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Chapter 6 Consensus II

Theory of Distributed Systems

Overview



- Introduction
- Consensus #1: Shared Memory
- Consensus #2: Wait-free Shared Memory
- Consensus #3: Read-Modify-Write Shared Memory
- Consensus #4: Synchronous Systems
- Consensus #5: Byzantine Failures
- Consensus #6: A Simple Algorithm for Byzantine Agreement
- Consensus #7: The Queen Algorithm
- Consensus #8: The King Algorithm
- Consensus #9: Byzantine Agreement Using Authentication
- Consensus #10: A Randomized Algorithm
- Shared Coin
- Most slides by R. Wattenhofer (ETHZ)

Theory of Distributed Systems

Consensus More Formally



Setting:

- *n* processes/threads/nodes $v_1, v_2, ..., v_n$
- Each process has an input $x_1, x_2, \dots, x_n \in \mathcal{D}$
- Each (non-failing) process computes an output $y_1, y_2, \dots, y_n \in D$

Agreement:

The outputs of all non-failing processes are equal.

Validity:

If all inputs are equal to x, all outputs are equal to x.

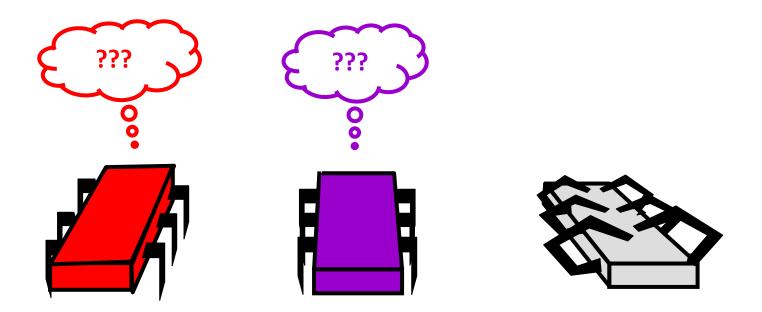
Termination:

All non-failing processes terminate after a finite number of steps.



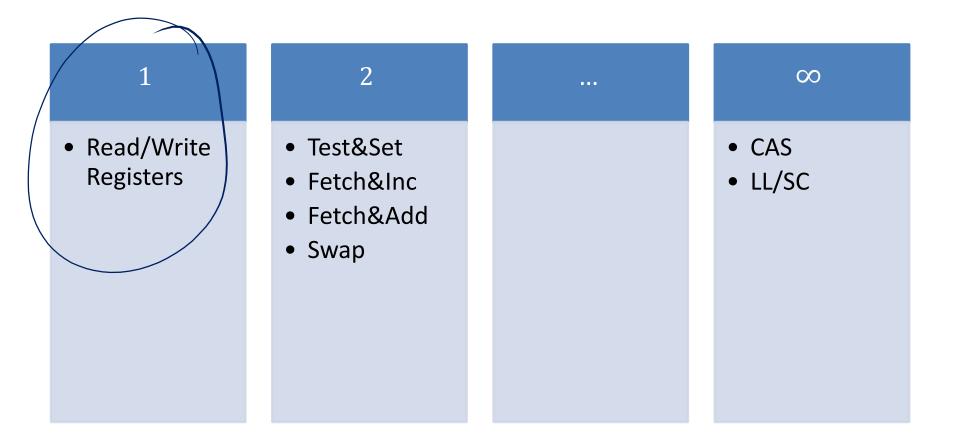
Theorem

There is no deterministic asynchronous wait-free consensus algorithm using read/write atomic registers.



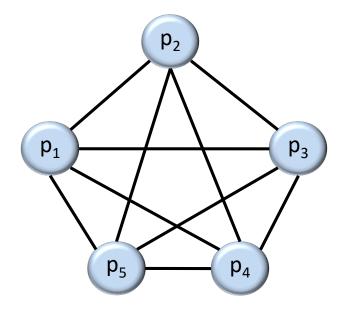
The Consensus Hierarchy





Consensus #4: Synchronous Systems

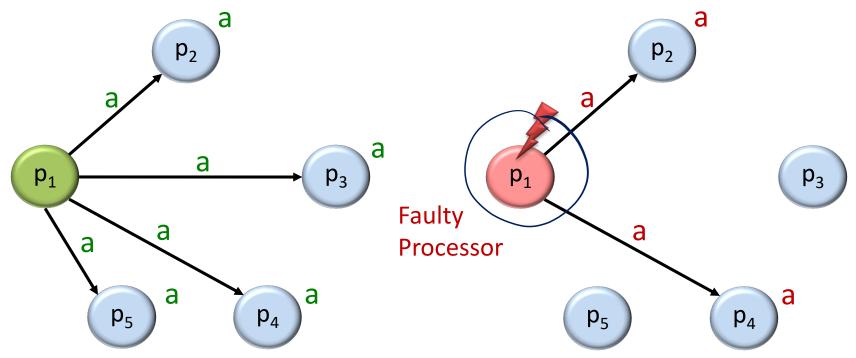
- One can sometimes tell if a processor has crashed
 - Timeouts
 - Broken TCP connections
- Can one solve consensus at least in synchronous systems?
- Model
 - All communication occurs in synchronous rounds
 - Complete communication graph



Crash Failures

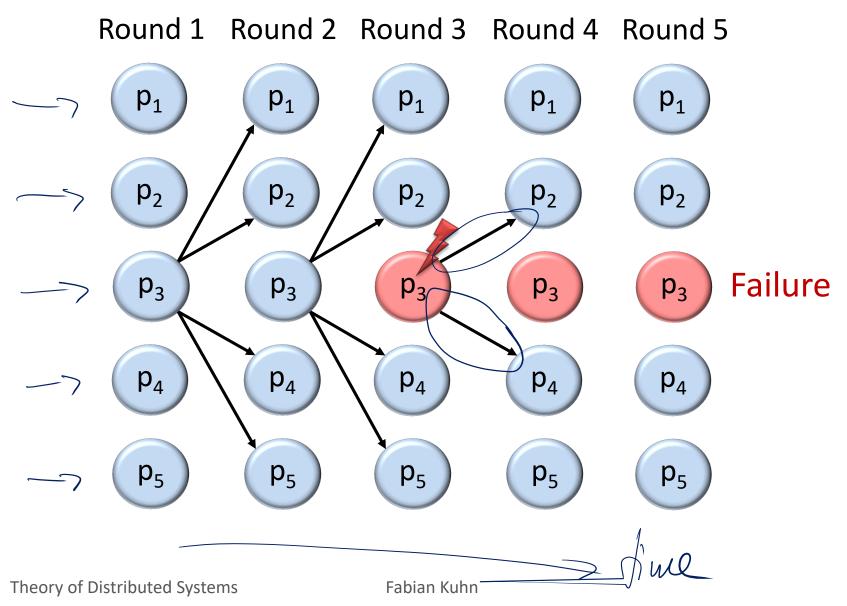


- Broadcast: Send a message to all nodes in one round
 - At the end of the round everybody receives the message a
 - Every process can broadcast a value in each round
- Crash Failures: A broadcast can fail if a process crashes
 - Some of the messages may be lost, i.e., they are never received



Process disappears after failure

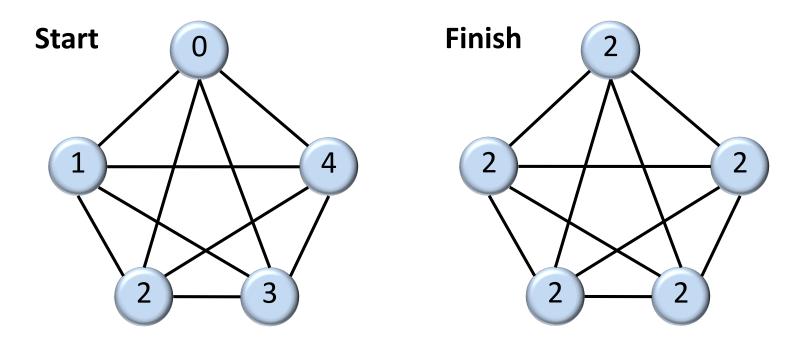




Consensus Repetition



- Input: everybody has an initial value
- Agreement: everybody must decide on the same value



• Validity conditon: If everybody starts with the same value, everybody must decide on that value



Each process:

- 1. Broadcast own value
- 2. Decide on the minimum of all received values

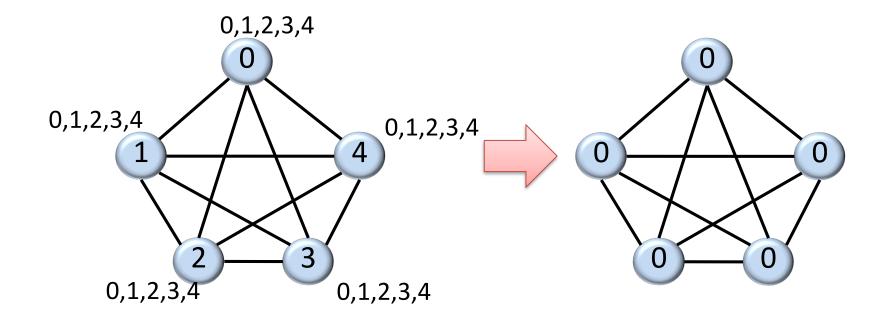
Including the own value

Note than only one round is needed!

Execution Without Failures

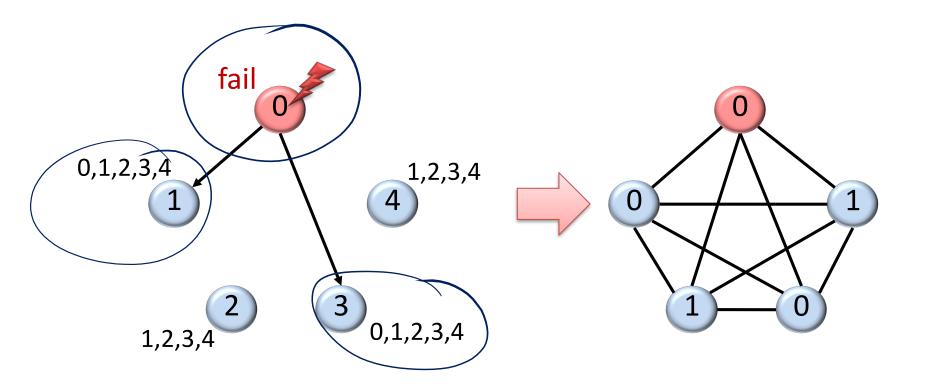


- Broadcast values and decide on minimum \rightarrow Consensus!
- Validity condition is satisfied: If everybody starts with the same initial value, everybody sticks to that value (minimum)



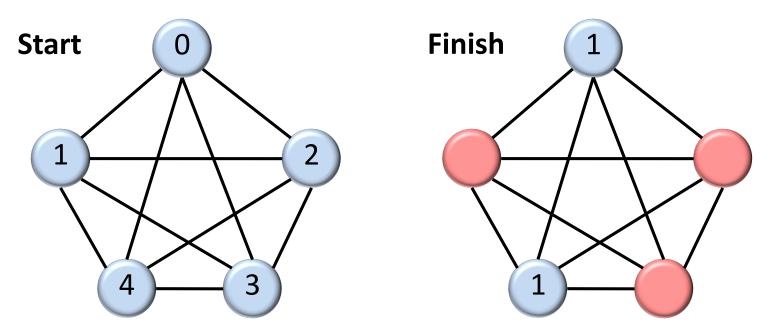
Execution With Failures

- The failed processor doesn't broadcast its value to all processors
- Decide on minimum \rightarrow No consensus!



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- If an algorithm solves consensus for f failed processes, we say it is an f-resilient consensus algorithm
- Example: The input and output of a 3-resilient consensus alg.



• Refined validity condition:

All processes decide on a value that is available initially

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Each process:

Round 1: Broadcast own value

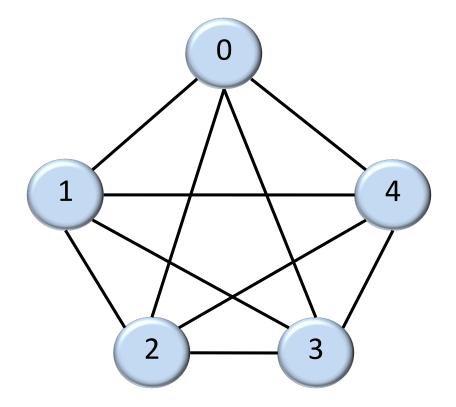
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Round 2 to round f + 1:
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Broadcast the minimum of the received values (unless it has been sent before)

End of round f + 1: Decide on the minimum value received

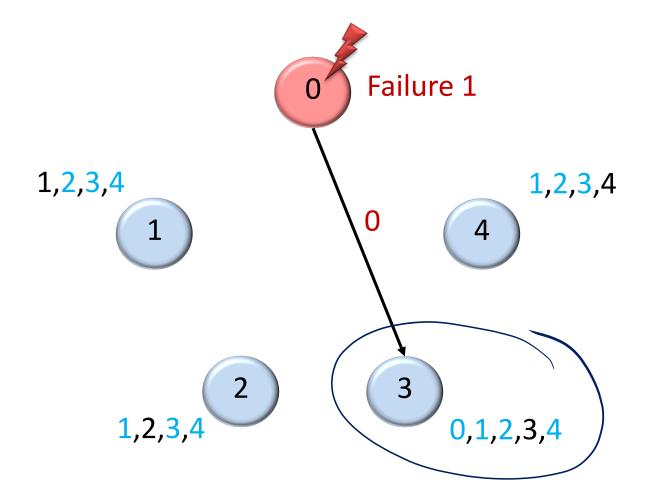


• Example: f = 2 failures, f + 1 = 3 rounds needed



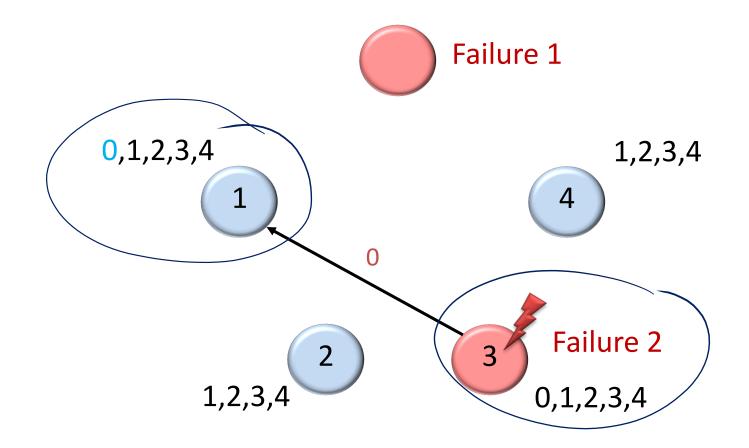


• Round 1: Broadcast all values to everybody



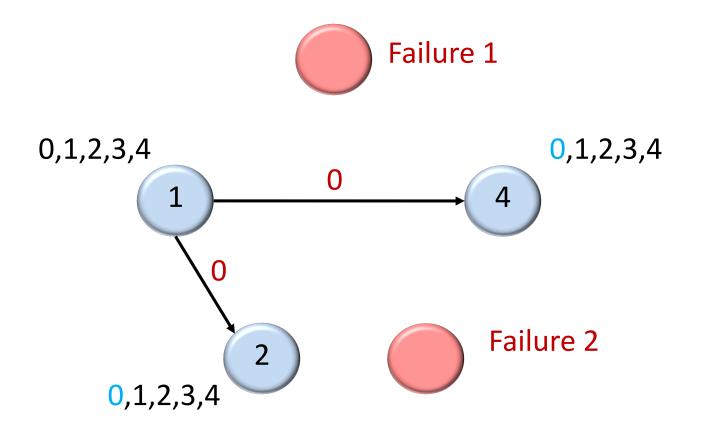
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• Round 2: Broadcast all new values to everybody



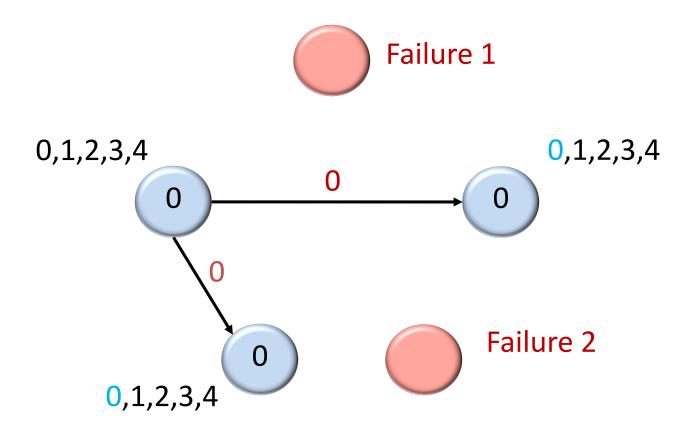
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• Round 3: Broadcast all new values to everybody





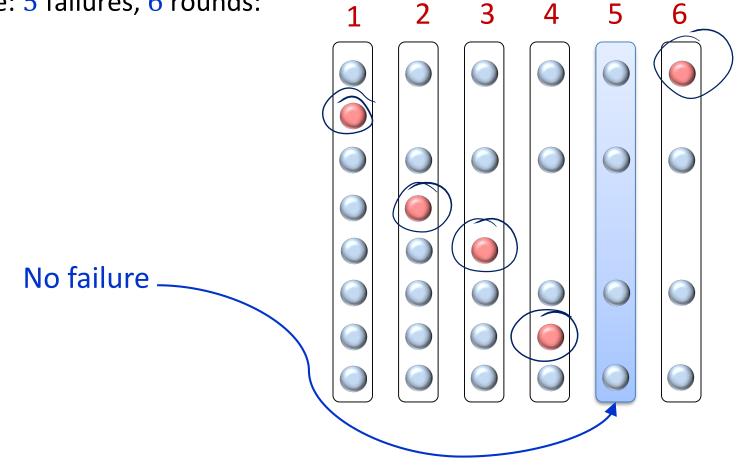
• Decide on minimum \rightarrow Consensus!



Analysis



- If there are f failures and f + 1 rounds, then there is a round with no failed process
- Example: 5 failures, 6 rounds:



Analysis



- At the end of the round with no failure
 - Every (non faulty) process knows about all the values of all the other participating processes
 - This knowledge doesn't change until the end of the algorithm
- Therefore, everybody will decide on the same value
- However, as we don't know the exact position of this round, we have to let the algorithm execute for f + 1 rounds
- Validity: When all processes start with the same input value, then consensus is that value

Theorem



Theorem

If at most $f \le n - 2$ of n nodes of a synchronous message passing system can crash, at least f + 1rounds are needed to solve consensus.

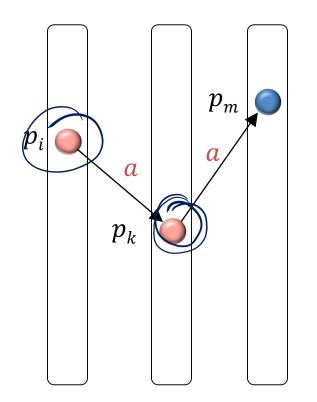
Proof idea:

- Show that f rounds are not enough if $n \ge f + 2$
- Before proving the theorem, we consider a

"worst-case scenario": In each round one of the processes fails

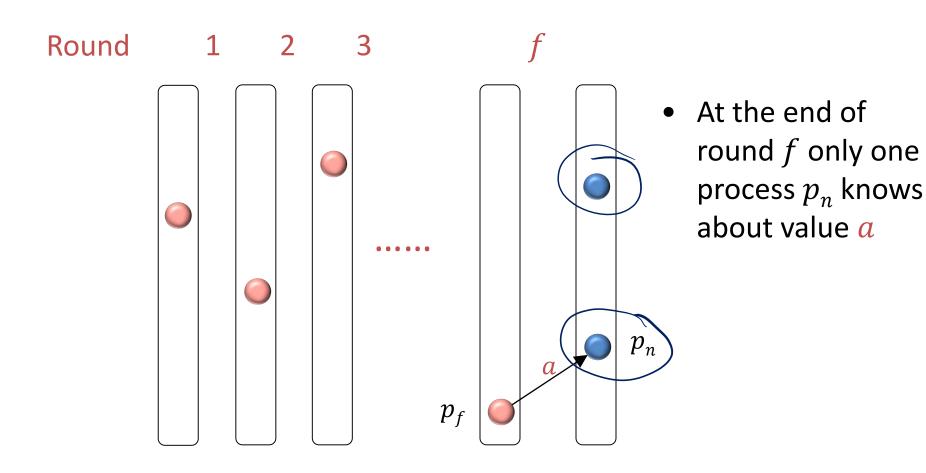




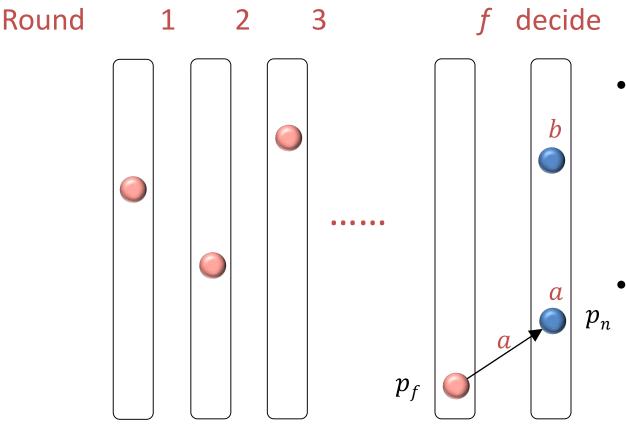


- Before process p_i fails, it sends its value a only to one process p_k
- Before process p_k fails, it sends its value a to only one process p_m









- Process p_n may decide on *a* and all other processes may decide on another value *b*
- *f* rounds are not enough ⇒ at least *f* + 1 rounds are needed

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Recall from earlier in the course:

- For the impossibility proof of the two generals problem, we used an indistinguishability proof
- Execution \underline{E} is indistinguishable from execution $\underline{E'}$ for some node v if v sees the same things in both executions.
 - same inputs and messages (schedule)
- If *E* is indistinguishable from *E'* for *v*, then *v* does the same thing in both executions.
 - We denoted this by $\underline{E}|v = E'|v|$

Similarity:

• Call E_i and E_j similar if $\underline{E_i | v = E_j | v}$ for some node v

$$E_{i} \sim_{v} E_{j} \Leftrightarrow E_{i} | v = E_{j} | v$$

$$E_{i} \sim E_{j} \iff \exists v \in \mathcal{E}_{i} \land \mathcal{E}_{i}$$

Theory of Distributed Systems



Similarity Chain:

• Consider a sequence of executions $E_1, E_2, E_3, \dots, E_T$ such that

$$\forall i \geq 1 : E_i \sim_{v_i} E_{i+1}$$

- any two consecutive executions E_i and E_{i+1} are indistinguishable for some node v_i (we assume that v_i does not crash in E_i and E_{i+1})
- Indistinguishability:

 $\forall i \geq 1$: Node v_i decides on the same value in E_i and E_{i+1}

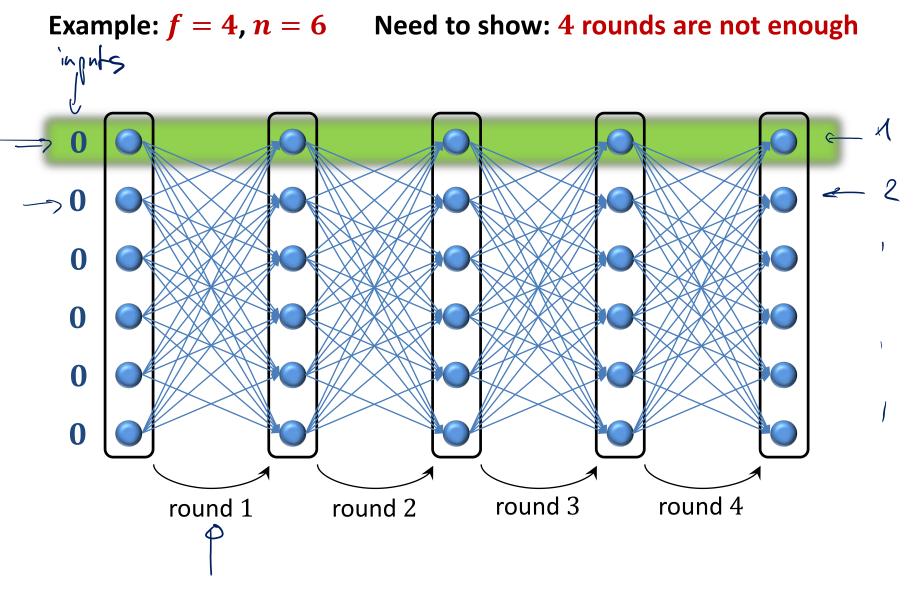
• Agreement:

 $\forall i \geq 1$: All nodes decide on the same value in E_i and E_{i+1}

- Hence, all executions E_1, \ldots, E_T have the same decision value!
- Goal:

<u> E_1 : no crashes, all inputs are 0</u>; <u> E_T : no crashes, all inputs are 1</u>

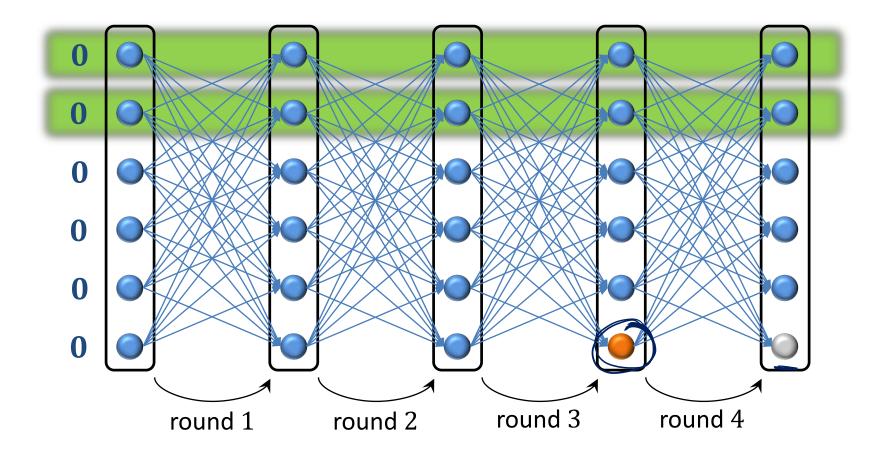




Theory of Distributed Systems

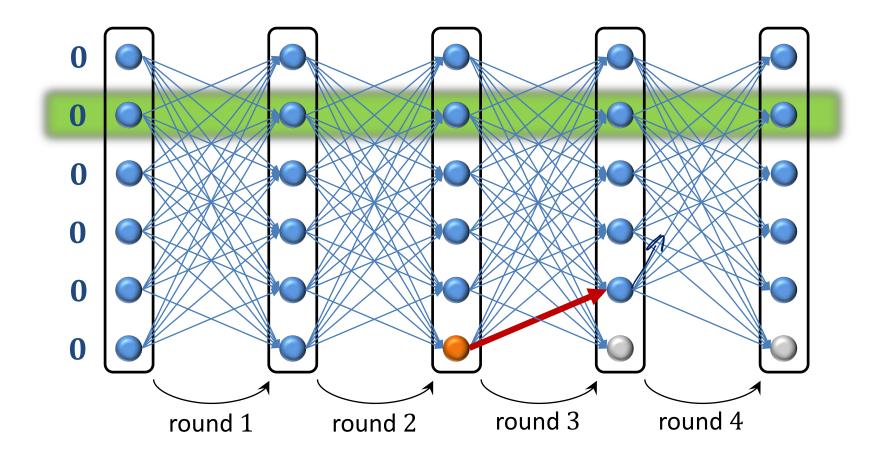


Example: f = 4, n = 6 Need to show: 4 rounds are not enough



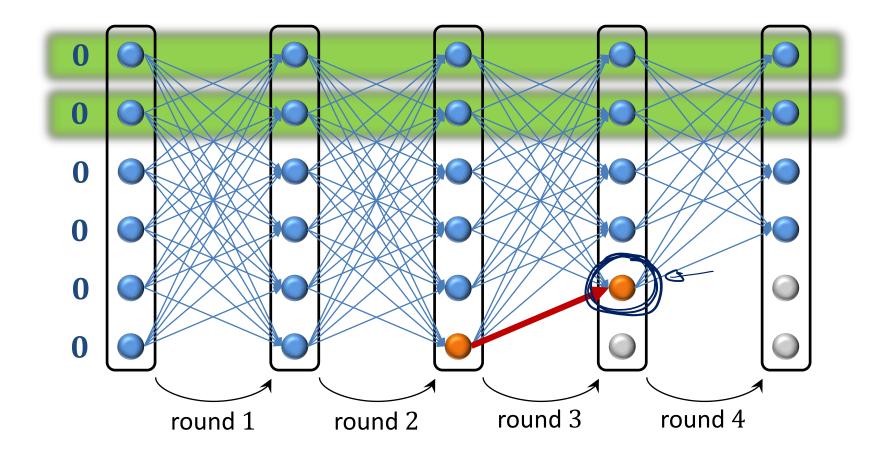


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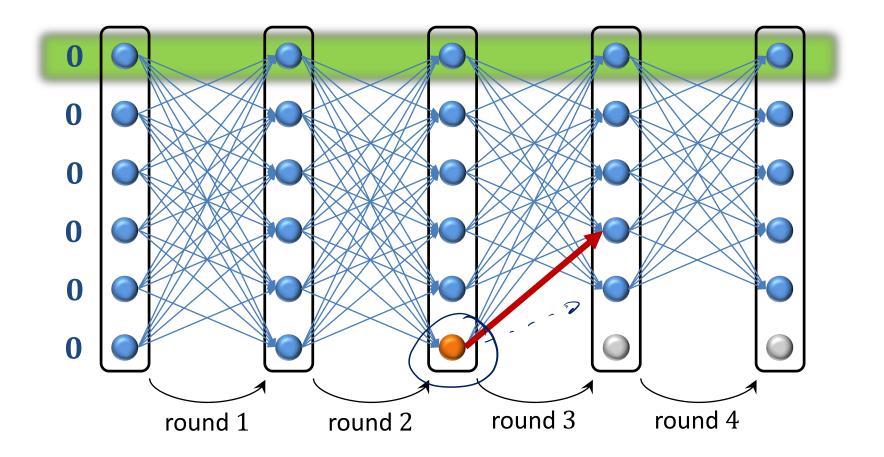


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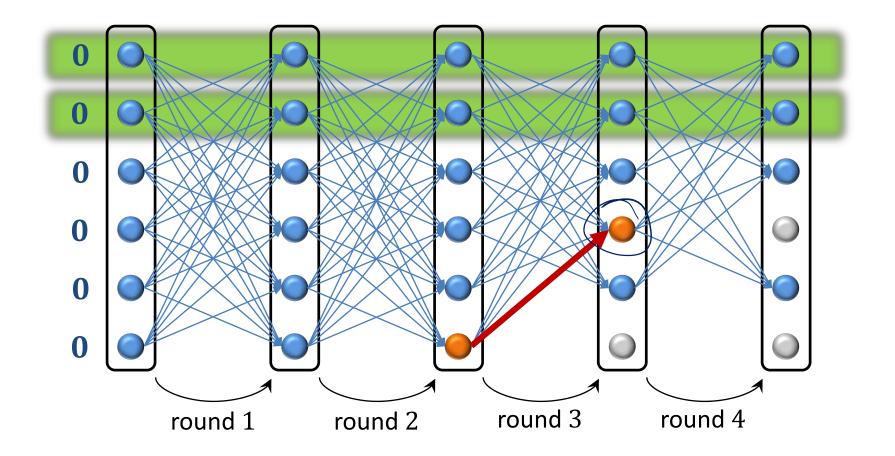


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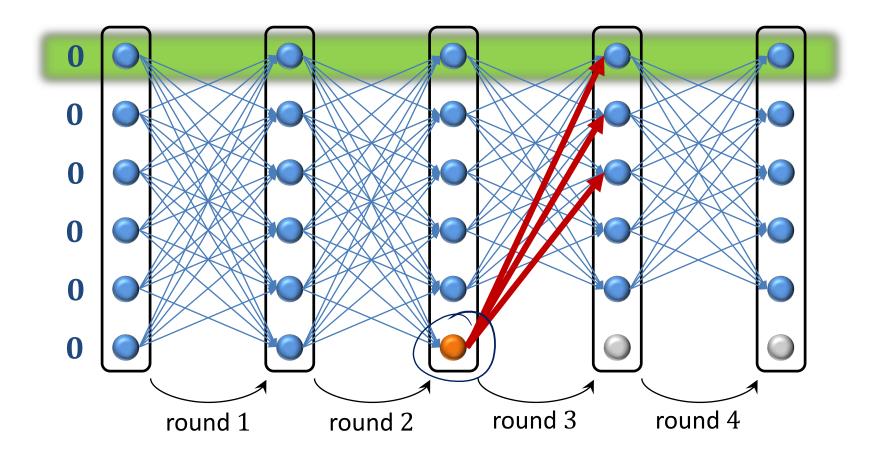


Example: f = 4, n = 6 Need to show: 4 rounds are not enough



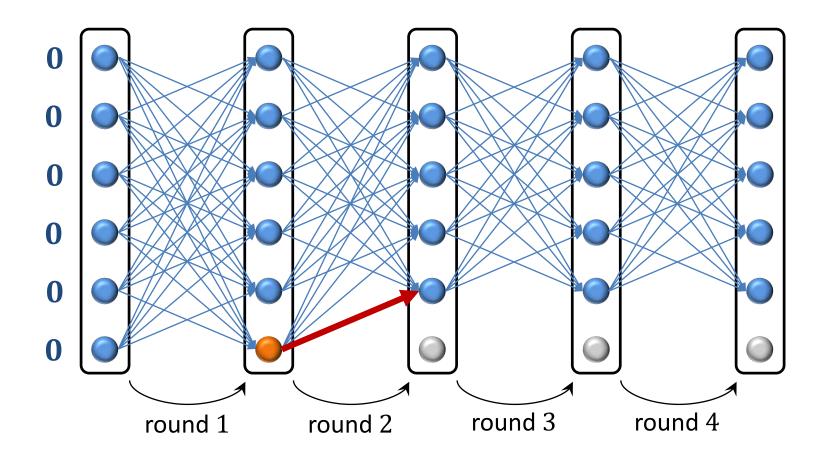


Example: f = 4, n = 6 Need to show: 4 rounds are not enough



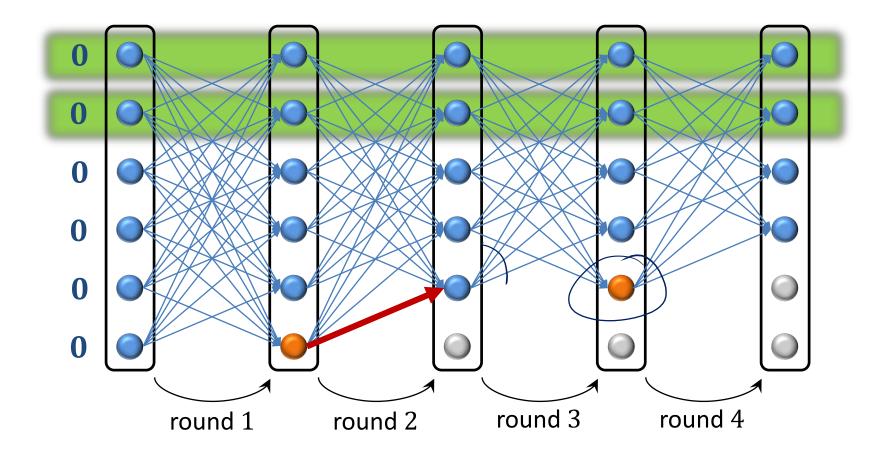


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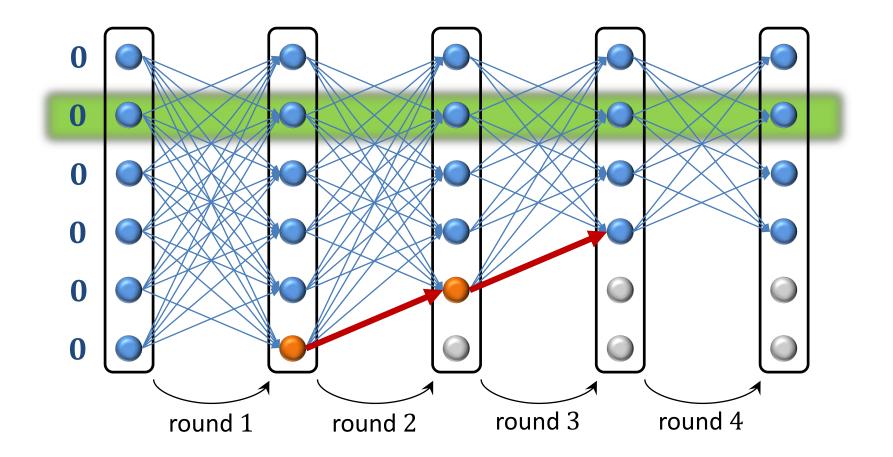


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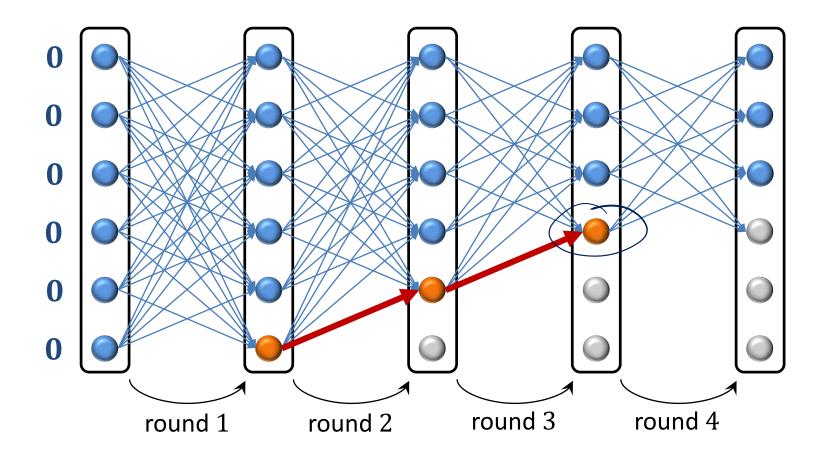


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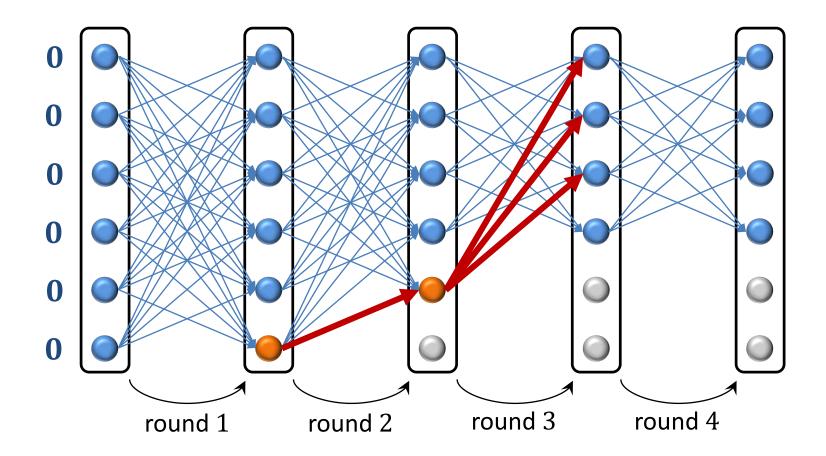


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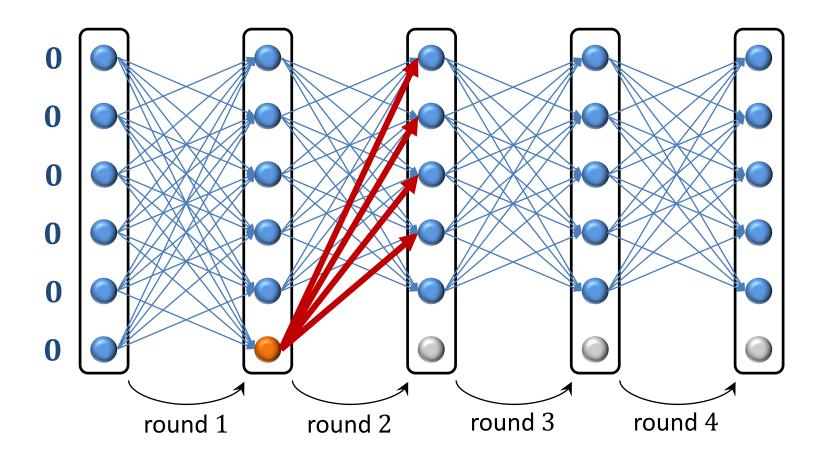




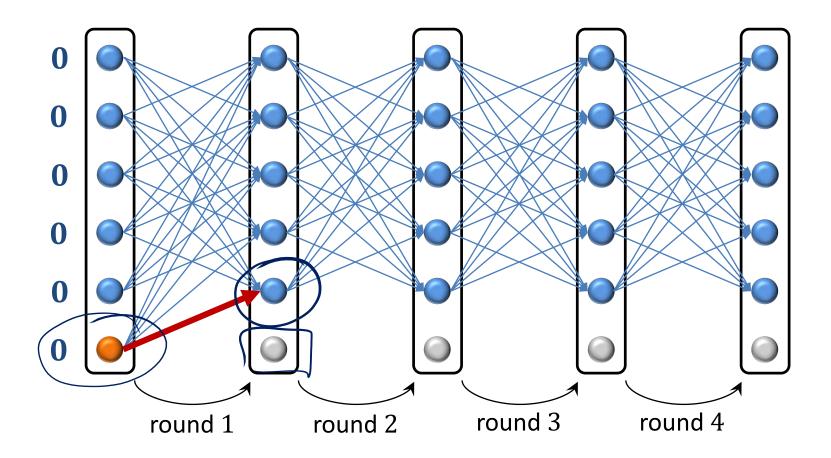




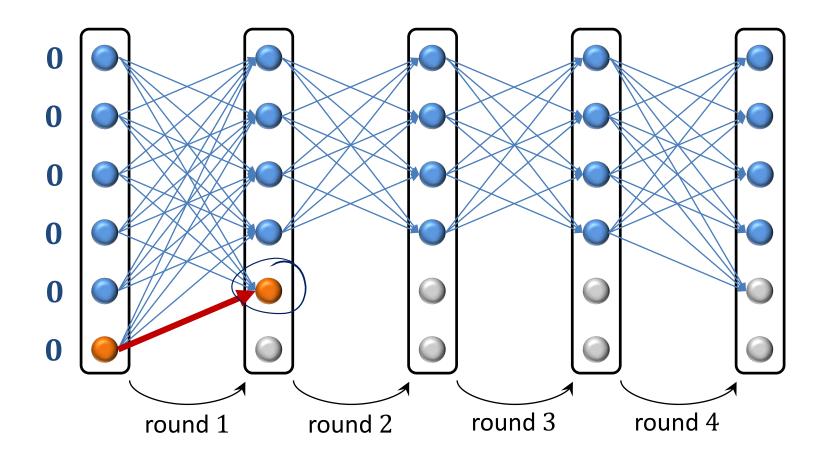




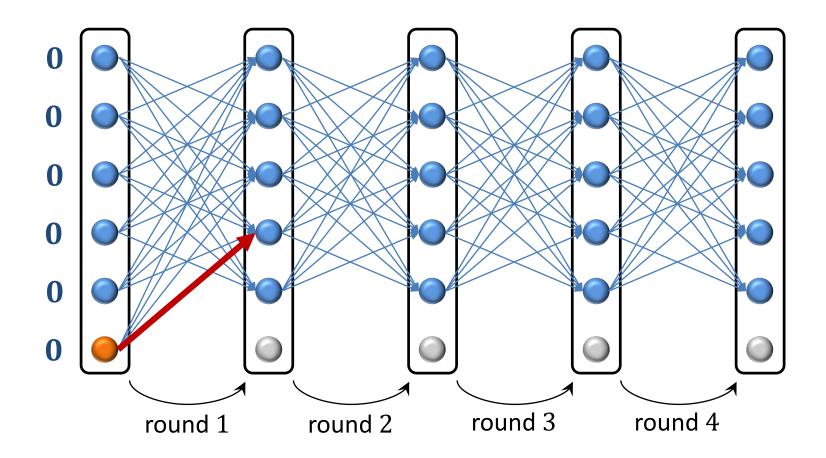




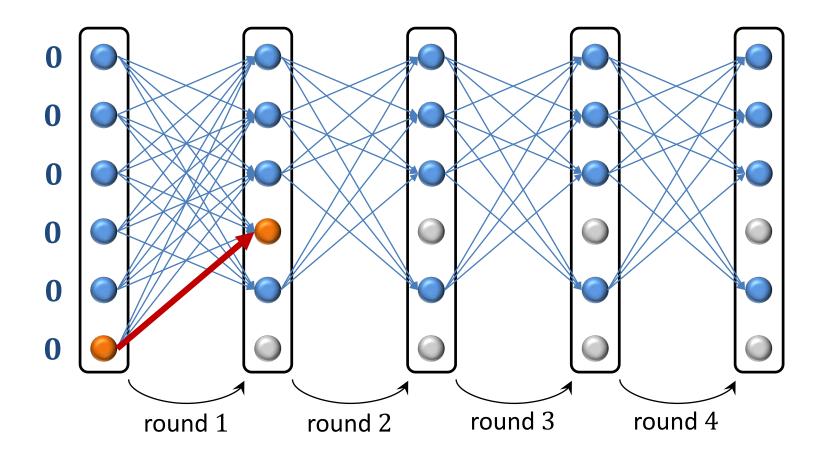




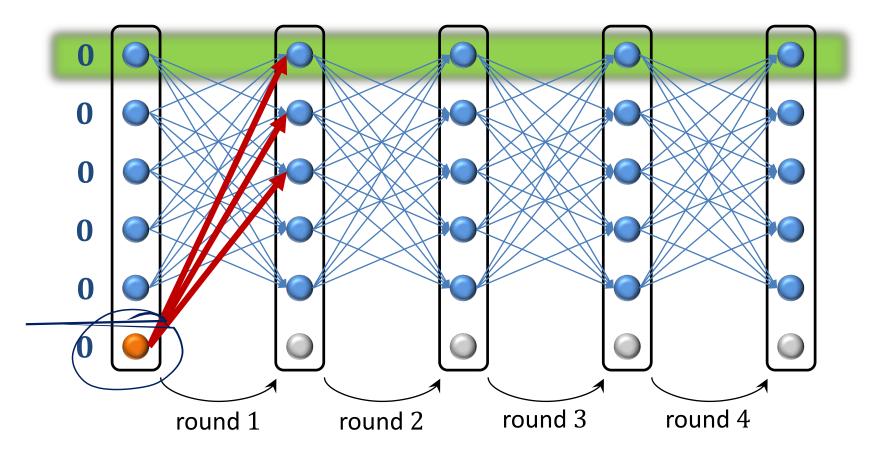




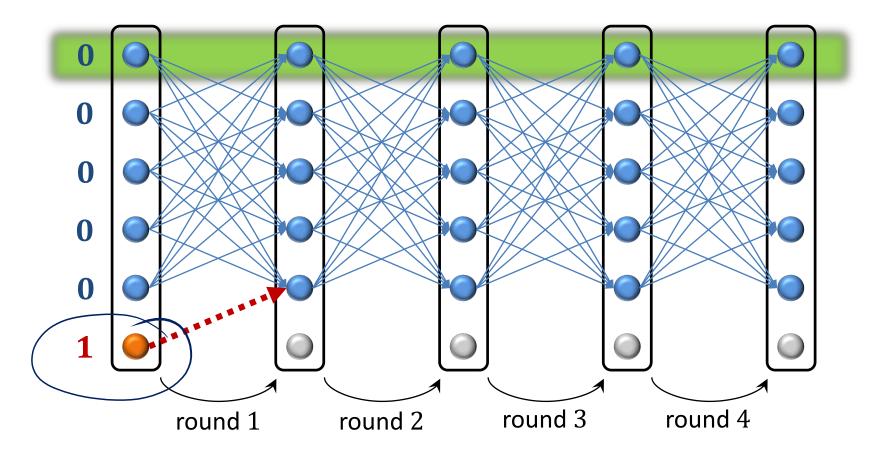




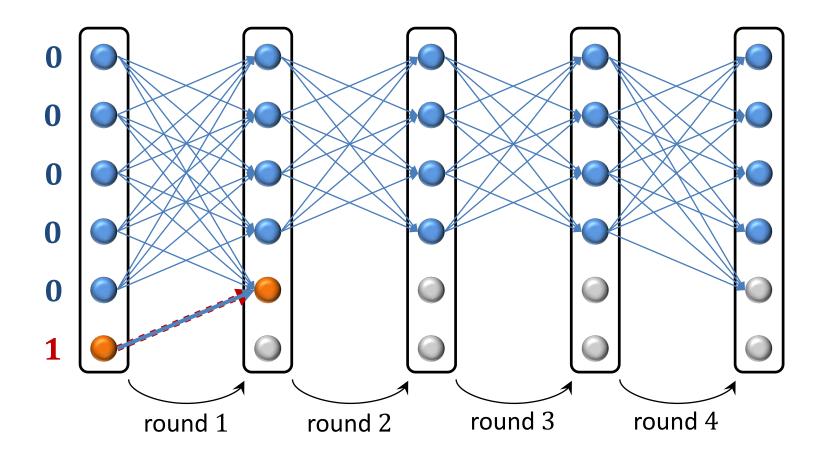




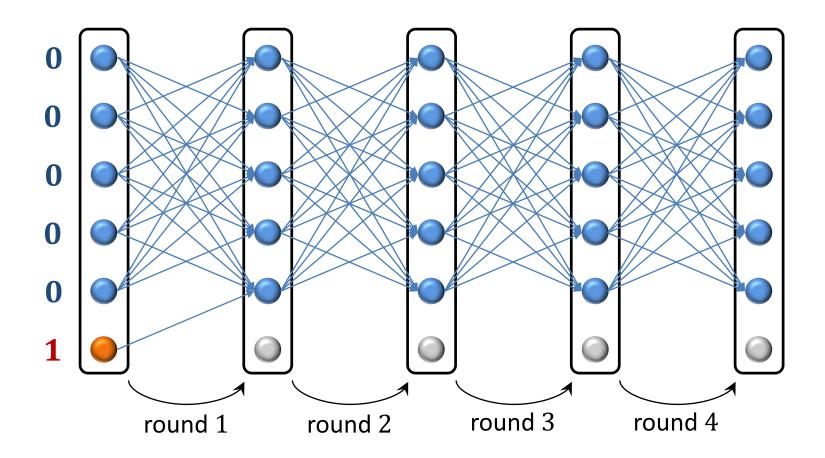




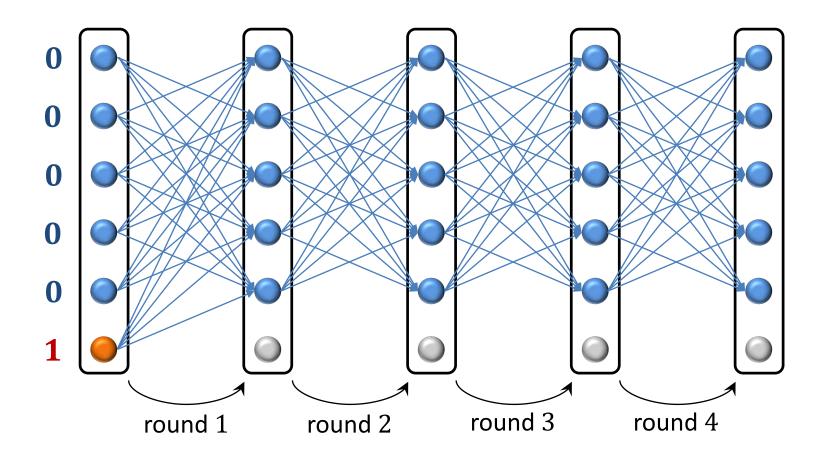




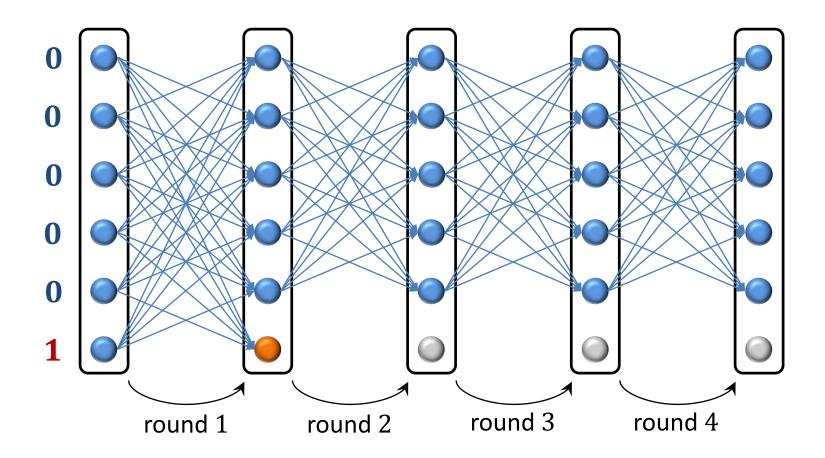




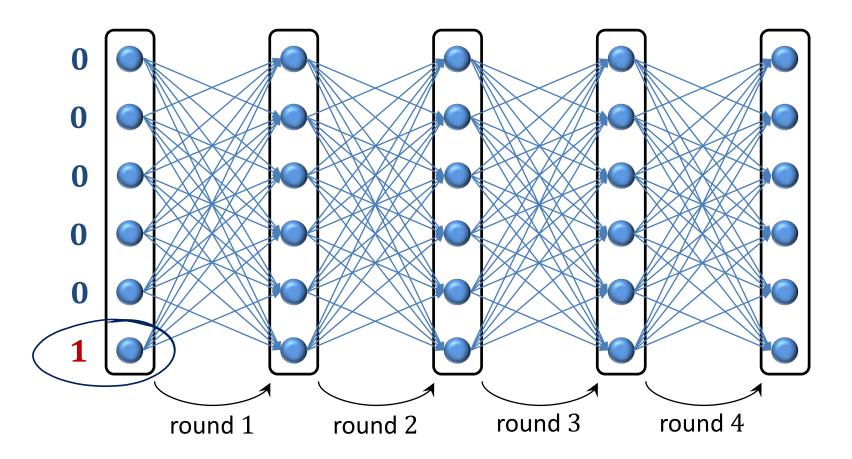






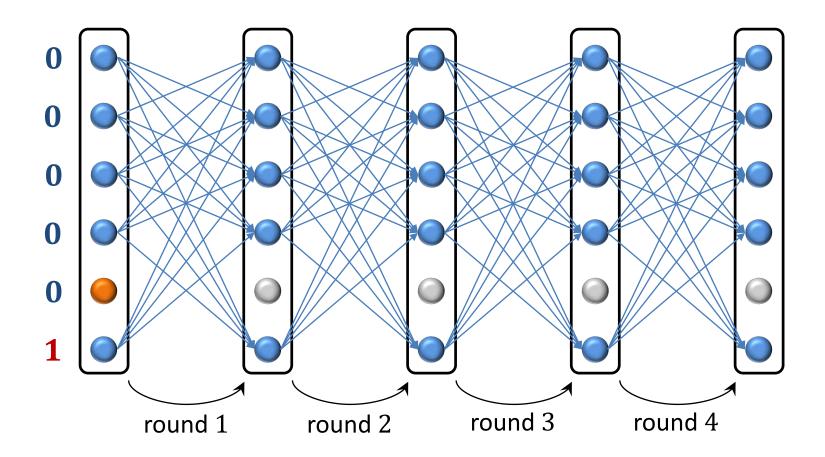








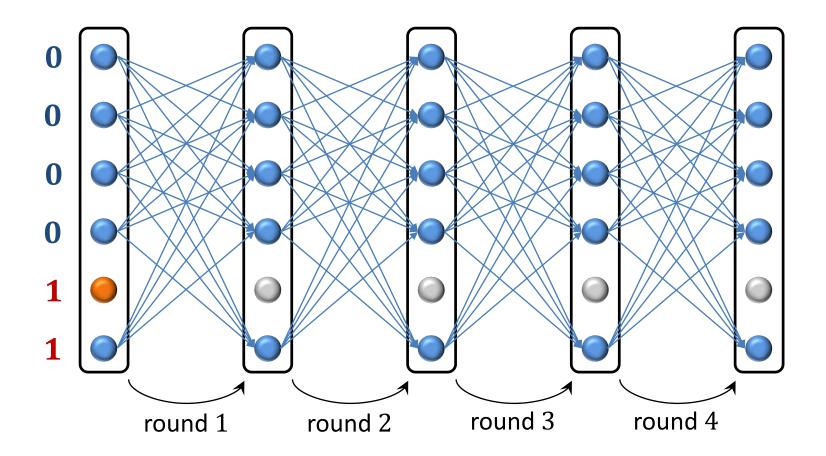
Example: f = 4, n = 6 Need to show: 4 rounds are not enough



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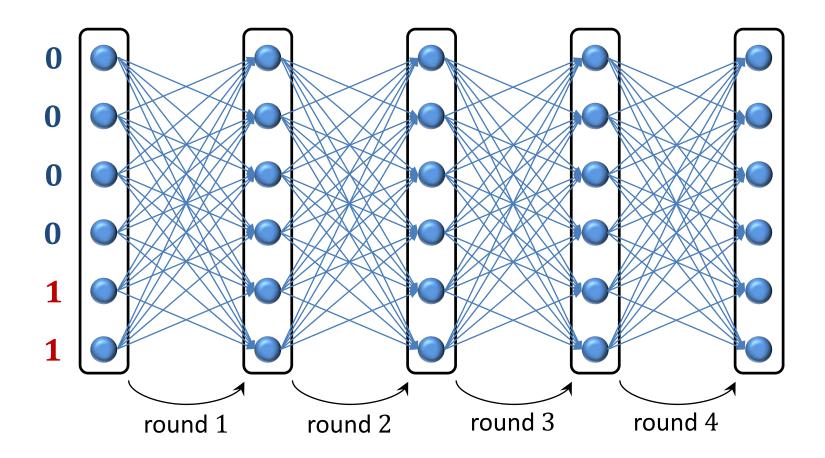


Example: f = 4, n = 6 Need to show: 4 rounds are not enough

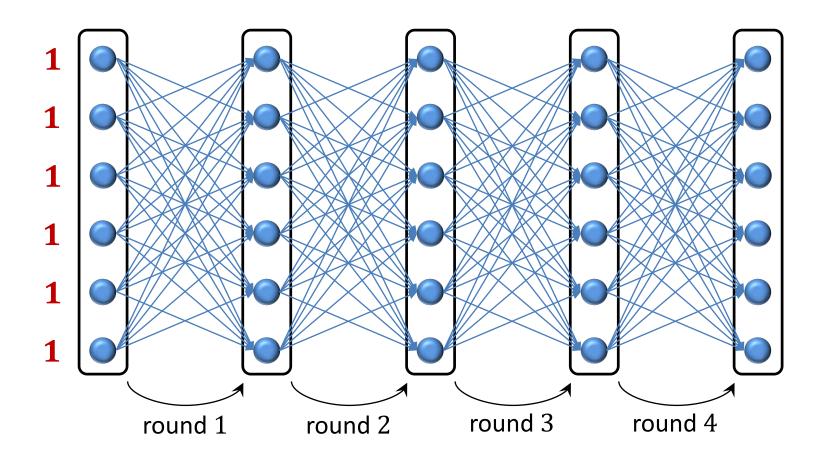


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Theorem

If at most $f \le n - 2$ of n nodes of a synchronous message passing system can crash, at least f + 1rounds are needed to solve consensus.

Proof Sketch:

- Similarity chain starting with fault-free all-zeroes execution and ending with fault-free all-ones execution
- In all executions, at most one crash per round
- Construction works as long as there are at least 2 non-faulty nodes in each execution ($n \ge f + 2$)
- Validity: all-zeroes ⇒ decision 0; all-ones ⇒ decision 1
 Similarity Chain: same decision in all executions

Arbitrary Behavior

- UNI FREIBURG
- The assumption that processes crash and stop forever is sometimes too optimistic
- Maybe the processes fail and recover:

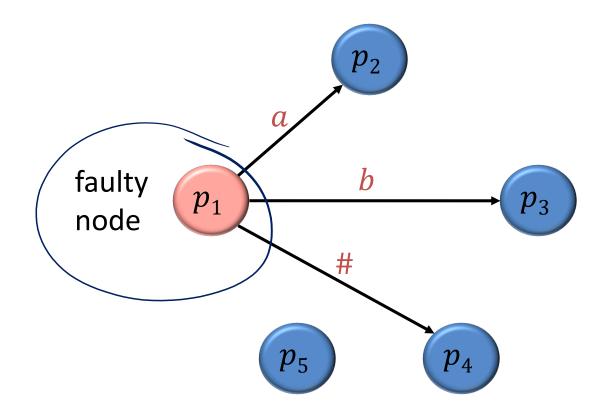
Probably Are you there? not... ??? Are you there? Time a!

• Maybe the processes are damaged:

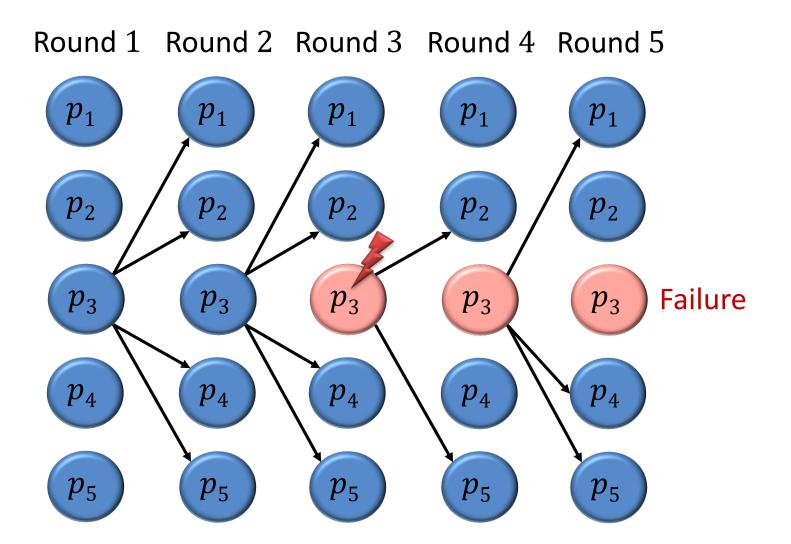
Consensus #5: Byzantine Failures



- Different processes may receive different values
- A Byzantine process can behave like a crash-failed process







Consensus with Byzantine Failures



- Again: If an algorithm solves consensus for *f* failed processes, we say it is an *f*-resilient consensus algorithm
- Validity: If all non-faulty processes start with the same value, then all non-faulty processes decide on that value
 - Note that in general this validity condition does not guarantee that the final value is an input value of a non-Byzantine process
 - However, if the input is binary, then the validity condition ensures that processes decide on a value that at least one non-Byzantine process had initially
- Obviously, any f-resilient consensus algorithm requires at least f + 1 rounds (follows from the crash failure lower bound)
- How large can *f* be...? Can we reach consensus as long as the majority of processes is correct (non-Byzantine)?



Theorem

There is no f-resilient Byzantine consensus algorithm for n nodes for $f \ge n/3$

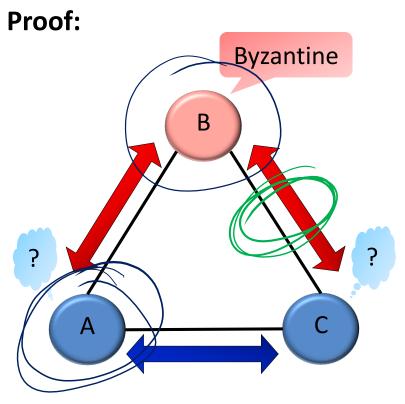
Proof outline

- First, we discuss the <u>3 node case</u>
 - not possible for f = 1
- The general case can then be proved by reduction from the 3 node case
 - Given an algorithm for n node and f faults for $f \ge n/3$, we can construct a 1-resilient 3-node algorithm



Lemma

There is no 1-resilient algorithm for 3 nodes



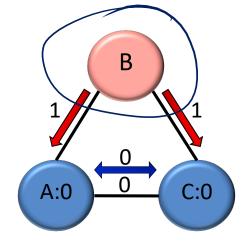
Intuition:

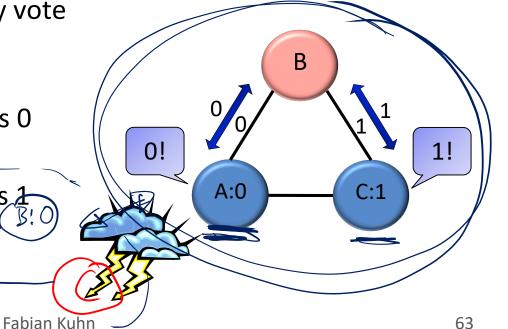
- Node A may also receive information from C about B's messages to C
- Node A may receive conflicting information about B from C and about C from B (the same for C!)
- It is impossible for A and C to decide which information to base their decision on!

Proof Sketch



- Assume that both A and C have input 0. If they decided 1, they could violate the validity condition \rightarrow A and C must decide 0 independent of what B says
- Similary, A and C must decide 1 if their inputs are 1
- We see that the processes must base their decision on the majority vote
- If A's input is 0 and B tells A that its input is $0 \rightarrow A$ decides 0
- If C's input is 1 and B tells C that its input is $1 \rightarrow C$ decides $\frac{1}{R_1}$

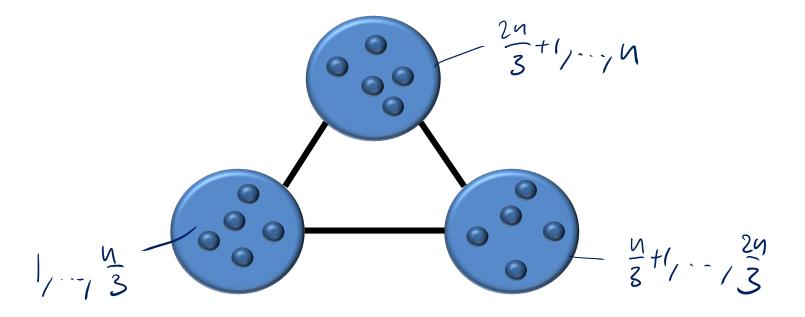




Theory of Distributed Systems

The General Case

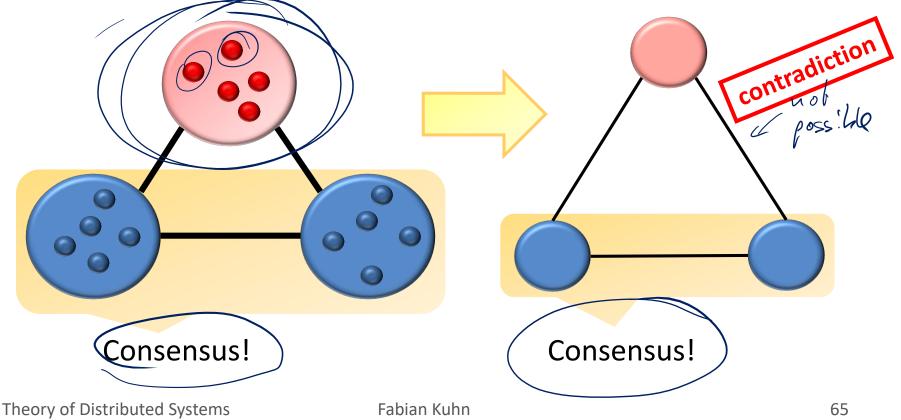
- FREIBURG
- Assume for contradiction that there is an f-resilient algorithm A for n nodes, where $f \ge n/3$
- We use this algorithm to solve consensus for 3 nodes where one node is Byzantine!
- For simplicity assume that *n* is divisible by 3
- We let each of the three processes simulate *n*/3 processes



The General Case



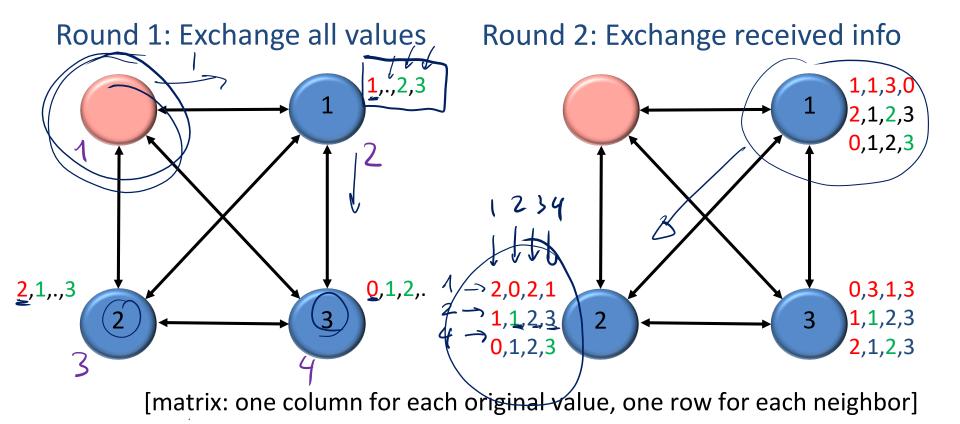
- One of the 3 nodes is Byzantine \implies its n/3 simulated nodes may all behave like Byzantine nodes
- Since algorithm A tolerates n/3 Byzantine failures, it can still reach consensus
 - \Rightarrow We solved the consensus problem for three processes!



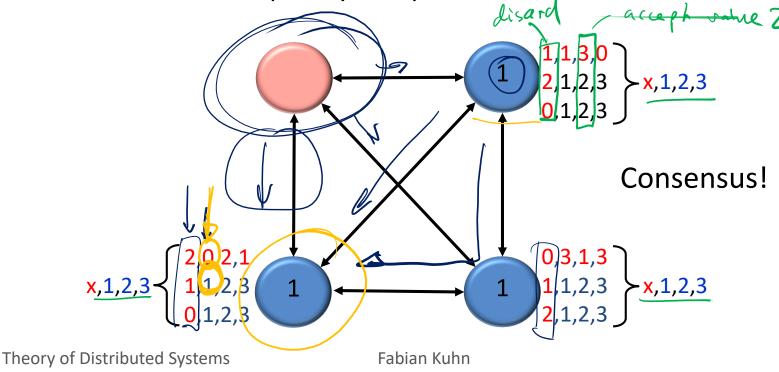
Cons. #6: Simple Byzantine Agreement Alg.



- Can the nodes reach consensus if n > 3f?
- A simpler question: What if n = 4 and f = 1?
- The answer is yes. It takes two rounds:



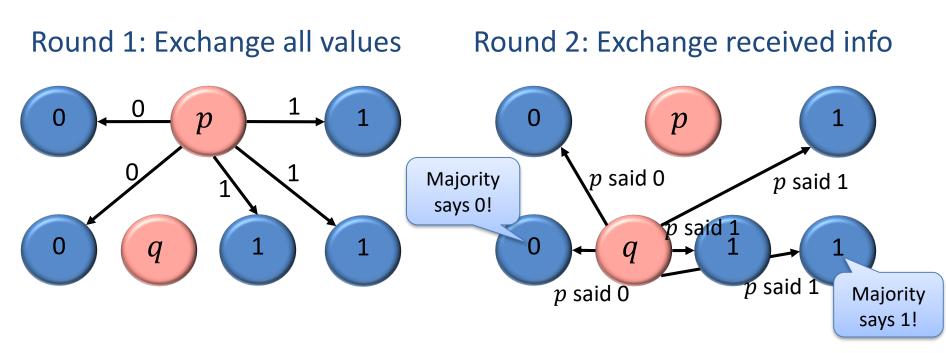
- After round 2, each node has received 12 values, 3 for each of the 4 input values (columns). If at least 2 of the 3 values of a column are equal, this value is accepted, otherwise it is discarded.
 - Values of honest nodes are accepted
 - The value of the Byzantine node is accepted iff it sends the same value to at least two nodes in the first round.
- Decide on most frequently accepted value, break ties consistently!



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- Does the algorithm still work in general for any f and n > 3f?
- The answer is no. Try f = 2 and n = 7:



- The problem is that q can say different things about what p sent to q
 - It can also obviously not work because of the f + 1 round lower bound.
 - What is the solution to this problem?



- The solution is simple: Again exchange all information!
- This way, the nodes can learn that $q\ {\rm gave}$ inconsistent information about p
- Hence, q can be excluded, and also p if it also gave inconsistent information (about q).
- If f = 2 and n > 6, consensus can be reached in 3 rounds!
- In fact, the following "algorithm" solves the problem for any f and any n > 3f:

Exchange all information for f + 1 rounds Ignore all nodes that provided inconsistent information Let all nodes decide based on the same input



The proposed algorithm has several advantages:

- + It works for any f and n > 3f, which is optimal
- + It only takes f + 1 rounds. This is even optimal for crash failures!
- + It works for any input and not just binary input

However, it has some considerable disadvantages:

- "Ignoring all nodes that provided inconsistent information"
 is not easy to formalize
- The size of the messages increases exponentially!
 This is a severe problem. It is therefore worth studying whether it is possible to solve the problem with small(er) messages

Consensus #7: The Queen Algorithm

- The Queen algorithm is a simple Byzantine agreement algorithm that uses small messages
- The Queen algorithm solves consensus with n nodes and f failures where f < n/4 in f + 1 phases

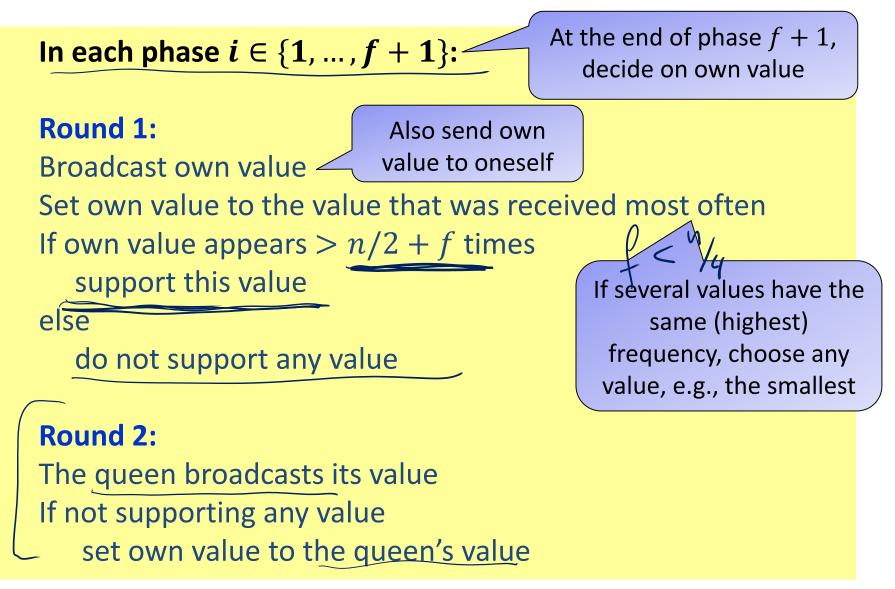
A phase consists of 2 rounds

Idea:

- There is a different (a priori known) queen in each phase
- Since there are f + 1 phases, in one phase the queen is not Byzantine
- Make sure that in this round all nodes choose the same value and that in future rounds the nodes do not change their values anymore

The Queen Algorithm





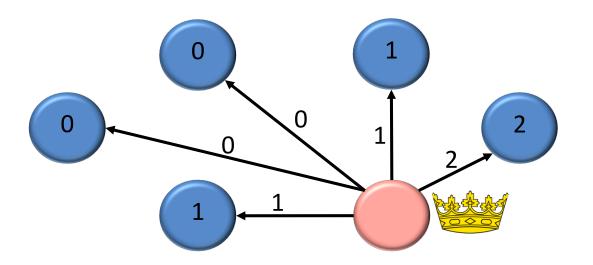


Example: n = 6, f = 1Phase 1, round 1 (all broadcast): No node supports a value All received values 0,0,1,1,1,2 <mark>0,0,0,</mark>1,1,2 1 0 0,0,0,1,1,2 0,0,0,1,1,2 2 0 Majority value 0,0,1,1,1,2



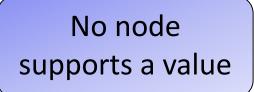
- Example: n = 6, f = 1
- Phase 1, round 2 (queen broadcasts):

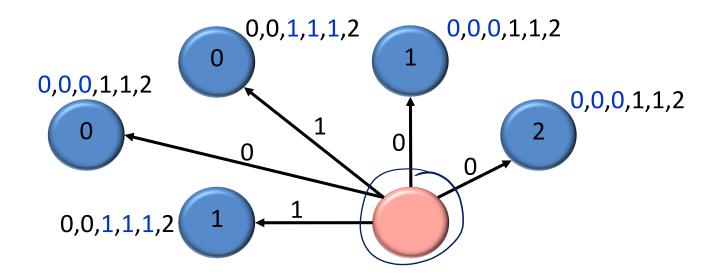
All nodes choose the queen's value





- Example: n = 6, f = 1
- Phase 2, round 1 (all broadcast):

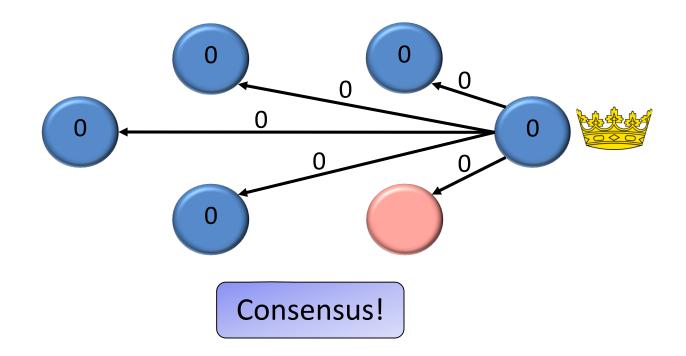






- Example: n = 6, f = 1
- Phase 2, round 2 (queen broadcasts):

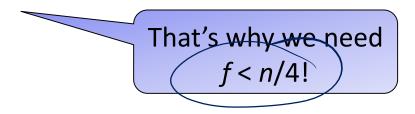
All nodes choose the queen's value



The Queen Algorithm: Analysis



- After the phase where the queen is correct, all correct nodes have the same value
 - If all nodes change their values to the queen's value, obviously all values are the same
 - If some node does not change its value to the queen's value, it received a value > n/2 + f times \rightarrow All other correct nodes (including the queen) received this value > n/2 times and thus all correct nodes share this value
- In all future phases, no node changes its value
 - In the first round of such a phase, nodes receive their own value from at least n –
 f > n/2 nodes and thus do not change it
 - The nodes do not accept the queen's proposal if it differs from their own value in the second round because the nodes received their own value at least n f > n/2 + f times. Thus, all correct nodes support the same value



The Queen Algorithm: Summary



The Queen algorithm has several advantages:

- + The messages are small: nodes only exchange their current values
- + It works for any input and not just binary input

However, it also has some disadvantages:

- The algorithm requires f + 1 phases consisting of 2 rounds each ... this is twice as much as an optimal algorithm
- It only works with f < n/4 Byzantine nodes!
- Is it possible to get an algorithm that works with f < n/3Byzantine nodes and uses small messages?

Consensus #8: The King Algorithm



- The King algorithm is an algorithm that tolerates f < n/3 Byzantine failures and uses small messages
- The King algorithm also takes f + 1 phases

A phase now consists of 3 rounds

- Idea:
- The basic idea is the same as in the Queen algorithm
- There is a different (a priori known) king in each phase
- Since there are f + 1 phases, in one phase the king is not Byzantine
- The difference to the Queen algorithm is that the correct nodes only propose a value if many nodes have this value, and a value is only accepted if many nodes propose this value

The King Algorithm



In each phase $i \in \{1 ... f + 1\}$: -At the end of phase f + 1, decide on own value Round 1: Broadcast own value -Also send own value to oneself Round 2: If some value x appears $\geq n - f$ times Broadcast "Propose x" If some proposal received > f times Set own value to this proposal Round 3: The king broadcasts its value If own value received < n - f proposals Set own value to the king's value

The King Algorithm: Summary



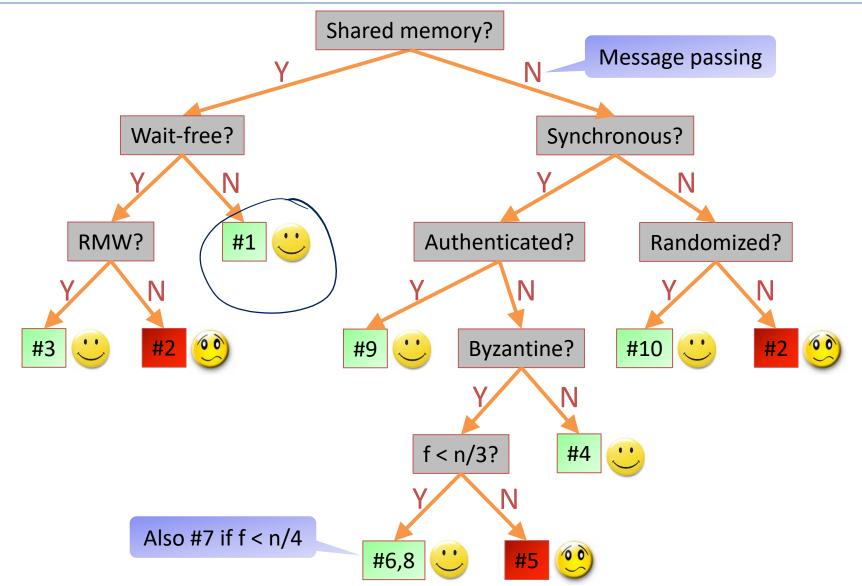
The King algorithm has several advantages:

- + It works for any f and n > 3f, which is optimal
- + The messages are small: processes only exchange their current values
- + It works for any input and not just binary input

However, it also has a disadvantage:

- The algorithm requires f + 1 phases consisting of 3 rounds each This is three times as much as an optimal algorithm

Consensus: Decision Tree





Credits



- The impossibility result (#2) is from Fischer, Lynch, Paterson, 1985
- The hierarchy (#3) is from Herlihy, 1991.
- The synchronous studies (#4) are from Dolev and Strong, 1983, and others.
- The Byzantine agreement problem (#5) and the simple algorithm (#6) are from Lamport, Shostak, Pease, 1980ff., and others
- The Queen algorithm (#7) and the King algorithm (#8) are from Berman, Garay, and Perry, 1989.
- The algorithm using authentication (#9) is due to Dolev and Strong, 1982.
- The first randomized algorithm (#10) is from Ben-Or, 1983.
- The concept of a shared coin was introduced by Bracha, 1984.
- Byzantine Agreement with fewer than n^2 messages is from King and Saia 2011.
- Byzantine Agreement in an asynchronous setting is from King and Saia 2013.