarrow_s r_6, r_6 \Rightarrow_s r_{10}$$

$$\Downarrow$$

$$s_1 \Rightarrow_s r_{10}$$

Happens-Before and Causal Shuffles

Theorem: For a schedule S and two (send and/or receive) events e and e' , the following two statements are equivalent:

- a) Event e happens-before e' , i.e., $e \Rightarrow_S e'$. $\neg(e \Rightarrow_S e')$
- b) Event e precedes e' in all causal shuffles S' of S . $\wedge \neg(e' \Rightarrow_S e)$

Some remarks before proving the theorem...

- Shows that the happens-before relation is exactly capturing what we need about the causality between events
 - It captures exactly what is observable about the order of events
- To prove the theorem, we show that
 - a) \rightarrow b)
 - b) \rightarrow a)

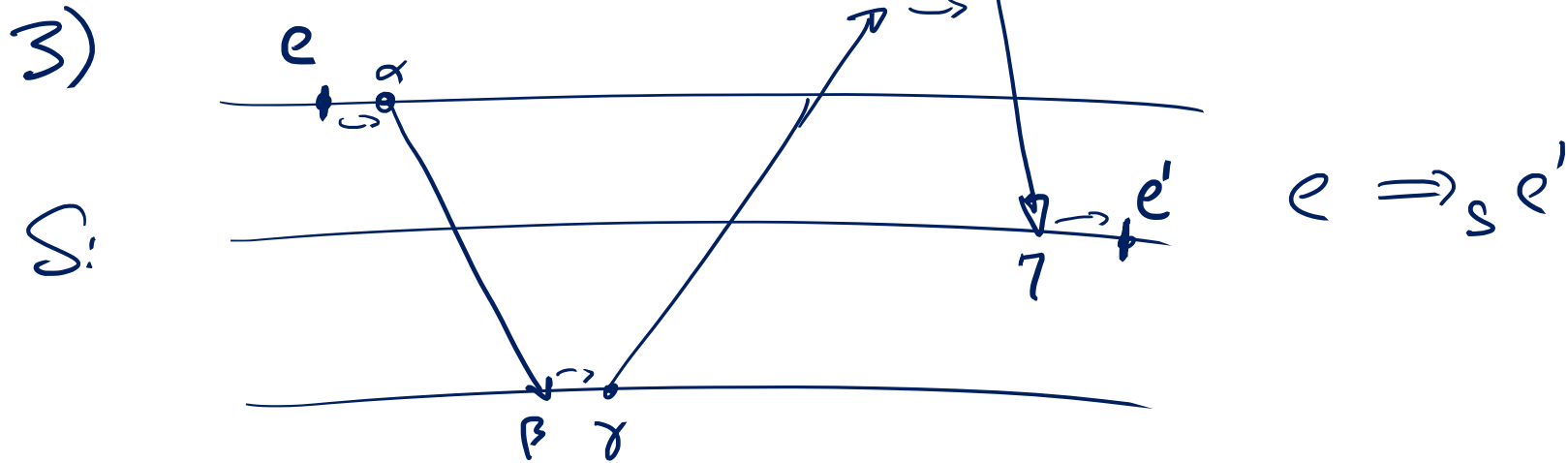
Remark:

\Rightarrow_S is a partial order

Happens-Before and Causal Shuffles

If $e \Rightarrow_s e'$, then e precedes e' in all causal shuffles S' of S .

- 1) e, e' occur at the same node ✓
- 2) e, e' belong to the same msg. (e : send, e' : receive) ✓



take shortest chain $e \Rightarrow_s e_1 \Rightarrow_s e_2 \dots \Rightarrow_s e_n \Rightarrow_s e'$

$e \Rightarrow_s e'' \Rightarrow_s e'$

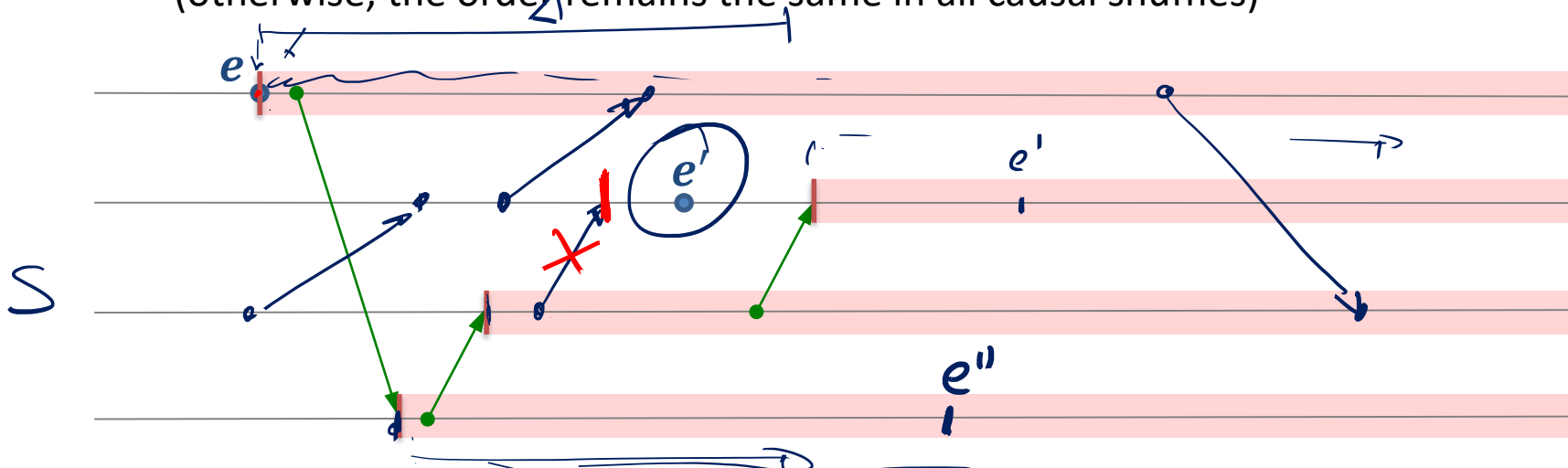
Happens-Before and Causal Shuffles

If e precedes e' in all causal shuffles S' of S , then $e \Rightarrow_S e'$.

Proof:

$$A \rightarrow B \quad \neg B \rightarrow \neg A$$

- Show: $e \not\Rightarrow_S e'$, there is a shuffle S' such that e' precedes e in S
- W.l.o.g., assume that e precedes e' in S
 - Consequently, e and e' happen at different nodes (otherwise, the order remains the same in all causal shuffles)



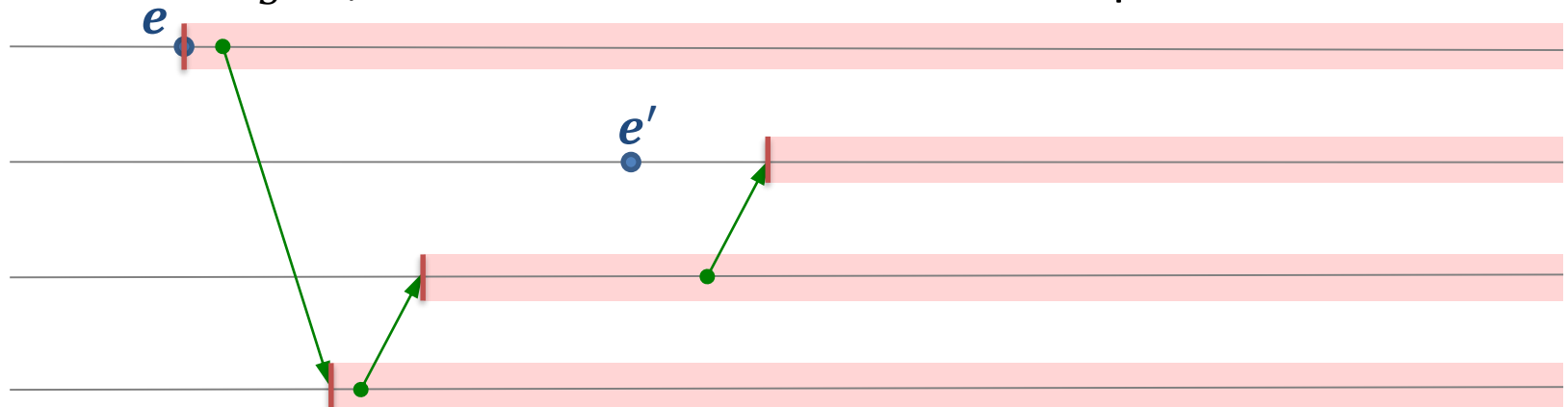
- Events in red part can be shifted by fixed amount Δ

Happens-Before and Causal Shuffles

If e precedes e' in all causal shuffles S' of S , then $e \Rightarrow_S e'$.

Proof:

- Show: $e \not\Rightarrow_S e'$, there is a shuffle S' such that e' precedes e in S



- **Events in red part can be shifted by fixed amount Δ**
 - Consider some message M with send/receive events s_M, r_M
 - If s_M and r_M or only r_M are shifted, message delay gets larger \rightarrow OK
 - It is not possible to only shift s_M
 - Choose Δ large enough to move e past e'

Lamport Clocks

Basic Idea:

1. Each event e gets a clock value $\tau(e) \in \mathbb{N}$
2. If e and e' are events at the **same node** and e precedes e' , then

$$\tau(e) < \tau(e')$$
3. If s_M and r_M are the **send and receive** events of some msg. M ,

$$\tau(s_M) < \tau(r_M)$$

Observation:

- For clock values $\tau(e)$ of events e satisfying 1., 2., and 3., we have

$$\underline{e \Rightarrow_s e'} \rightarrow \underline{\tau(e) < \tau(e')}$$

- because $<$ relation (on \mathbb{N}) is transitive

- Hence, the partial order defined by $\tau(e)$ is a **superset of \Rightarrow_s**

Lamport Clocks

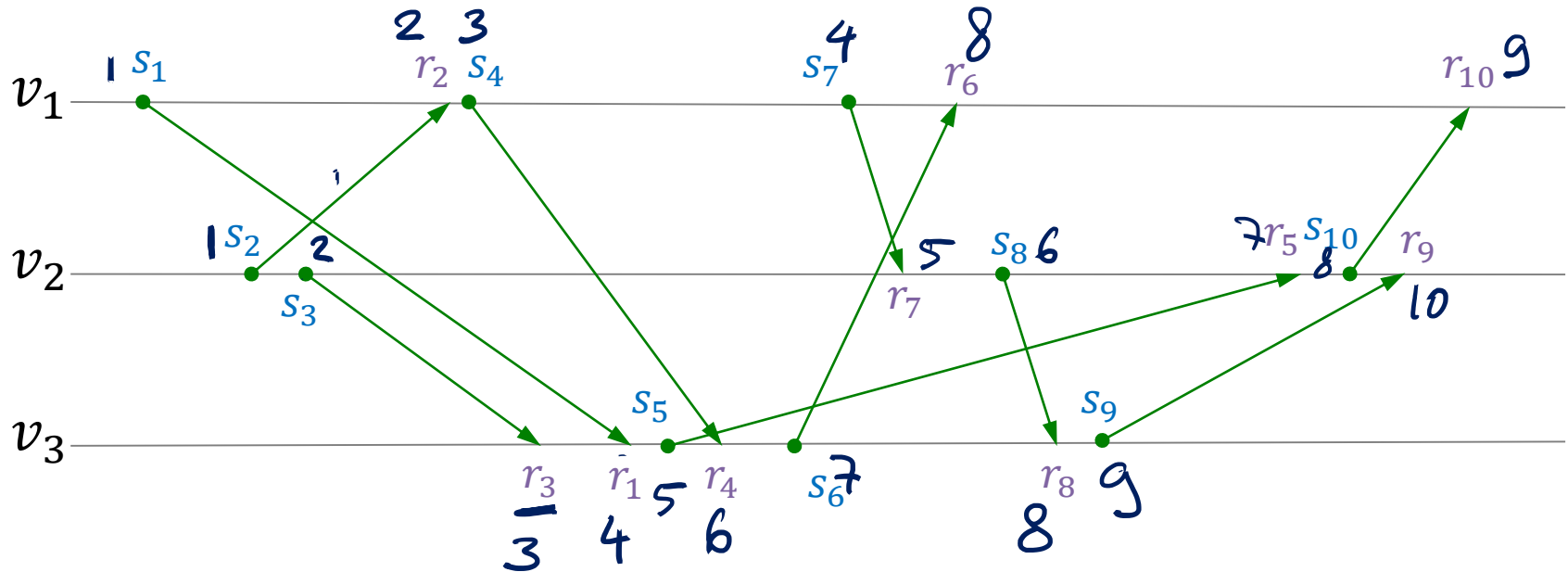
Algorithm:

- Each node u keeps a counter c_u which is initialized to 0
- For any non-receive event e at node u , node u computes
$$c_u := c_u + 1; \tau(e) := c_u$$
- For any send event s at node u , node u attaches the value of $\tau(s)$ to the message
- For any receive event r at node u (with corresponding send event s), node u computes

$$c_u := \max\{c_u, \tau(s)\} + 1; \tau(r) := c_u$$

Lamport Clocks: Example

Schedule S



Neiger-Toueg-Welch Clocks

Discussion Lamport Clocks:

- Advantage: no changes in the behavior of the underlying protocol
- Disadvantage: clocks might make huge jumps (when recv. a msg.)

Idea by Neiger, Toueg, and Welch:

- Assume nodes have some approximate knowledge of real time
 - e.g., by using a clock synchronization algorithm
- Nodes increase their clock value periodically
- Combine with Lamport clock ideas to ensure safety
- When receiving a message with a time stamp which is larger than the current local clock value, wait with processing the message.

Fidge-Mattern Vector Clocks

- Lamport clocks give a superset of the happens-before relation
- Can we compute logical clocks to get \Rightarrow_S exactly?

Vector Clocks:

- Each node u maintains a vector $VC(u)$ of clock values
 - one entry $VC_v(u)$ for each node $v \in V$
- In the vector $VC(e)$ assigned (by u) to some event e happening at node u , the **component** x_v corresponding to $v \in V$ refers to the **number of events at node v , u knows about when e occurs**

Vector Clocks Algorithm

- All Nodes u keep a vector $VC(u)$ with an entry for all nodes in V
 - all components are initialized to 0
 - component corresponding to node v : $VC_v(u)$
- For any non-receive event e at node u , node u computes

$$\underline{VC_u(u)} := VC_u(u) + 1; \quad \underline{VC(e)} := VC(u)$$
- For any send event s at node u , node u attaches the value of $VC(s)$ to the message
- For any receive event r at node u (with corresponding send event s), node u computes

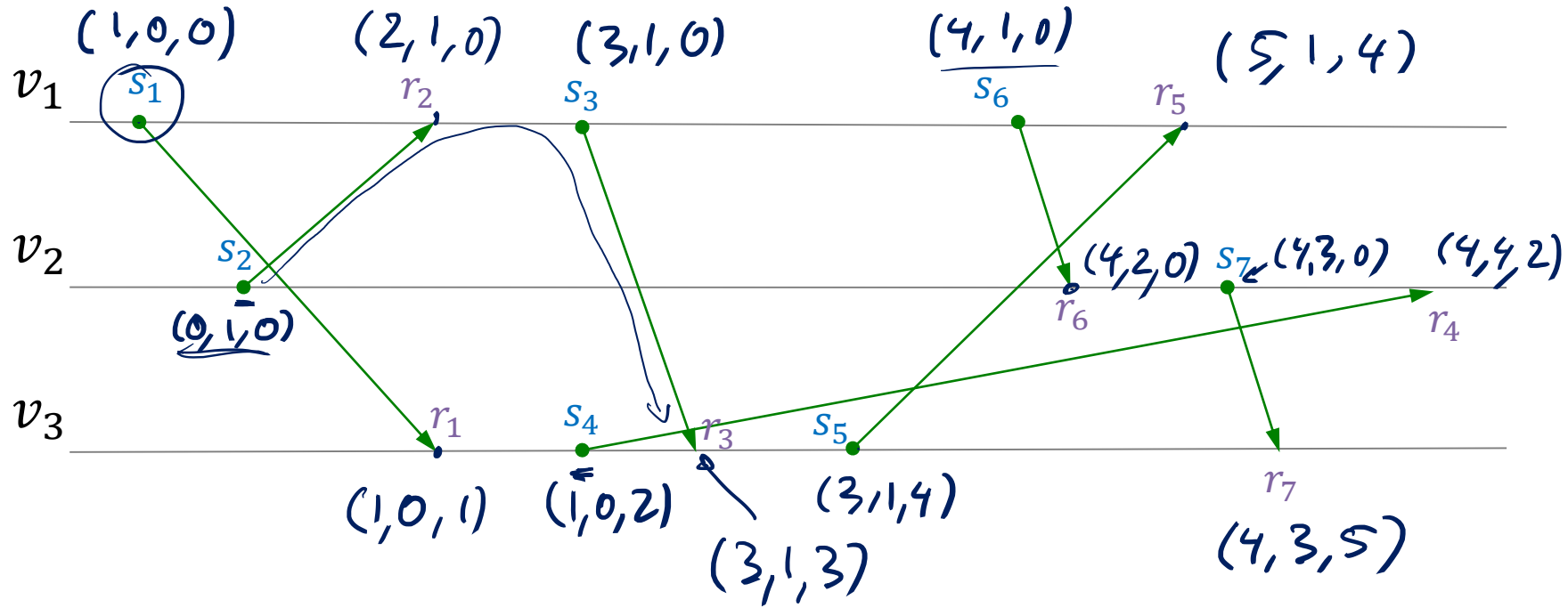
$$\forall v \neq u: \underline{VC_v(u)} := \max\{\underline{VC_v(s)}, VC_v(u)\};$$

$$VC_u(u) := VC_u(u) + 1;$$

$$VC(r) := \underline{VC(u)}$$

Vector Clocks Example

Schedule S



Vector Clocks and Happens-Before

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} < \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix}$$

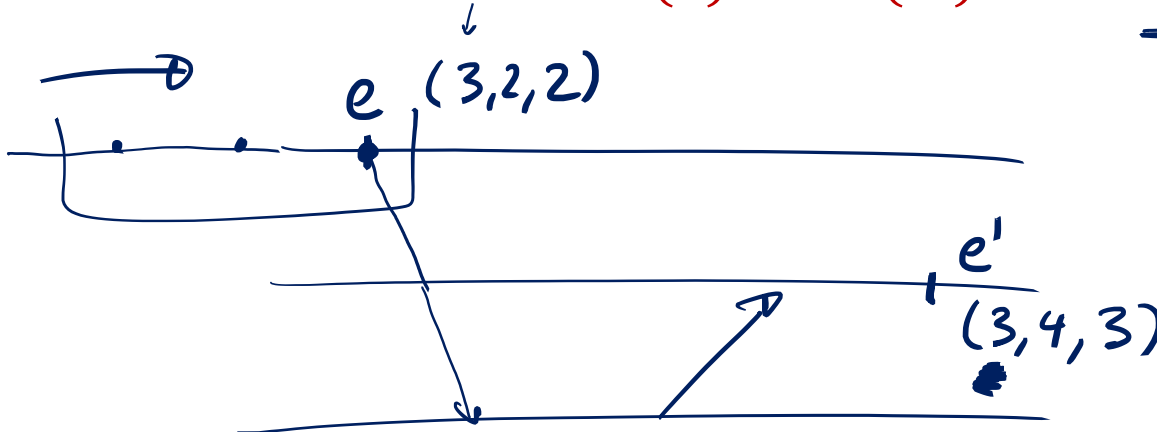


$$x_1 \leq y_1 \wedge x_2 \leq y_2 \wedge x_3 \leq y_3$$

Definition: $\underline{VC}(e) < \underline{VC}(e') := (\forall v \in V: \underline{VC}_v(e) \leq \underline{VC}_v(e')) \wedge (\underline{VC}(e) \neq \underline{VC}(e'))$

Theorem: Given a schedule S , for any two events e and e' ,

$$\underline{VC}(e) < \underline{VC}(e') \iff \underline{e \Rightarrow_s e'}$$

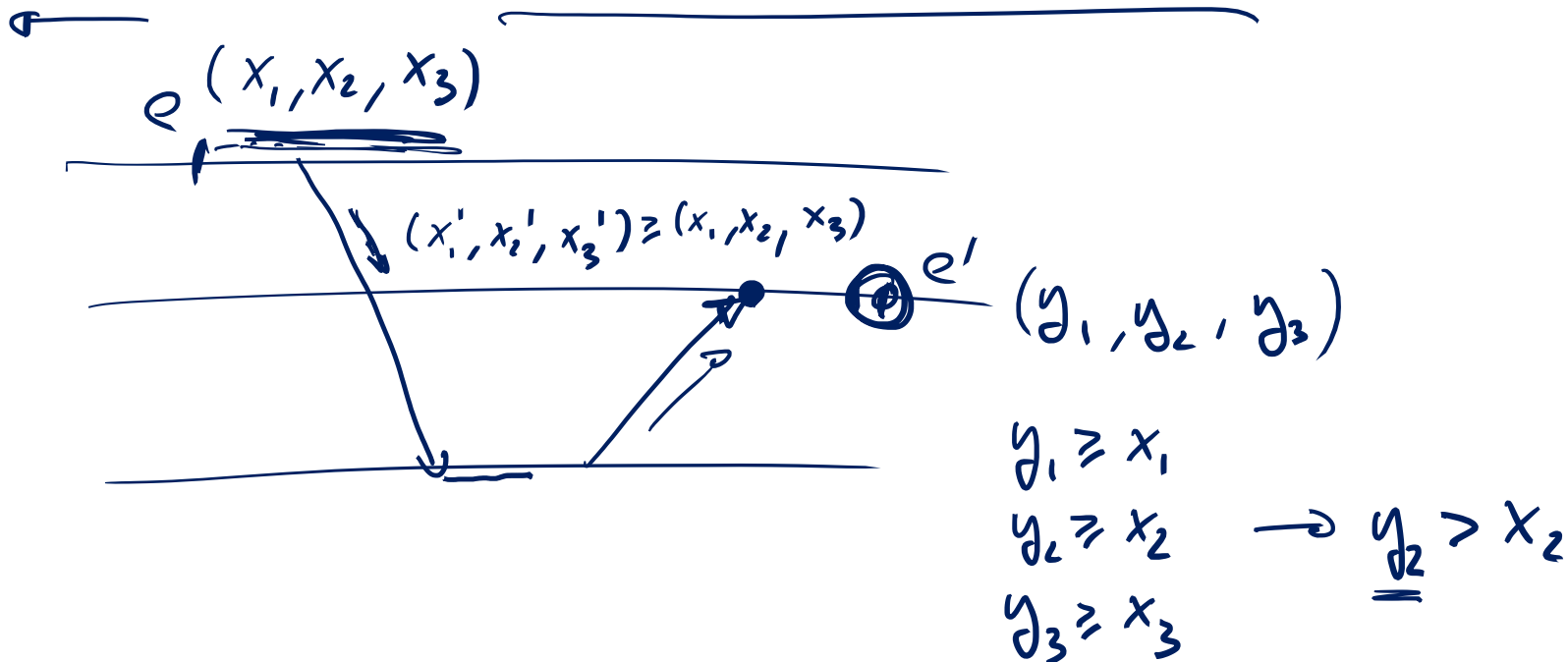


Vector Clocks and Happens-Before

Definition: $VC(e) < VC(e') :=$
 $(\forall v \in V: VC_v(e) \leq VC_v(e')) \wedge (VC(e) \neq VC(e'))$

Theorem: Given a schedule S , for any two events e and e' ,

$$VC(e) < VC(e') \leftrightarrow e \Rightarrow_s e'$$



Logical Clocks vs. Synchronizers

Synchronizer:

- Algorithm that generates clock pulses that allow to run an synchronous algorithm in an asynchronous network
 - We will discuss synchronizers later

The clock pulses (local round numbers) generated by a **synchronizer** can also be used as **logical clocks**

- Send events of round r get clock value $2r - 1$
- Receive events of round r get clock value $2r$
- superset of the happens-before relation
- requires to drastically change the protocol and its behavior
 - synchronizer determines when messages can be sent
- a very heavy-weight method to get logical clock values
 - requires a lot of messages

Replicated State Machine

- main application suggested by Lamport in his original paper
- a shared state machine where every node can issue operations
- state machine is simulated by several replicas

Solution:

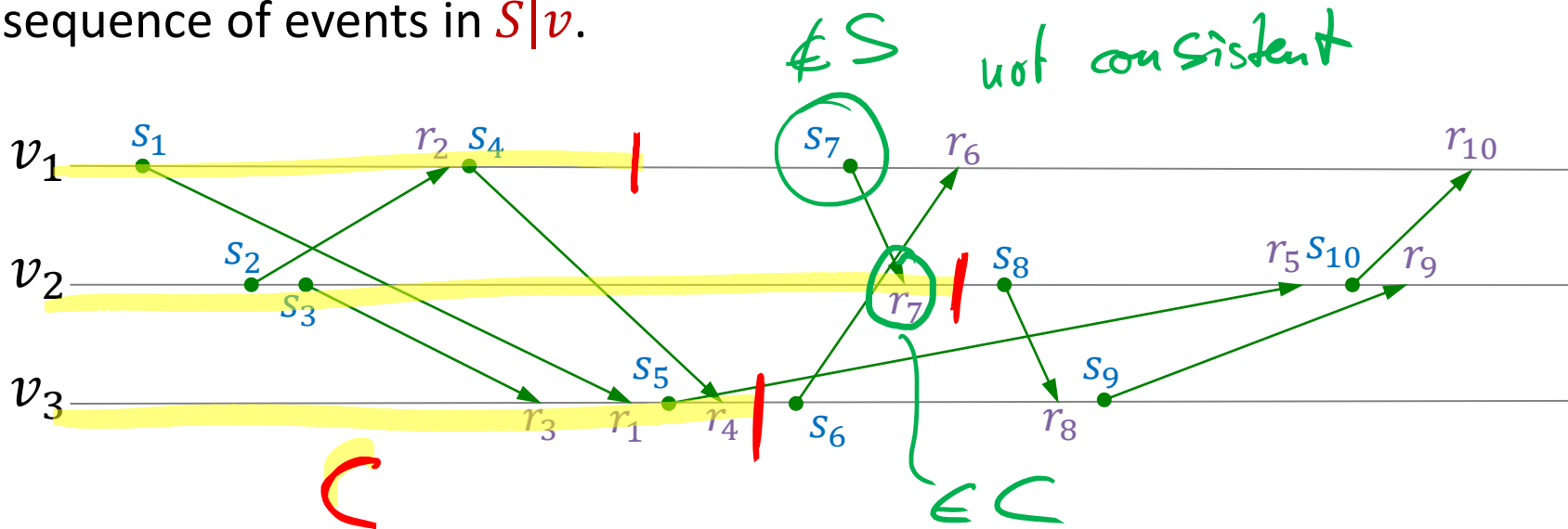
- add current clock value (and issuer node ID) to every operation
- operations have to be carried out in order of clock values / IDs
- **Safety:**
 - all replicas use same order of operations
 - order of operations is a possible actual order (consistent with local views)
- **Liveness:**
 - progress is guaranteed if nodes regularly send messages to each other

- Sometimes the nodes of a distributed system need to figure out the global state of the system
 - e.g., to find out if some property about the system state is true
- Executions/schedules which lead to the same happens-before relation (i.e., causal shifts) cannot be distinguished by the system.
- Generally not possible to record the global state at any given time of the execution
- Best solution: A global state which is consistent with all local views
 - i.e., a state which could have been true at some time
- Called a **consistent** or **global snapshot** of the system and based on **consistent cuts** of the schedule

Consistent Cut

Cut

Given a schedule S , a **cut** is a **subset C of the events of S** such that for all nodes $v \in V$, the events in C happening at v form a **prefix** of the sequence of events in $S|v$.

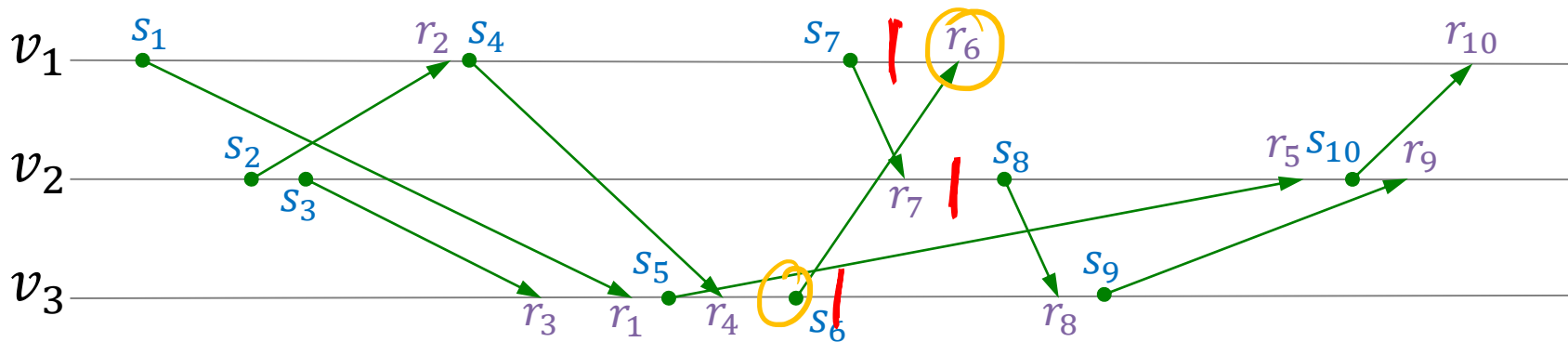


Consistent Cut

Consistent Cut

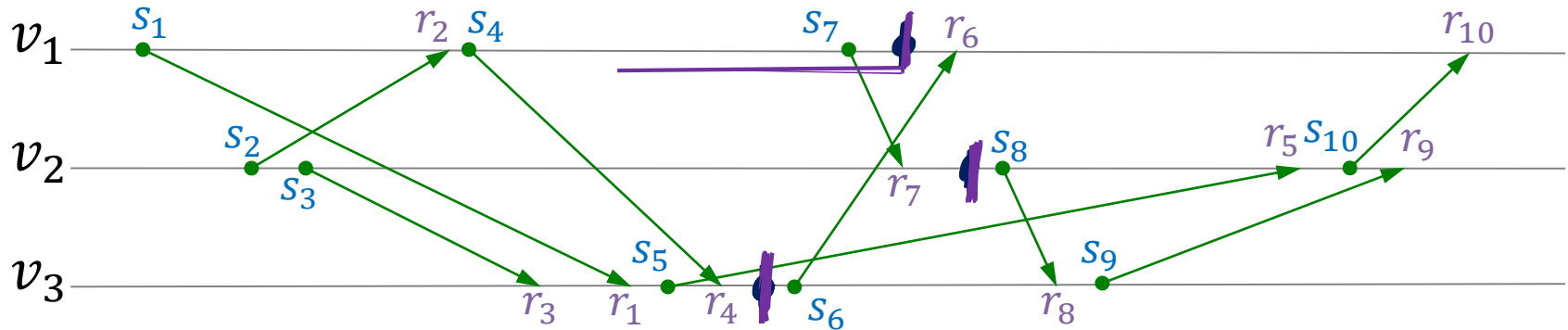
Given a schedule S , a **consistent cut** C is cut such that for all events $e \in C$ and all events f in S , it holds that

$$\underline{f \Rightarrow_s e} \rightarrow f \in C$$

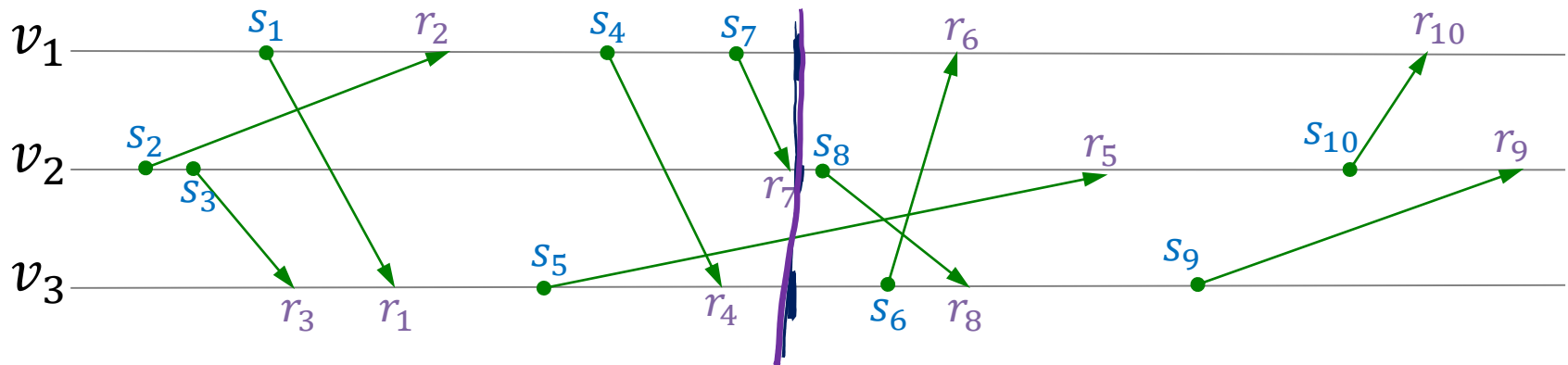


Consistent Cut

Schedule S



Some Causal Shuffle S'



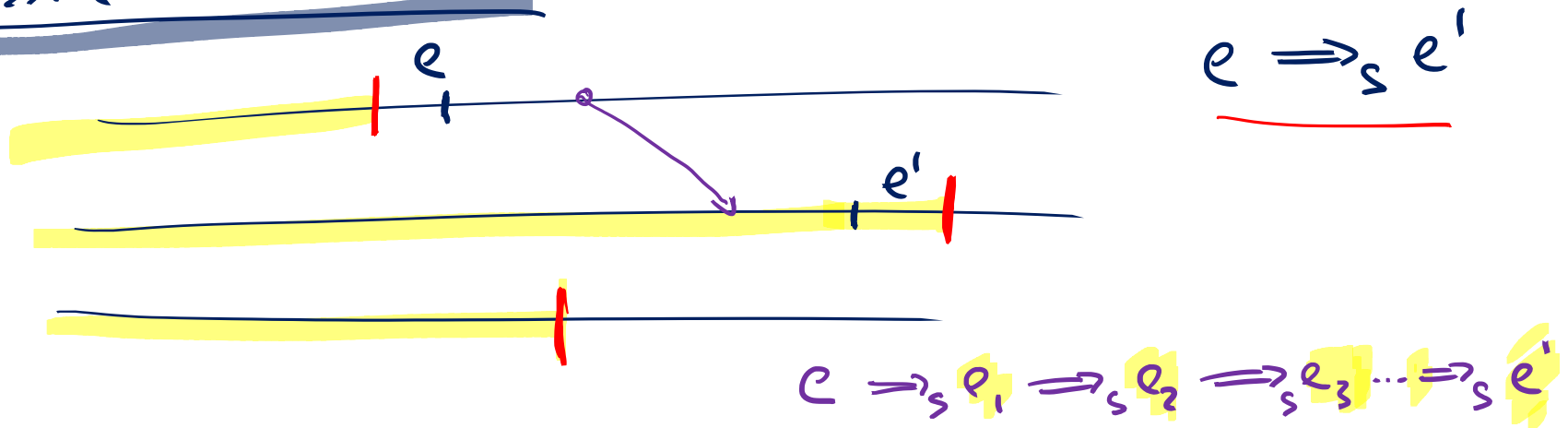
Consistent Cuts

Claim: Given a schedule S , a cut C is a consistent cut if and only if for each message M with send event s_M and receive event r_M , if $r_M \in C$, then it also holds that $s_M \in C$.

$\forall M: r_M \in C \rightarrow s_M \in C \iff C \text{ consistent}$
def. of consistent cuts

other dir. (\rightarrow)

assume C not consistent:



Consistent Snapshot

Consistent Snapshot = Global Snapshot = Consistent Global State

- A consistent snapshot is a global system state which is consistent with all local views.

Global System State (for schedule S)

- A vector of intermediate states (in S) of all nodes and a description of the messages currently in transit
 - Remark: If nodes keep logs of messages sent and received, the local states contain the information about messages in transit.

Consistent Snapshot

- A global system state which is an intermediate global state for some causal shuffle of S (consistent with all local views)