



# Chapter 1

# Divide and Conquer

## Polynomial Multiplication II

Algorithm Theory  
WS 2015/16

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# Operations: Multiplication

- Given: Polynomials  $p, q \in \mathbb{R}[x]$  of degree  $n$

$$p(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$$

$$q(x) = b_n x^n + b_{n-1} x^{n-1} + \dots + b_1 x + b_0$$

- Product  $p(x) \cdot q(x)$ :

$$p(x) \cdot q(x) = (a_n x^n + \dots + a_0) \cdot (b_n x^n + \dots + b_0)$$

$$= c_{2n} x^{2n} + c_{2n-1} x^{2n-1} + \dots + c_1 x + c_0$$

- Obtaining  $c_i$ : what products of monomials have degree  $i$ ?

$$\text{For } 0 \leq i \leq 2n: c_i = \sum_{j=0}^i a_j b_{i-j}$$

where  $a_i = b_i = 0$  for  $i > n$ .

# Polynomial Multiplication using DFT

Idea to compute  $p(x) \cdot q(x)$  (for polynomials of degree  $< n$ ):

$p, q$  of degree  $n - 1$ ,  $n$  coefficients

**Evaluation** at points  $\omega_{2n}^0, \omega_{2n}^1, \dots, \omega_{2n}^{2n-1}$

$2 \times 2n$  point-value pairs  $(\omega_{2n}^k, p(\omega_{2n}^k))$  and  $(\omega_{2n}^k, q(\omega_{2n}^k))$

**Point-wise multiplication**

$2n$  point-value pairs  $(\omega_{2n}^k, p(\omega_{2n}^k)q(\omega_{2n}^k))$

**Interpolation**

$p(x)q(x)$  of degree  $2n - 2$ ,  $2n - 1$  coefficients

# Point-Value Representation of $p, q$

- Select points  $x_0, x_1, \dots, x_{N-1}$  to evaluate  $p$  and  $q$  in a clever way

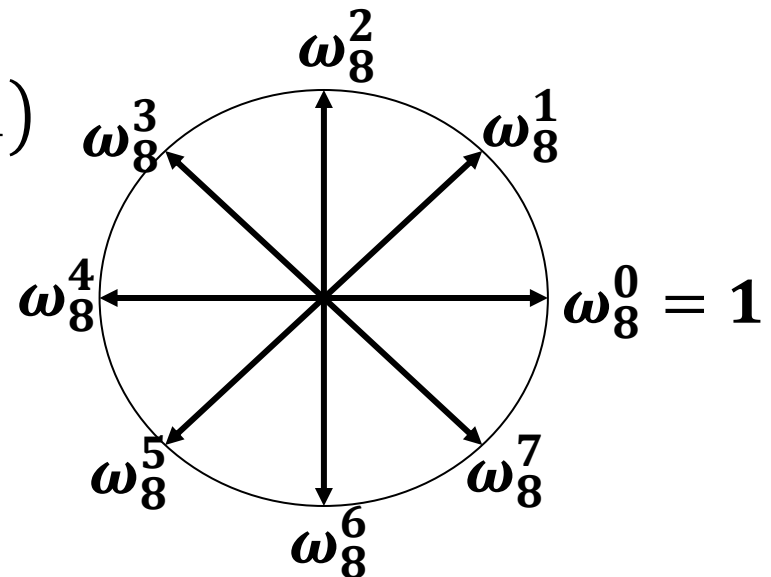
Consider the  $N$  powers of the principle  $N$ th root of unity:

**Principle root of unity:**  $\omega_N = e^{2\pi i/N}$

$$(i = \sqrt{-1}, \quad e^{2\pi i} = 1)$$

**Powers of  $\omega_N$  (roots of unity):**

$$1 = \omega_N^0, \omega_N^1, \dots, \omega_N^{N-1}$$



**Properties:**  $\omega_N^{dk} = \omega_N^k, \quad \omega_N^{k \pm n} = \omega_N^k$

# Discrete Fourier Transform

- The values  $p(\omega_N^i)$  for  $i = 0, \dots, N - 1$  uniquely define a polynomial  $p$  of degree  $< N$ .

## Discrete Fourier Transform (DFT):

- Assume  $a = (a_0, \dots, a_{N-1})$  is the coefficient vector of poly.  $p$   
$$(p(x) = a_{N-1}x^{N-1} + \dots + a_1x + a_0)$$

$$\text{DFT}_N(a) := \left( p(\omega_N^0), p(\omega_N^1), \dots, p(\omega_N^{N-1}) \right)$$

# Divide-and-Conquer Approach

- Divide  $p(x)$  of degree  $N - 1$  ( $N$  is even) into 2 polynomials of degree  $N/2 - 1$  differently than in Karatsuba's algorithm
- $p_0(x) = a_0 + a_2x + a_4x^2 + \dots + a_{N-2}x^{N/2-1}$  (even coeff.)  
 $p_1(x) = a_1 + a_3x + a_5x^2 + \dots + a_{N-1}x^{N/2-1}$  (odd coeff.)

# Recursively Computing the DFT

Polynomial  $p$  of degree  $N - 1$ :

$$\begin{aligned}
 p(\omega_N^k) &= \begin{cases} p_0(\omega_{N/2}^k) + \omega_N^k \cdot p_1(\omega_{N/2}^k) & \text{if } k < N/2 \\ p_0(\omega_{N/2}^{k-N/2}) + \omega_N^k \cdot p_1(\omega_{N/2}^{k-N/2}) & \text{if } k \geq N/2 \end{cases} \\
 &= \begin{cases} p_0(\omega_{N/2}^k) + \omega_N^k \cdot p_1(\omega_{N/2}^k) & \text{if } k < N/2 \\ p_0(\omega_{N/2}^{k-N/2}) - \omega_N^{k-N/2} \cdot p_1(\omega_{N/2}^{k-N/2}) & \text{if } k \geq N/2 \end{cases}
 \end{aligned}$$

Need to compute  $p_0(\omega_{N/2}^k)$  and  $\omega_N^k \cdot p_1(\omega_{N/2}^k)$  for  $0 \leq k < N/2$ .

# Example $n = 8$

$$p(\omega_8^0) = p_0(\omega_4^0) + \omega_8^0 \cdot p_1(\omega_4^0)$$

$$p(\omega_8^1) = p_0(\omega_4^1) + \omega_8^1 \cdot p_1(\omega_4^1)$$

$$p(\omega_8^2) = p_0(\omega_4^2) + \omega_8^2 \cdot p_1(\omega_4^2)$$

$$p(\omega_8^3) = p_0(\omega_4^3) + \omega_8^3 \cdot p_1(\omega_4^3)$$

$$p(\omega_8^3) = p_0(\omega_4^0) - \omega_8^0 \cdot p_1(\omega_4^0)$$

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$$p(\omega_8^3) = p_0(\omega_4^3) - \omega_8^3 \cdot p_1(\omega_4^3)$$



# Example $n = 4$

$$p(\omega_4^0) = p_0(\omega_2^0) + \omega_4^0 \cdot p_1(\omega_2^0)$$

$$p(\omega_4^1) = p_0(\omega_2^1) + \omega_4^1 \cdot p_1(\omega_2^1)$$

$$p(\omega_4^2) = p_0(\omega_2^0) - \omega_4^0 \cdot p_1(\omega_2^0)$$

$$p(\omega_4^3) = p_0(\omega_2^1) - \omega_4^1 \cdot p_1(\omega_2^1)$$

# Example

- $p(x) = 3x^3 - 15x^2 + 18x + 0, a = [0, 18, -15, 3]$

# Faster Polynomial Multiplication?

Idea to compute  $p(x) \cdot q(x)$  (for polynomials of degree  $< n$ ):

$p, q$  of degree  $n - 1$ ,  $n$  coefficients

**Evaluation** at  $\omega_{2n}^0, \omega_{2n}^1, \dots, \omega_{2n}^{2n-1}$  using **FFT**

$2 \times 2n$  point-value pairs  $(\omega_{2n}^k, p(\omega_{2n}^k))$  and  $(\omega_{2n}^k, q(\omega_{2n}^k))$

**Point-wise multiplication**

$2n$  point-value pairs  $(\omega_{2n}^k, p(\omega_{2n}^k)q(\omega_{2n}^k))$

**Interpolation**

$p(x)q(x)$  of degree  $2n - 2$ ,  $2n - 1$  coefficients

# Interpolation

Convert point-value representation into coefficient representation

**Input:**  $(x_0, y_0), \dots, (x_{n-1}, y_{n-1})$  with  $x_i \neq x_j$  for  $i \neq j$

**Output:**

Degree- $(n - 1)$  polynomial with coefficients  $a_0, \dots, a_{n-1}$  such that

$$\begin{aligned} p(x_0) &= a_0 + a_1x_0 + a_2x_0^2 + \dots + a_{n-1}x_0^{n-1} = y_0 \\ p(x_1) &= a_0 + a_1x_1 + a_2x_1^2 + \dots + a_{n-1}x_1^{n-1} = y_1 \\ &\vdots \\ p(x_{n-1}) &= a_0 + a_1x_{n-1} + a_2x_{n-1}^2 + \dots + a_{n-1}x_{n-1}^{n-1} = y_{n-1} \end{aligned}$$

→ linear system of equations for  $a_0, \dots, a_{n-1}$

# Interpolation

## Matrix Notation:

$$\begin{pmatrix} 1 & x_0 & \cdots & x_0^{n-1} \\ 1 & x_1 & \cdots & x_1^{n-1} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_{n-1} & \cdots & x_{n-1}^{n-1} \end{pmatrix} \cdot \begin{pmatrix} a_0 \\ a_1 \\ \vdots \\ a_{n-1} \end{pmatrix} = \begin{pmatrix} y_0 \\ y_1 \\ \vdots \\ y_{n-1} \end{pmatrix}$$

- System of equations solvable iff  $x_i \neq x_j$  for all  $i \neq j$

## Special Case $x_i = \omega_n^i$ :

$$\begin{pmatrix} 1 & 1 & 1 & \cdots & 1 \\ 1 & \omega_n & \omega_n^2 & \cdots & \omega_n^{n-1} \\ 1 & \omega_n^2 & \omega_n^4 & \cdots & \omega_n^{2(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega_n^{n-1} & \omega_n^{2(n-1)} & \cdots & \omega_n^{(n-1)(n-1)} \end{pmatrix} \cdot \begin{pmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_{n-1} \end{pmatrix} = \begin{pmatrix} y_0 \\ y_1 \\ y_2 \\ \vdots \\ y_{n-1} \end{pmatrix}$$

# Interpolation

- Linear system:

$$W \cdot \mathbf{a} = \mathbf{y} \quad \Rightarrow \quad \mathbf{a} = W^{-1} \cdot \mathbf{y}$$

$$W_{i,j} = \omega_n^{ij}, \quad \mathbf{a} = \begin{pmatrix} a_0 \\ \vdots \\ a_{n-1} \end{pmatrix}, \quad \mathbf{y} = \begin{pmatrix} y_0 \\ \vdots \\ y_{n-1} \end{pmatrix}$$

**Claim:**

$$W_{ij}^{-1} = \frac{\omega_n^{-ij}}{n}$$

Proof: Need to show that  $W^{-1}W = I_n$

# DFT Matrix Inverse

$$W^{-1}W = \begin{pmatrix} \frac{1}{n} & \frac{\omega_n^{-i}}{n} & \dots & \frac{\omega_n^{-(n-1)i}}{n} \\ \dots & \dots & \dots & \dots \\ \dots & \dots & \vdots & \dots \\ \dots & \dots & \dots & \dots \end{pmatrix} \cdot \begin{pmatrix} \dots & 1 & \dots \\ \dots & \omega_n^j & \dots \\ \dots & \omega_n^{2j} & \dots \\ \dots & \vdots & \dots \\ \dots & \omega_n^{(n-1)j} & \dots \end{pmatrix}$$

# DFT Matrix Inverse

$$(W^{-1}W)_{i,j} = \sum_{\ell=0}^{n-1} \frac{\omega_n^{\ell(j-i)}}{n}$$

Need to show  $(W^{-1}W)_{i,j} = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$

**Case  $i = j$ :**



$$(W^{-1}W)_{i,j} = \sum_{\ell=0}^{n-1} \frac{\omega_n^{\ell(j-i)}}{n}$$

**Case  $i \neq j$ :**

# Inverse DFT

- $$W^{-1} = \begin{pmatrix} \frac{1}{n} & \frac{\omega_n^{-k}}{n} & \dots & \frac{\omega_n^{-(n-1)k}}{n} \\ \vdots & \vdots & \ddots & \vdots \\ \dots & \dots & \dots & \dots \end{pmatrix}$$

- We get  $\mathbf{a} = W^{-1} \cdot \mathbf{y}$  and therefore

$$\begin{aligned} a_k &= \begin{pmatrix} \frac{1}{n} & \frac{\omega_n^{-k}}{n} & \dots & \frac{\omega_n^{-(n-1)k}}{n} \end{pmatrix} \cdot \begin{pmatrix} y_0 \\ y_1 \\ \vdots \\ y_{n-1} \end{pmatrix} \\ &= \frac{1}{n} \cdot \sum_{j=0}^{n-1} \omega_n^{-kj} \cdot y_j \end{aligned}$$

# DFT and Inverse DFT

## Inverse DFT:

$$a_k = \frac{1}{n} \cdot \sum_{j=0}^{n-1} \omega_n^{-kj} \cdot y_j$$

- Define polynomial  $q(x) = y_0 + y_1x + \dots + y_{n-1}x^{n-1}$ :

$$a_k = \frac{1}{n} \cdot q(\omega_n^{-k})$$

## DFT:

- Polynomial  $p(x) = a_0 + a_1x + \dots + a_{n-1}x^{n-1}$ :

$$y_k = p(\omega_n^k)$$

# DFT and Inverse DFT

$$q(x) = y_0 + y_1x + \cdots + y_{n-1}x^{n-1}, \quad a_k = \frac{1}{n} \cdot q(\omega_n^{-k}):$$

- Therefore:

$$\begin{aligned} & (a_0, a_1, \dots, a_{n-1}) \\ &= \frac{1}{n} \cdot \left( q(\omega_n^{-0}), q(\omega_n^{-1}), q(\omega_n^{-2}), \dots, q(\omega_n^{-(n-1)}) \right) \\ &= \frac{1}{n} \cdot \left( q(\omega_n^0), q(\omega_n^{n-1}), q(\omega_n^{n-2}), \dots, q(\omega_n^1) \right) \end{aligned}$$

- Recall:

$$\begin{aligned} \text{DFT}_n(\mathbf{y}) &= \left( q(\omega_n^0), q(\omega_n^1), q(\omega_n^2), \dots, q(\omega_n^{n-1}) \right) \\ &= n \cdot (a_0, a_{n-1}, a_{n-2}, \dots, a_2, a_1) \end{aligned}$$

# DFT and Inverse DFT

- We have  $\text{DFT}_n(\mathbf{y}) = n \cdot (a_0, a_{n-1}, a_{n-2}, \dots, a_2, a_1)$ :

$$a_i = \begin{cases} \frac{1}{n} \cdot (\text{DFT}_n(\mathbf{y}))_0 & \text{if } i = 0 \\ \frac{1}{n} \cdot (\text{DFT}_n(\mathbf{y}))_{n-i} & \text{if } i \neq 0 \end{cases}$$

- DFT and inverse DFT can both be computed using FFT algorithm in  $O(n \log n)$  time.
- 2 polynomials of  $\text{degr.} < n$  can be multiplied in time  $O(n \log n)$ .

# Faster Polynomial Multiplication?

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**Interpolation** using **FFT**

$p(x)q(x)$  of degree  $2n - 2$ ,  $2n - 1$  coefficients

# Convolution

- More generally, the polynomial multiplication algorithm computes the convolution of two vectors:

$$\mathbf{a} = (a_0, a_1, \dots, a_{m-1})$$

$$\mathbf{b} = (b_0, b_1, \dots, b_{n-1})$$

$$\mathbf{a} * \mathbf{b} = (c_0, c_1, \dots, c_{m+n-2}),$$

$$\text{where } c_k = \sum_{\substack{(i,j):i+j=k \\ i < m, j < n}} a_i b_j$$

- $c_k$  is exactly the coefficient of  $x^k$  in the product polynomial of the polynomials defined by the coefficient vectors  $\mathbf{a}$  and  $\mathbf{b}$

# More Applications of Convolutions

## Signal Processing Example:

- Assume  $\mathbf{a} = (a_0, \dots, a_{n-1})$  represents a sequence of measurements over time
- Measurements might be noisy and have to be smoothed out
- Replace  $a_i$  by weighted average of nearby last  $m$  and next  $m$  measurements (e.g., Gaussian smoothing):

$$a'_i = \frac{1}{Z} \cdot \sum_{j=i-m}^{i+m} a_j e^{-(i-j)^2}$$

- New vector  $\mathbf{a}'$  is the convolution of  $\mathbf{a}$  and the weight vector  $\frac{1}{Z} \cdot (e^{-m^2}, e^{-(m-1)^2}, \dots, e^{-1}, 1, e^{-1}, \dots, e^{-(m-1)^2}, e^{-m^2})$
- Might need to take care of boundary points...



# More Applications of Convolutions

## Combining Histograms:

- Vectors  $\mathbf{a}$  and  $\mathbf{b}$  represent two histograms
- E.g., annual income of all men & annual income of all women
- Goal: Get new histogram  $\mathbf{c}$  representing combined income of all possible pairs of men and women:

$$\mathbf{c} = \mathbf{a} * \mathbf{b}$$

**Also, the DFT (and thus the FFT alg.) has many other applications!**