



# Chapter 1

# Divide and Conquer

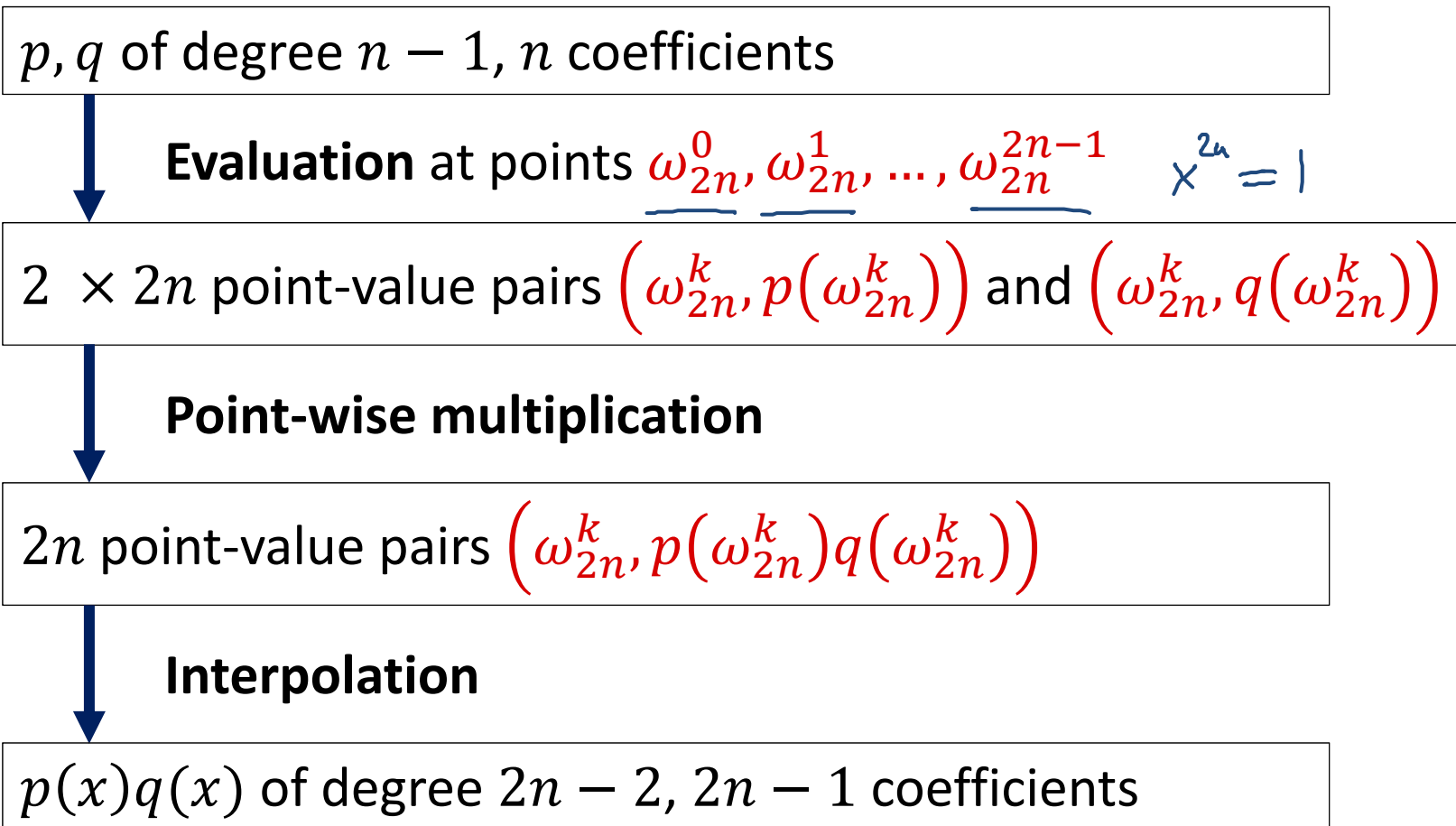
## Part 2: Polynomial Multiplication

Algorithm Theory  
WS 2013/14

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# Faster Polynomial Multiplication?

Idea to compute  $p(x) \cdot q(x)$  (for polynomials of degree  $< n$ ):



# Point-Value Representation of $p, q$

- Select points  $x_0, x_1, \dots, x_{N-1}$  to evaluate  $p$  and  $q$  in a clever way

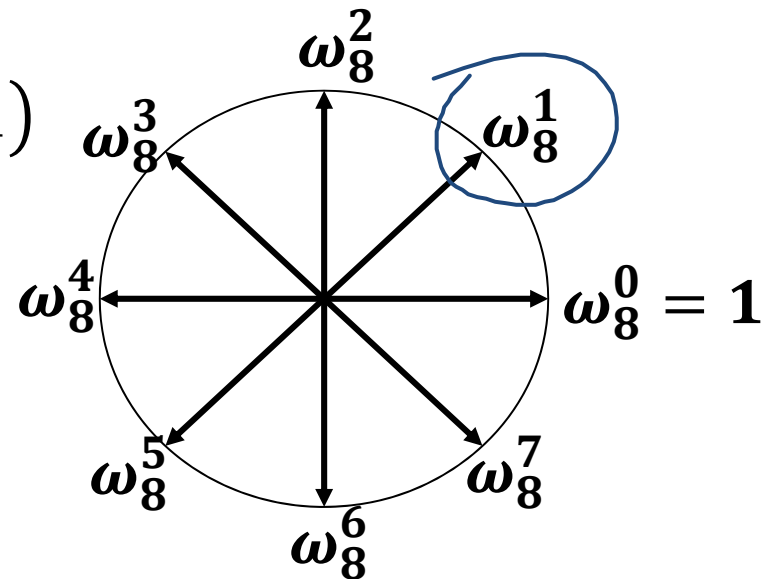
Consider the  $N$  powers of the principle  $N$ th root of unity:

**Principle root of unity:**  $\omega_N = e^{2\pi i/N}$

$$(i = \sqrt{-1}, e^{2\pi i} = 1)$$

**Powers of  $\omega_n$  (roots of unity):**

$$1 = \omega_N^0, \omega_N^1, \dots, \omega_N^{N-1}$$



Note:  $\omega_N^k = e^{2\pi i k/N} = \cos \frac{2\pi k}{N} + i \cdot \sin \frac{2\pi k}{N}$

# Discrete Fourier Transform

- The values  $p(\omega_N^i)$  for  $i = 0, \dots, N - 1$  uniquely define a polynomial  $p$  of degree  $< N$ .

## Discrete Fourier Transform (DFT):

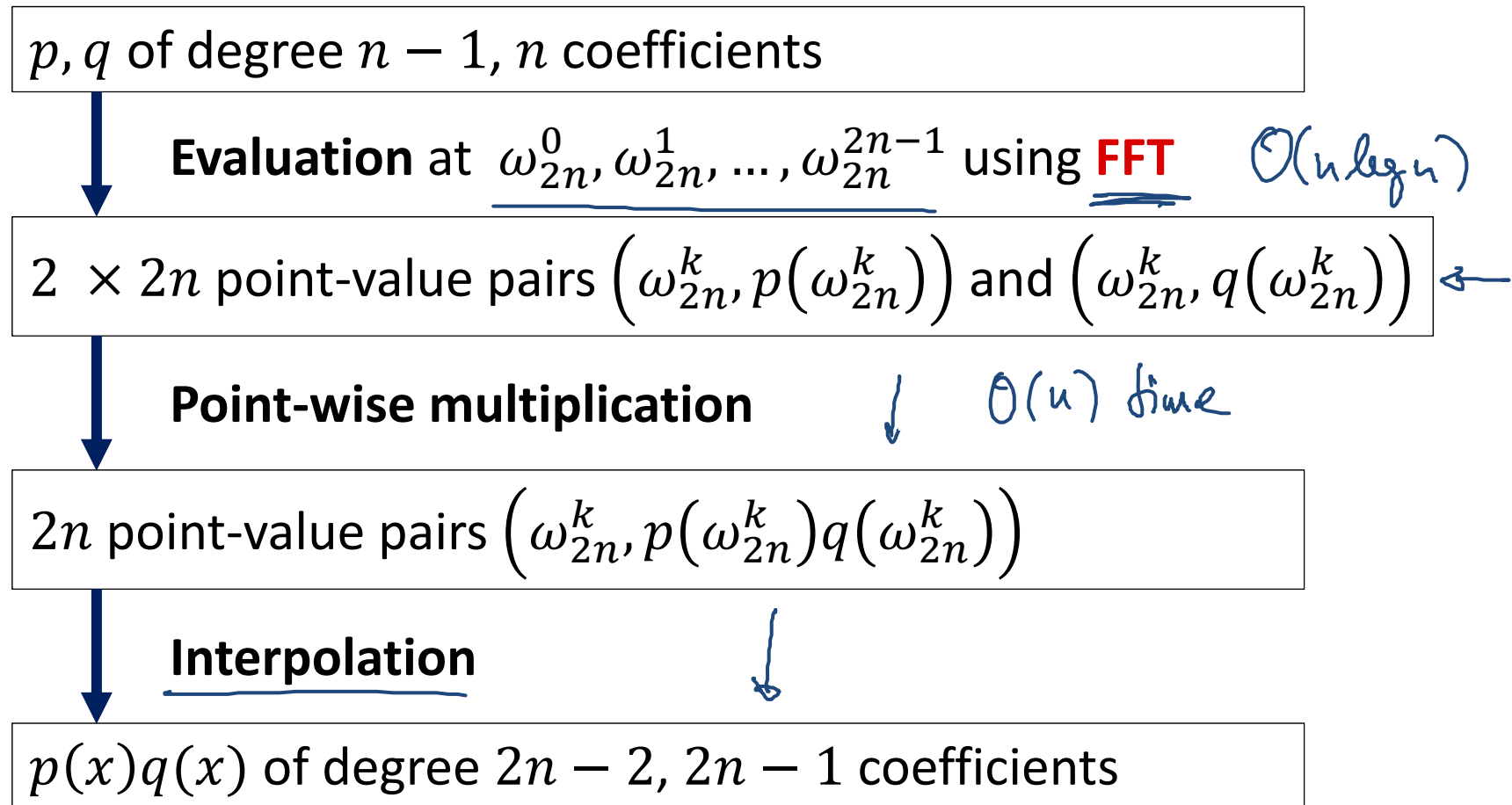
- Assume  $a = (a_0, \dots, a_{N-1})$  is the coefficient vector of poly.  $p$   
$$(p(x) = a_{N-1}x^{N-1} + \dots + a_1x + a_0)$$

$$\text{DFT}_N(a) := (p(\omega_N^0), p(\omega_N^1), \dots, p(\omega_N^{N-1}))$$

FFT : (fast) divide & conq. alg. to compute the DFT  $O(n \log n)$

# Faster Polynomial Multiplication?

Idea to compute  $p(x) \cdot q(x)$  (for polynomials of degree  $< n$ ):



# Interpolation

Convert point-value representation into coefficient representation

**Input:**  $(x_0, y_0), \dots, (x_{n-1}, y_{n-1})$  with  $x_i \neq x_j$  for  $i \neq j$

**Output:**

$$y_i = p(x_i) \quad p = \underline{a_0} + \underline{a_1}x + \dots + \underline{a_{n-1}}x^{n-1}$$

Degree- $(n - 1)$  polynomial with coefficients  $a_0, \dots, a_{n-1}$  such that

$$\begin{aligned} p(x_0) &= \underline{a_0} + \underline{a_1}x_0 + \underline{a_2}x_0^2 + \dots + a_{n-1}x_0^{n-1} = y_0 \leftarrow \\ p(x_1) &= \underline{a_0} + \underline{a_1}x_1 + \underline{a_2}x_1^2 + \dots + a_{n-1}x_1^{n-1} = y_1 \leftarrow \\ &\vdots \\ p(x_{n-1}) &= a_0 + a_1x_{n-1} + a_2x_{n-1}^2 + \dots + a_{n-1}x_{n-1}^{n-1} = y_{n-1} \end{aligned}$$

→ linear system of equations for  $a_0, \dots, a_{n-1}$

# Interpolation



## Matrix Notation:

$$\begin{pmatrix} 1 & x_0 & \dots & x_0^{n-1} \\ 1 & x_1 & \dots & x_1^{n-1} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_{n-1} & \dots & x_{n-1}^{n-1} \end{pmatrix} \cdot \begin{pmatrix} a_0 \\ a_1 \\ \vdots \\ a_{n-1} \end{pmatrix} = \begin{pmatrix} y_0 \\ y_1 \\ \vdots \\ y_{n-1} \end{pmatrix}$$

- System of equations solvable iff  $x_i \neq x_j$  for all  $i \neq j$

Special Case  $x_i = \omega_n^i$ :

$W_{ij} = \omega_n^{ij}$

$$\begin{pmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & \omega_n & \omega_n^2 & \dots & \omega_n^{n-1} \\ 1 & \omega_n^2 & \omega_n^4 & \dots & \omega_n^{2(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega_n^{n-1} & \omega_n^{2(n-1)} & \dots & \omega_n^{(n-1)(n-1)} \end{pmatrix} \cdot \begin{pmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_{n-1} \end{pmatrix} = \begin{pmatrix} y_0 \\ y_1 \\ y_2 \\ \vdots \\ y_{n-1} \end{pmatrix}$$

# Interpolation

- Linear system:

$$\begin{aligned}
 & \downarrow \\
 & \underline{W \cdot \mathbf{a} = \mathbf{y}} \quad \Rightarrow \quad \underline{\mathbf{a} = W^{-1} \cdot \mathbf{y}} \\
 & \underline{W_{i,j} = \omega_n^{ij}}, \quad \mathbf{a} = \begin{pmatrix} a_0 \\ \vdots \\ a_{n-1} \end{pmatrix}, \quad \mathbf{y} = \begin{pmatrix} y_0 \\ \vdots \\ y_{n-1} \end{pmatrix}
 \end{aligned}$$

Claim:

$$\underline{W_{ij}^{-1} = \frac{\omega_n^{-ij}}{n}}$$

$W_i$

Proof: Need to show that  $W^{-1}W = \underline{I_n}$



# Inverse DFT

- $$W^{-1} \Rightarrow \begin{pmatrix} 1 & \omega_n^{-k} & \dots & \omega_n^{-(n-1)k} \\ n & n & \dots & n \\ \vdots & \vdots & \ddots & \vdots \\ \dots & \dots & \dots & \dots \end{pmatrix} \begin{pmatrix} y_0 \\ \vdots \\ y_{n-1} \end{pmatrix} = \begin{pmatrix} a_0 \\ \vdots \\ a_{n-1} \end{pmatrix}$$

- We get  $\mathbf{a}$  =  $W^{-1}$  ·  $\mathbf{y}$  and therefore

$$\begin{aligned} \underline{a_k} &= \underline{\begin{pmatrix} 1 & \omega_n^{-k} & \dots & \omega_n^{-(n-1)k} \\ n & n & \dots & n \end{pmatrix}} \cdot \underline{\begin{pmatrix} y_0 \\ y_1 \\ \vdots \\ y_{n-1} \end{pmatrix}} \\ &= \underline{\frac{1}{n}} \cdot \sum_{j=0}^{n-1} \underline{\omega_n^{-kj}} \cdot \underline{y_j} \end{aligned}$$

# DFT and Inverse DFT

## Inverse DFT:

$$a_k = \frac{1}{n} \cdot \sum_{j=0}^{n-1} \omega_n^{-kj} \cdot y_j$$

Handwritten annotations: A blue arrow points from the exponent  $-kj$  to the term  $\omega_n^{-k}$  in a circled expression  $(\omega_n^{-k})^j$  above the sum. Another blue arrow points from the term  $y_j$  to the right.

- Define polynomial  $q(x) = y_0 + y_1x + \dots + y_{n-1}x^{n-1}$ :

$$a_k = \frac{1}{n} \cdot q(\omega_n^{-k})$$

Handwritten annotations: The fraction  $\frac{1}{n}$  is circled in red. A blue arrow points from the exponent  $-k$  to the term  $\omega_n^{-k}$  in the polynomial argument.

## DFT:

- Polynomial  $p(x) = a_0 + a_1x + \dots + a_{n-1}x^{n-1}$ :

$$y_k = p(\omega_n^k)$$

Handwritten annotations: The equation is underlined with a blue line.

# DFT and Inverse DFT

$$q(x) = y_0 + y_1x + \dots + y_{n-1}x^{n-1},$$

$$a_k = \frac{1}{n} \cdot q(\omega_n^{-k}):$$

$$\omega_n^{k+n} = \omega_n^k$$

- Therefore:

$$\underline{(a_0, a_1, \dots, a_{n-1})}$$

$$\rightarrow = \frac{1}{n} \cdot \left( q(\omega_n^{-0}), q(\omega_n^{-1}), q(\omega_n^{-2}), \dots, q(\omega_n^{-(n-1)}) \right)$$

$$= \frac{1}{n} \cdot \left( q(\omega_n^0), q(\omega_n^{n-1}), q(\omega_n^{n-2}), \dots, q(\omega_n^1) \right)$$

- Recall:

$$\rightarrow \underline{\text{DFT}_n(\mathbf{y})} = \underline{\left( q(\omega_n^0), q(\omega_n^1), q(\omega_n^2), \dots, q(\omega_n^{n-1}) \right)}$$

$$= \underline{n \cdot (a_0, a_{n-1}, a_{n-2}, \dots, a_2, a_1)}$$

# DFT and Inverse DFT

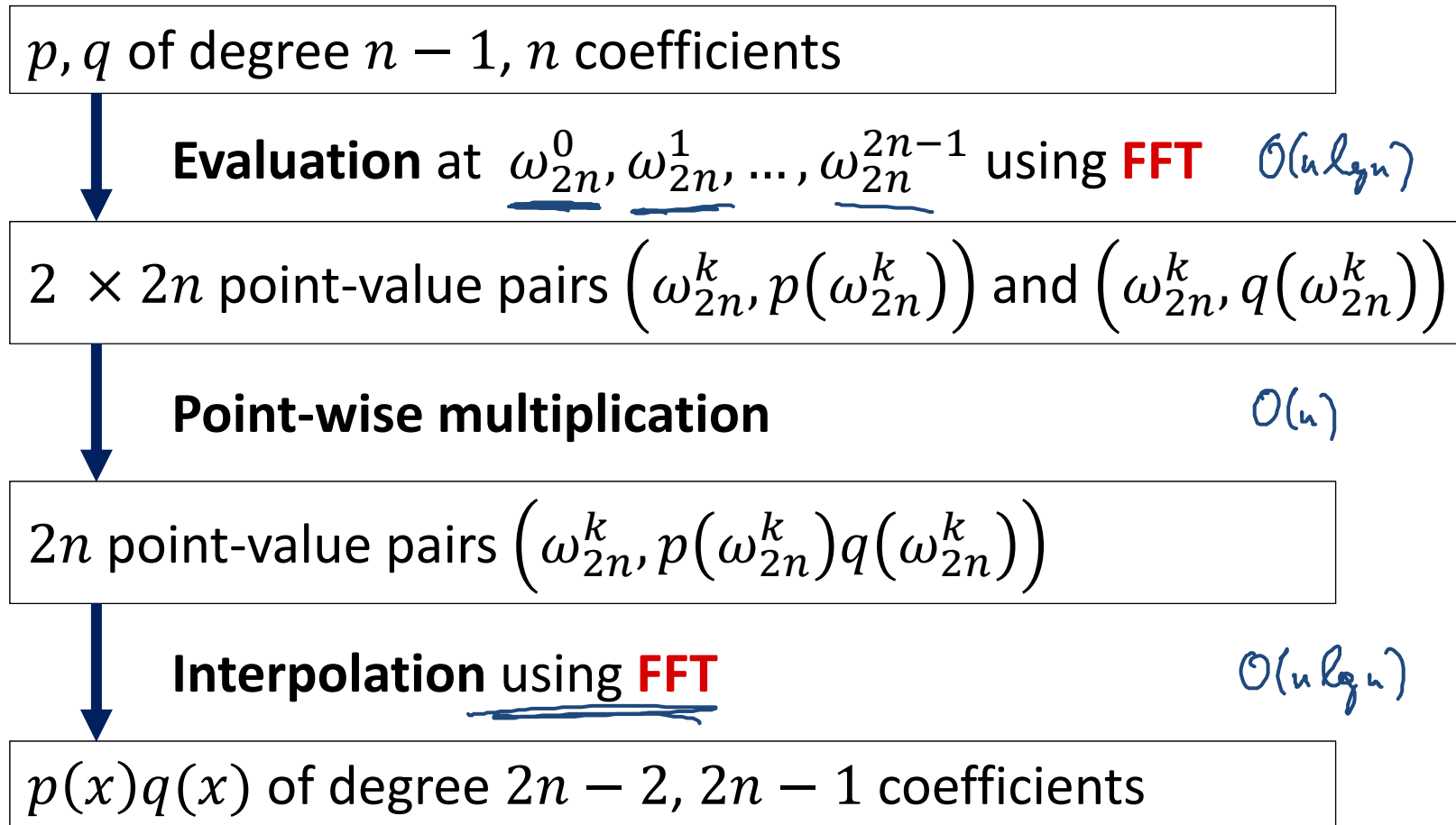
- We have  $\text{DFT}_n(\mathbf{y}) = n \cdot (a_0, a_{n-1}, a_{n-2}, \dots, a_2, a_1)$ :

$$a_i = \begin{cases} (\text{DFT}_n(\mathbf{y}))_0 \cdot \frac{1}{n} & \text{if } i = 0 \\ (\text{DFT}_n(\mathbf{y}))_{n-i} \cdot \frac{1}{n} & \text{if } i \neq 0 \end{cases}$$

- DFT and inverse DFT can both be computed using FFT algorithm in  $O(n \log n)$  time.
- 2 polynomials of degr.  $< n$  can be multiplied in time  $O(n \log n)$ .

# Faster Polynomial Multiplication?

Idea to compute  $p(x) \cdot q(x)$  (for polynomials of degree  $< n$ ):



$O(n \log n \log \log n)$

# Convolution

- More generally, the polynomial multiplication algorithm computes the convolution of two vectors:

$$\mathbf{a} = (a_0, a_1, \dots, a_{\underline{m-1}}) \leftarrow$$

$$\mathbf{b} = (b_0, b_1, \dots, b_{\underline{n-1}}) \leftarrow$$

$$\mathbf{a} * \mathbf{b} = (\underline{c_0}, c_1, \dots, c_{\underline{m+n-2}}), \leftarrow$$

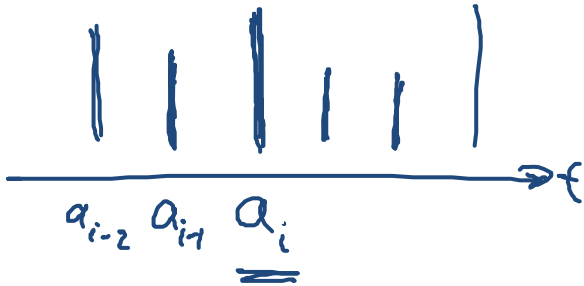
$$\text{where } \underline{c_k} = \sum_{\substack{(i,j): i+j=k \\ i < m, j < n}} a_i b_j$$

- $c_k$  is exactly the coefficient of  $x^k$  in the product polynomial of the polynomials defined by the coefficient vectors  $\mathbf{a}$  and  $\mathbf{b}$

# More Applications of Convolutions

## Signal Processing Example:

- Assume  $\mathbf{a} = (a_0, \dots, a_{n-1})$  represents a sequence of measurements over time
- Measurements might be noise and have to be smoothed out
- Replace  $a_i$  by weighted average of nearby last  $m$  and next  $m$  measurements (e.g., Gaussian smoothing):

$$\rightarrow a'_i = \frac{1}{Z} \cdot \sum_{j=i-m}^{i+m} a_j e^{-(i-j)^2}$$


- New vector  $\mathbf{a}'$  is the convolution of  $\mathbf{a}$  and the weight vector  $\frac{1}{Z} \cdot (e^{-m^2}, e^{-(m-1)^2}, \dots, e^{-1}, 1, e^{-1}, \dots, e^{-(m-1)^2}, e^{-m^2})$
- Might need to take care of boundary points...

# More Applications of Convolutions

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## Combining Histograms:

- Vectors  $\mathbf{a}$  and  $\mathbf{b}$  represent two histograms
- E.g., annual income of all men & annual income of all women
- Goal: Get new histogram  $\mathbf{c}$  representing combined income of all possible pairs of men and women:

$$\underline{\mathbf{c} = \mathbf{a} * \mathbf{b}}$$

**Also, the DFT (and thus the FFT alg.) has many other applications!**

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