



# Chapter 4 Data Structures

Algorithm Theory WS 2014/15

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# Priority Queue / Heap



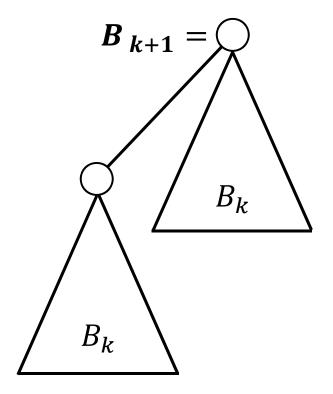
- Stores (key,data) pairs (like dictionary)
- But, different set of operations:
- Initialize-Heap: creates new empty heap
- **Is-Empty**: returns true if heap is empty
- **Insert**(*key,data*): inserts (*key,data*)-pair, returns pointer to entry
- **Get-Min**: returns (*key,data*)-pair with minimum *key*
- **Delete-Min**: deletes minimum (*key,data*)-pair
- **Decrease-Key**(*entry*, *newkey*): decreases *key* of *entry* to *newkey* 
  - entry: pointer to entry in data structure
- Merge: merges two heaps into one

### **Definition: Binomial Tree**



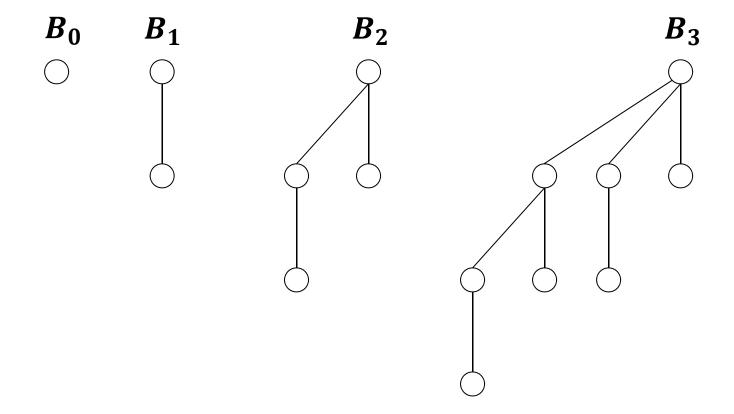
### Binomial tree $B_k$ of order $k \ (n \ge 0)$ :

$$B_0 = \bigcirc$$



### **Binomial Trees**





# **Properties**



1. Tree  $B_k$  has  $2^k$  nodes

2. Height of tree  $B_k$  is k

3. Root degree of  $B_k$  is k

4. In  $B_k$ , there are exactly  $\binom{k}{i}$  nodes at depth i

### Binomial Heap



Keys are stored in nodes of binomial trees of different order

 $\boldsymbol{n}$  nodes: there is a binomial tree  $B_i$  of order i iff bit i of base-2 representation of n is 1.

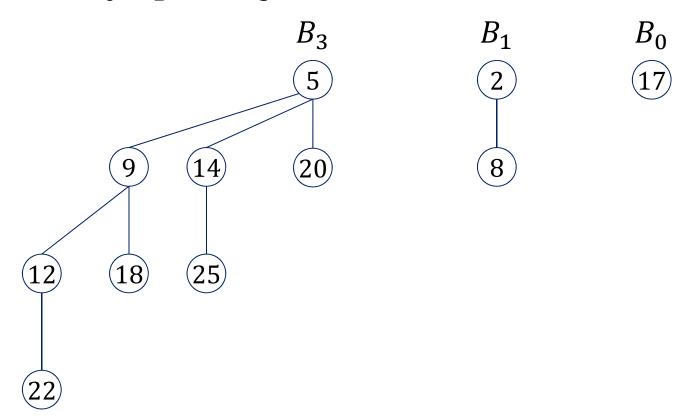
Min-Heap Property:

Key of node  $v \le \text{keys}$  of all nodes in sub-tree of v

# Example



- 11 keys: {2, 5, 8, 9, 12, 14, 17, 18, 20, 22, 25}
- Binary representation of n:  $(11)_2 = 1011$  $\rightarrow$  trees  $B_0$ ,  $B_1$ , and  $B_3$  present



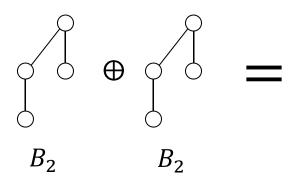
# **Link Operation**

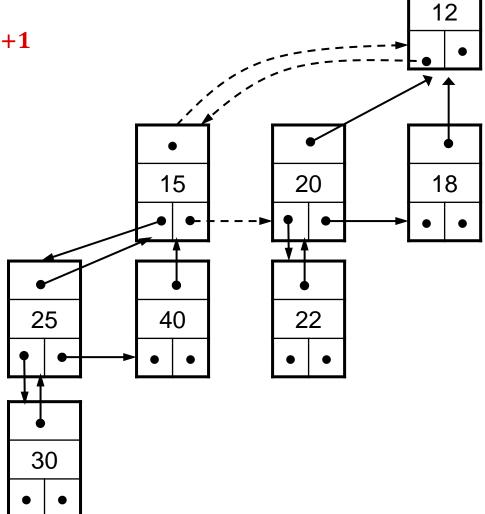


• Unite two binomial trees of the same order to one tree:

 $B_n \oplus B_n \Rightarrow B_{n+1}$ 

• Time: **0**(1)



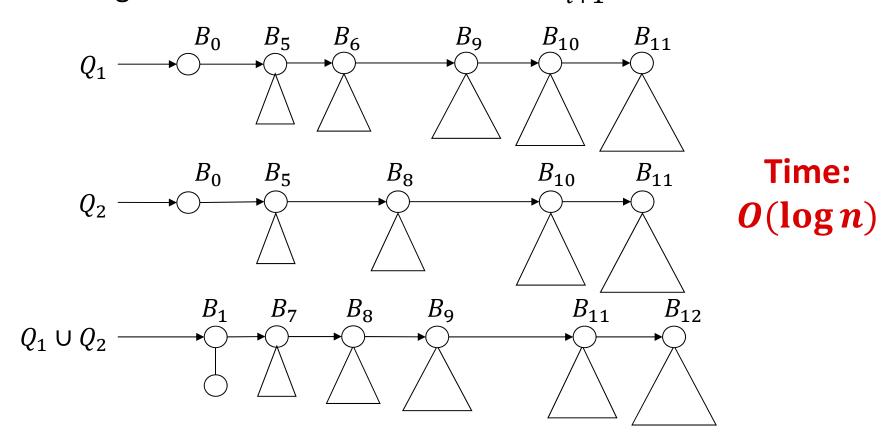


### Merge Operation



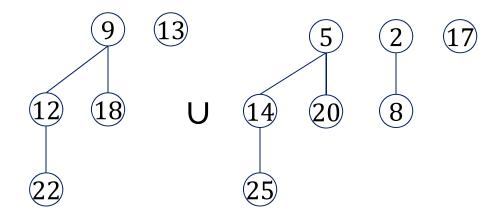
Merging two binomial heaps:

• For  $i = 0, 1, ..., \log n$ : If there are 2 or 3 binomial trees  $B_i$ : apply link operation to merge 2 trees into one binomial tree  $B_{i+1}$ 



# Example





### **Operations**



Initialize: create empty list of trees

**Get minimum** of queue: time O(1) (if we maintain a pointer)

### **Decrease-key** at node v:

- Set key of node v to new key
- Swap with parent until min-heap property is restored
- Time:  $O(\log n)$

### **Insert** key x into queue Q:

- 1. Create queue Q' of size 1 containing only x
- 2. Merge Q and Q'
- Time for insert:  $O(\log n)$

# **Operations**



### **Delete-Min Operation:**

- Smallest key is at the root of some tree
- Removing the root of a binomial tree:

# **Operations**



### **Delete-Min Operation:**

1. Find tree  $B_i$  with minimum root r

2. Remove  $B_i$  from queue  $Q \rightarrow$  queue Q'

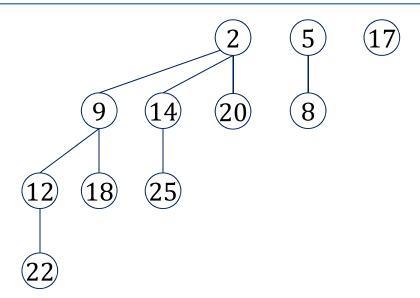
3. Children of r form new queue Q''

4. Merge queues Q' and Q''

• Overall time:  $O(\log n)$ 

# Delete-Min Example





# **Complexities Binomial Heap**



• Initialize-Heap: O(1)

• Is-Empty: O(1)

• Insert:  $O(\log n)$ 

• Get-Min: **0**(1)

• Delete-Min:  $O(\log n)$ 

• Decrease-Key:  $O(\log n)$ 

• Merge (heaps of size m and  $n, m \le n$ ):  $O(\log n)$ 

### Can We Do Better?



- Binomial heap: insert, delete-min, and decrease-key cost  $O(\log n)$
- One of the operations insert or delete-min must cost  $\Omega(\log n)$ :
  - Heap-Sort: Insert n elements into heap, then take out the minimum n times
  - (Comparison-based) sorting costs at least  $\Omega(n \log n)$ .
- But maybe we can improve decrease-key and one of the other two operations?
- Structure of binomial heap is not flexible:
  - Simplifies analysis, allows to get strong worst-case bounds
  - But, operations almost inherently need at least logarithmic time

# Fibonacci Heaps



Lacy-merge variant of binomial heaps:

Do not merge trees as long as possible...

#### **Structure:**

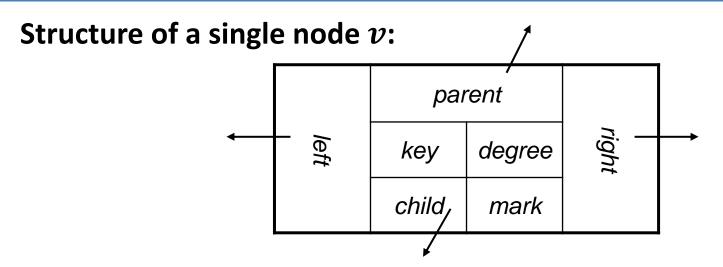
A Fibonacci heap H consists of a collection of trees satisfying the min-heap property.

#### **Variables:**

- *H.min*: root of the tree containing the (a) minimum key
- H.rootlist: circular, doubly linked, unordered list containing the roots of all trees
- *H. size*: number of nodes currently in *H*

### Trees in Fibonacci Heaps





- v.child: points to circular, doubly linked and unordered list of the children of v
- v.left, v.right: pointers to siblings (in doubly linked list)
- v.mark: will be used later...

### Advantages of circular, doubly linked lists:

- Deleting an element takes constant time
- Concatenating two lists takes constant time

# Example



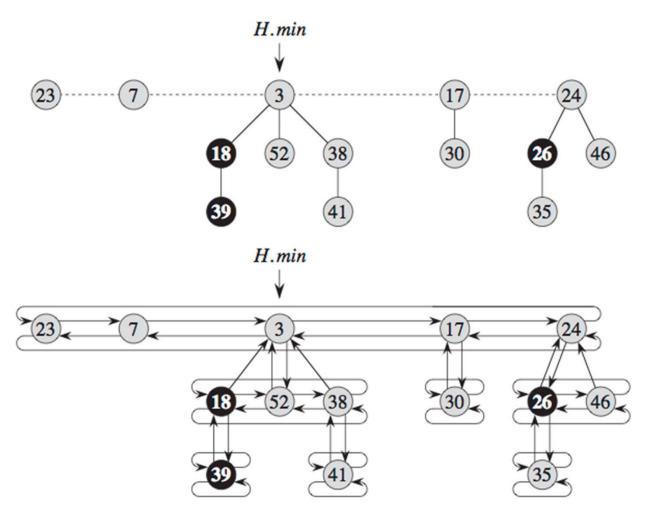


Figure: Cormen et al., Introduction to Algorithms

# Simple (Lazy) Operations



### Initialize-Heap *H*:

• H.rootlist := H.min := null

### Merge heaps H and H':

- concatenate root lists
- update *H.min*

#### **Insert** element *e* into *H*:

- create new one-node tree containing  $e \rightarrow H'$
- merge heaps H and H'

#### **Get minimum** element of *H*:

• return *H.min* 

# Operation Delete-Min



Delete the node with minimum key from *H* and return its element:

```
    m := H.min;
    if H.size > 0 then
    remove H.min from H.rootlist;
    add H.min.child (list) to H.rootlist
    H.Consolidate();
    // Repeatedly merge nodes with equal degree in the root list // until degrees of nodes in the root list are distinct. // Determine the element with minimum key
```

6. **return** *m* 

# Rank and Maximum Degree



### Ranks of nodes, trees, heap:

#### Node *v*:

• rank(v): degree of v

#### Tree T:

• rank(T): rank (degree) of root node of T

### Heap H:

• rank(H): maximum degree of any node in H

**Assumption** (n: number of nodes in H):

$$rank(H) \leq D(n)$$

- for a known function D(n)

### Merging Two Trees

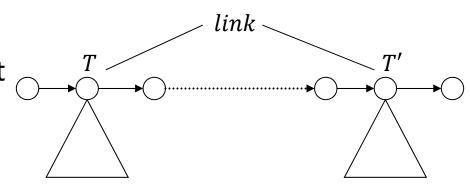


**Given:** Heap-ordered trees T, T' with rank(T) = rank(T')

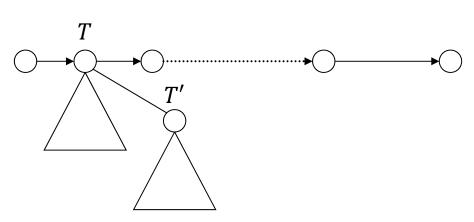
• Assume: min-key of T < min-key of T'

### Operation link(T, T'):

• Removes tree T' from root list and adds T' to child list of T



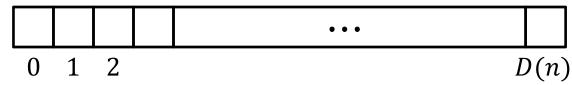
- rank(T) := rank(T) + 1
- T'. mark := false



### **Consolidation of Root List**



Array A pointing to find roots with the same rank:

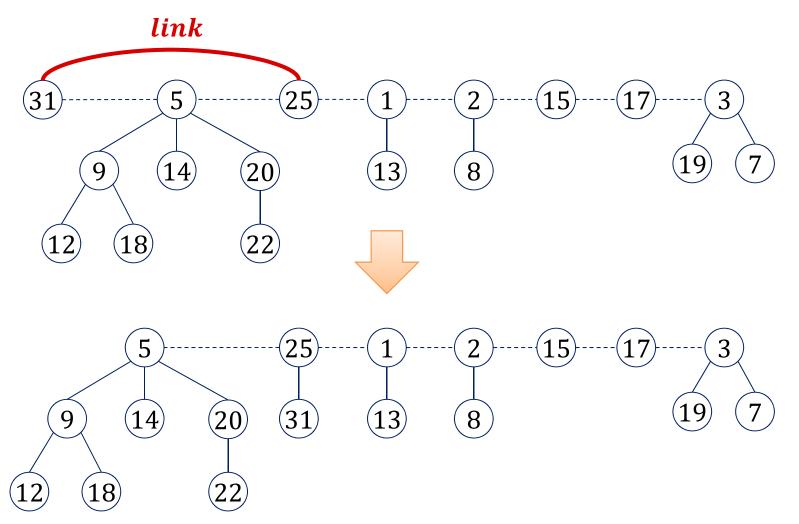


#### **Consolidate:**

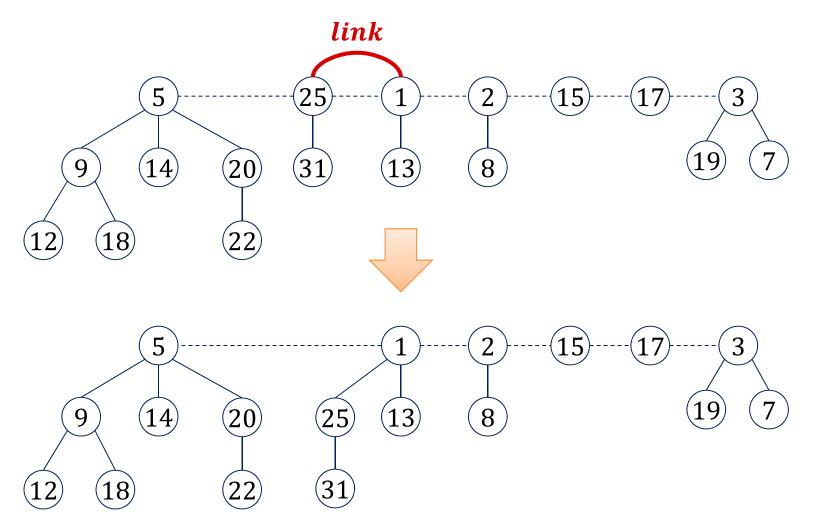
- 1. for i := 0 to D(n) do A[i] := null;
- 2. while  $H.rootlist \neq null do$

- Time: O(|H.rootlist|+D(n))
- 3. T := "delete and return first element of H.rootlist"
- 4. while  $A[rank(T)] \neq \text{null do}$
- 5.  $T' \coloneqq A[rank(T)];$
- 6. A[rank(T)] := null;
- 7. T := link(T, T')
- 8. A[rank(T)] := T
- 9. Create new *H*. rootlist and *H*. min

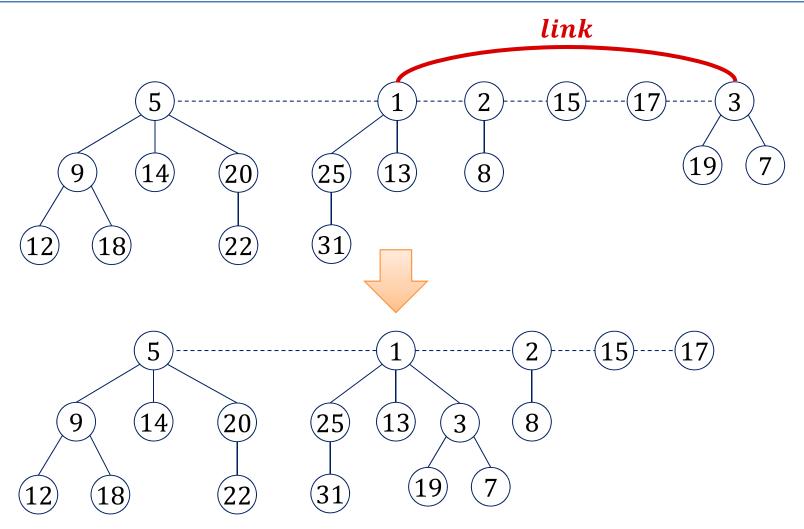




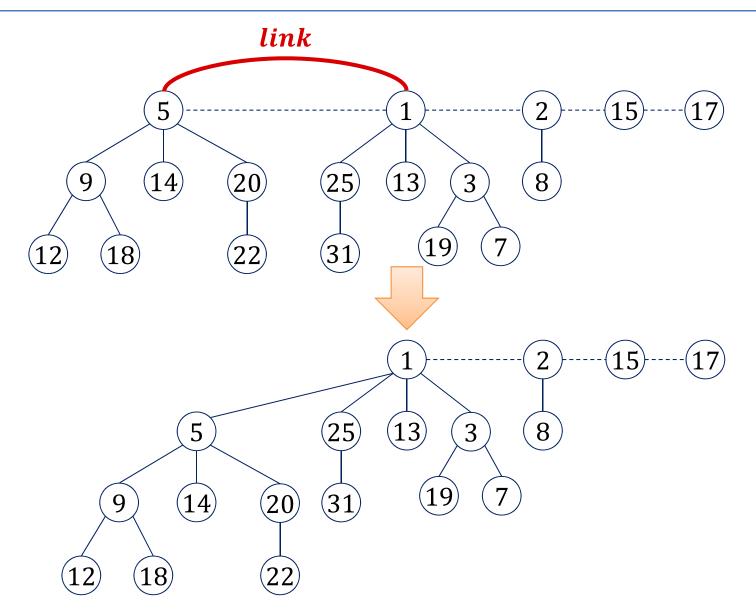




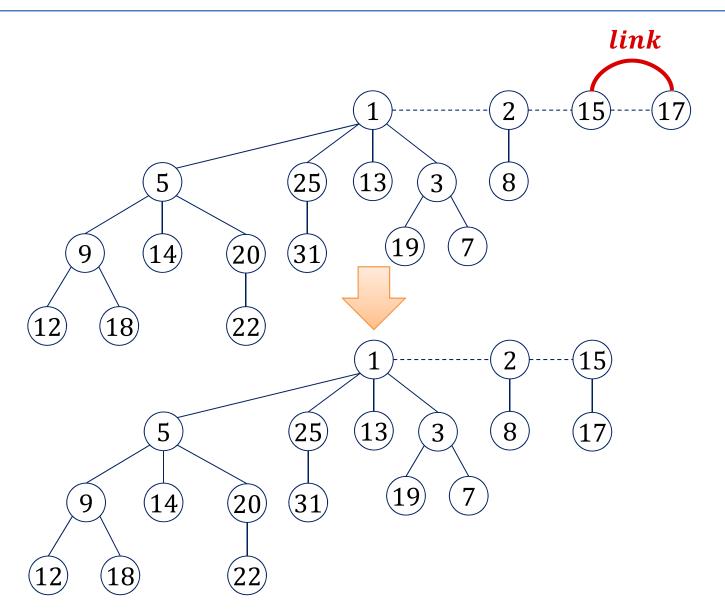




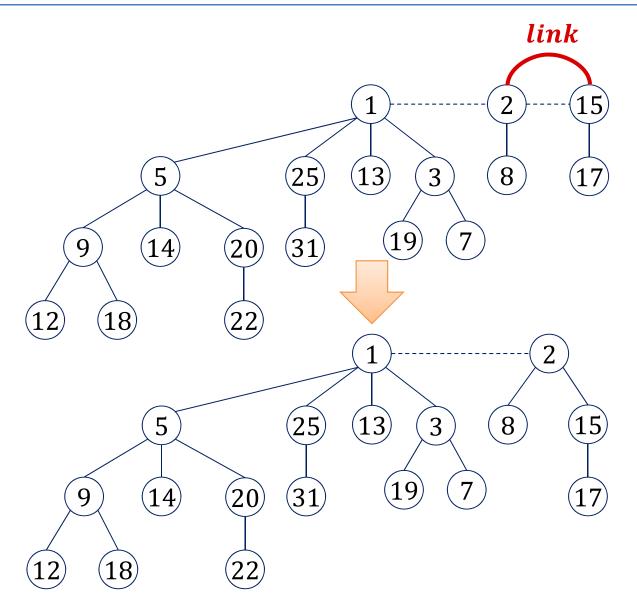












### **Operation Decrease-Key**



**Decrease-Key**(v, x): (decrease key of node v to new value x)

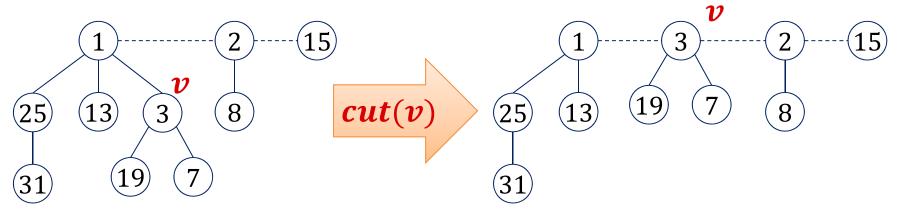
```
    if x ≥ v.key then return;
    v.key := x; update H.min;
    if v ∈ H.rootlist ∨ x ≥ v.parent.key then return
    repeat
    parent := v.parent;
    H.cut(v);
    v := parent;
    until ¬(v.mark) ∨ v ∈ H.rootlist;
    if v ∉ H.rootlist then v.mark := true;
```

# Operation Cut(v)



### Operation H.cut(v):

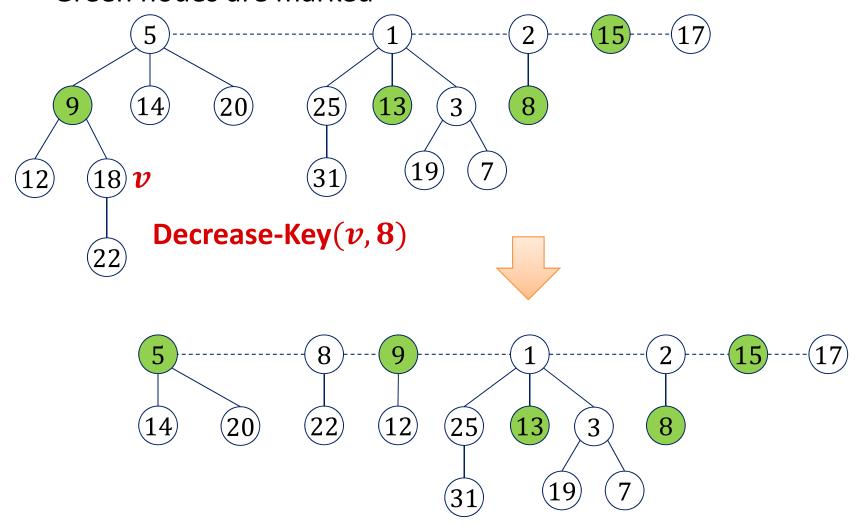
- Cuts v's sub-tree from its parent and adds v to rootlist
- 1. if  $v \notin H$ . rootlist then
- 2. // cut the link between v and its parent
- 3. rank(v.parent) = rank(v.parent) 1;
- 4. remove v from v. parent. child (list)
- 5. v.parent := null;
- 6. add v to H.rootlist



### Decrease-Key Example



Green nodes are marked



### Fibonacci Heap Marks



### History of a node v:

v is being linked to a node v. mark := false

a child of v is cut  $\longrightarrow$  v. mark := true

a second child of v is cut  $\longrightarrow$  H. cut(v)

Hence, the boolean value v. mark indicates whether node v
has lost a child since the last time v was made the child of
another node.

# Cost of Delete-Min & Decrease-Key



#### **Delete-Min:**

- 1. Delete min. root r and add r. child to H. rootlist time: O(1)
- 2. Consolidate H.rootlist time: O(length of <math>H.rootlist + D(n))
- Step 2 can potentially be linear in n (size of H)

### Decrease-Key (at node v):

- 1. If new key < parent key, cut sub-tree of node v time: O(1)
- 2. Cascading cuts up the tree as long as nodes are marked time: *O*(number of consecutive marked nodes)
- Step 2 can potentially be linear in n

Exercises: Both operations can take  $\Theta(n)$  time in the worst case!

# Cost of Delete-Min & Decrease-Key



- Cost of delete-min and decrease-key can be  $\Theta(n)$ ...
  - Seems a large price to pay to get insert and merge in O(1) time
- Maybe, the operations are efficient most of the time?
  - It seems to require a lot of operations to get a long rootlist and thus,
     an expensive consolidate operation
  - In each decrease-key operation, at most one node gets marked:
     We need a lot of decrease-key operations to get an expensive decrease-key operation
- Can we show that the average cost per operation is small?
- We can → requires amortized analysis