



Chapter 5 Data Structures

Algorithm Theory WS 2015/16

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Priority Queue / Heap



- Stores (key,data) pairs (like dictionary)
- But, different set of operations:
- Initialize-Heap: creates new empty heap
- Is-Empty: returns true if heap is empty
- Insert(key,data): inserts (key,data)-pair, returns pointer to entry
- Get-Min: returns (key,data)-pair with minimum key
- Delete-Min: deletes minimum (key,data)-pair
- **Decrease-Key**(*entry*, *newkey*): decreases *key* of *entry* to *newkey*
- Merge: merges two heaps into one

Analysis



Number of priority queue operations for Dijkstra:

• Initialize-Heap: 1

• Is-Empty: |V|

• Insert: |*V*|

• Get-Min: V

• Del<u>ete</u>-Min: |V|

• Decrease-Key: |E|

Merge: 0

Priority Queue Implementation



Implementation as min-heap:

> complete binary tree, e.g., stored in an array

Initialize-Heap: **0**(1)

Is-Empty: O(1)

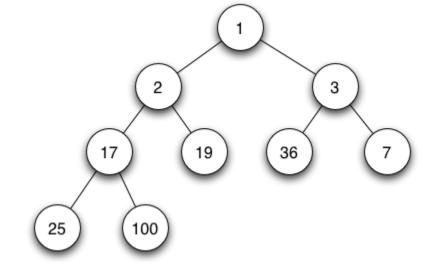
 $O(\log n)$ Insert:

Get-Min: O(1)

Delete-Min: $O(\log n)$

 $O(\log n)$ **Decrease-Key**:

Merge (heaps of size m and $n, m \leq n$): $O(m \log n)$



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Fibonacci Heaps

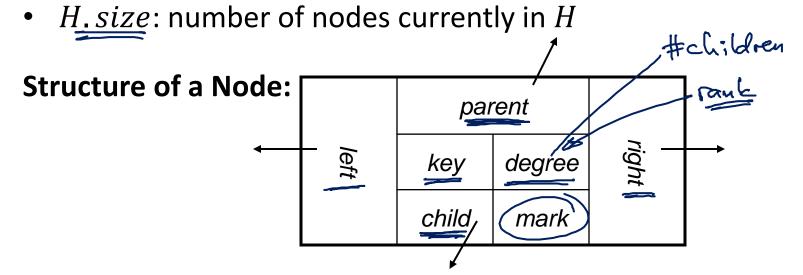


Structure:

A Fibonacci heap H consists of a collection of trees satisfying the min-heap property.

Global Variables:

- *H.min*: root of the tree containing the (a) minimum key
- *H.rootlist*: circular, doubly linked, unordered list containing the roots of all trees



Fibonacci Heaps



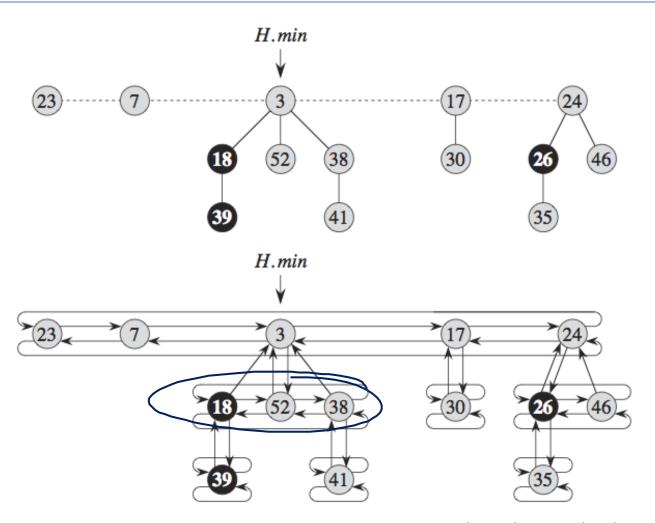


Figure: Cormen et al., Introduction to Algorithms

Simple (Lazy) Operations



Initialize-Heap *H*:

• H.rootlist := H.min := null

Merge heaps H and H':

- concatenate root lists
- update *H.min*

Insert element *e* into *H*:

- create new one-node tree containing $e \rightarrow H'$
 - mark of root node is set to false
- merge heaps H and H'

Get minimum element of *H*:

return H. min

Operation Delete-Min



Delete the node with minimum key from H and return its element:

- 1. $m \coloneqq H.min$;
- 2. if H.size > 0 then
- 3. remove H.min from H.rootlist;
- 4. add *H. min. child* (list) to *H. rootlist*
- 5. (H. Consolidate();

```
// Repeatedly merge nodes with equal <u>degree</u> in the root list 
// until <u>degrees</u> of nodes in the root list are distinct.
// Determine the element with minimum key
```

6. return m

Rank and Maximum Degree



Ranks of nodes, trees, heap:

Node v:

• rank(v): degree of v (number of children of v)

Tree T:

• rank(T): rank (degree) of root node of T

Heap H:

• rank(H): maximum degree (#children) of any node in H

Assumption (n: number of nodes in H):

$$rank(H) \leq D(n)$$

- for a known function D(n)



Merging Two Trees



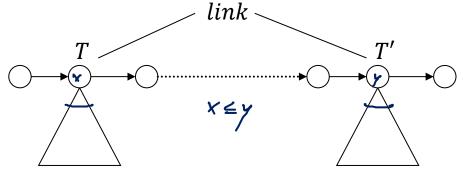
Given: Heap-ordered trees T, T' with rank(T) = rank(T')

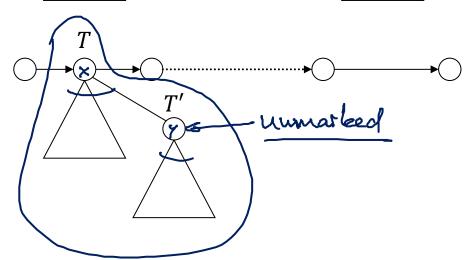
• Assume: \min -key of $T \leqslant \min$ -key of T'

Operation link(T, T'):

• Removes tree T' from root list and adds T' to child list of T

- $rank(T) \coloneqq rank(T) + 1$
- (T'.mark := false)





Consolidation of Root List 17/1---





Array \underline{A} pointing to find roots with the same rank:

Consolidate:

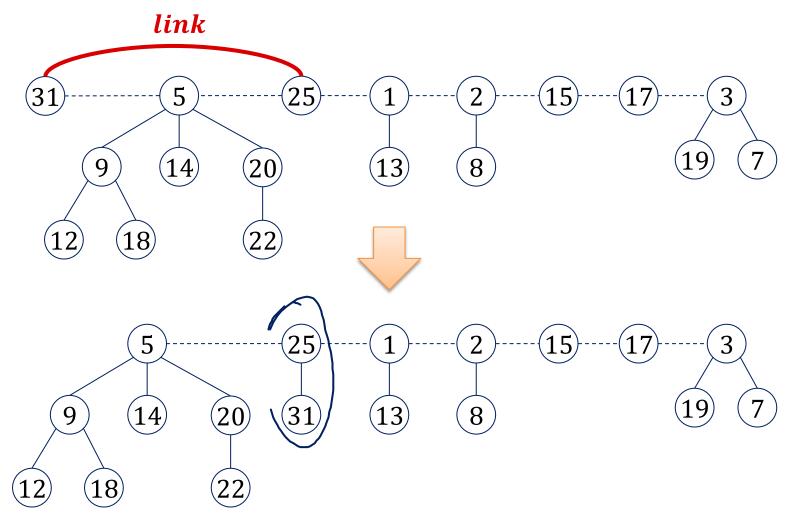
- 1. for i := 0 to D(n) do A[i] := null;
- 2. while $H.rootlist \neq null$ do

Time:
$$O(|H.rootlist| + D(n))$$

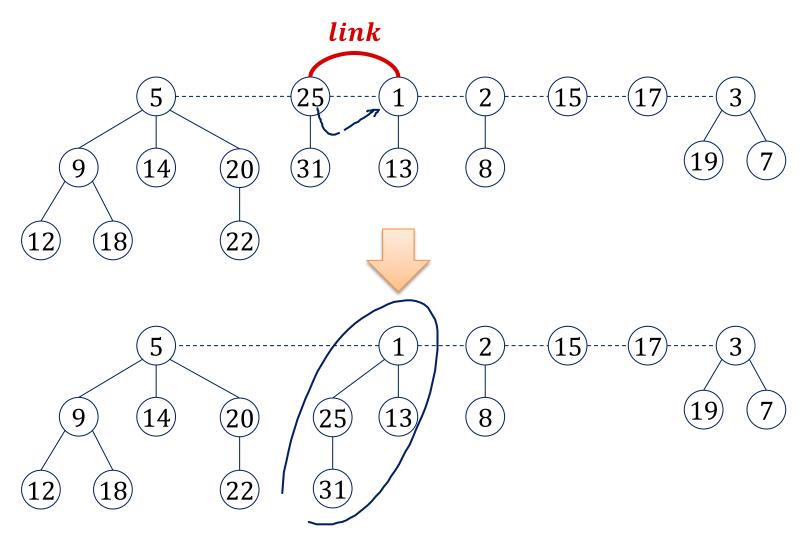
H. rotCist1-1

- 3. T := "delete and return first element of H.rootlist"
- 4. while $A[rank(T)] \neq \text{null do}$
- 5. $\underline{T}' \coloneqq A[rank(T)];$
- 6. A[rank(T)] := null;
- 7. T := link(T, T')
- 8. A[rank(T)] := T
- 9. Create new H.rootlist and H.min

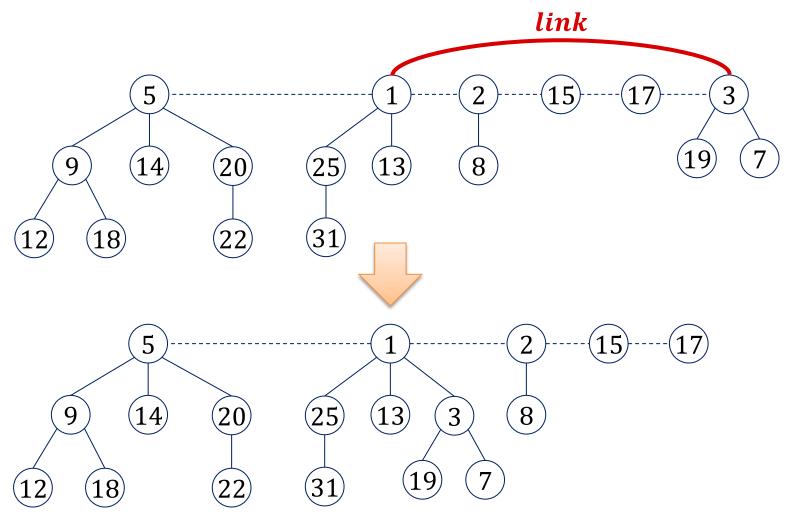




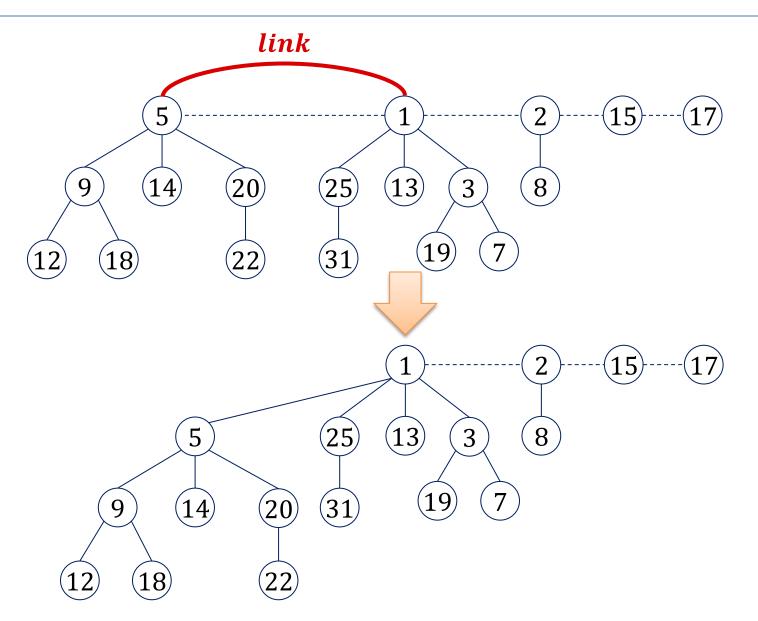




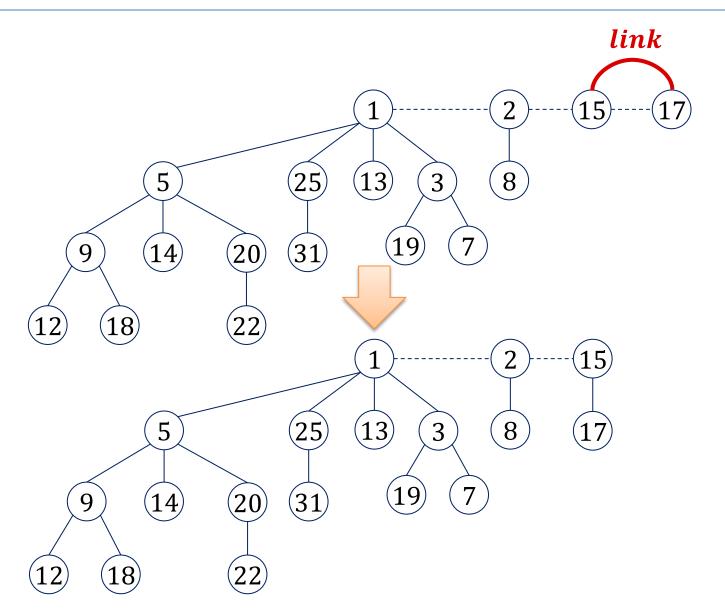




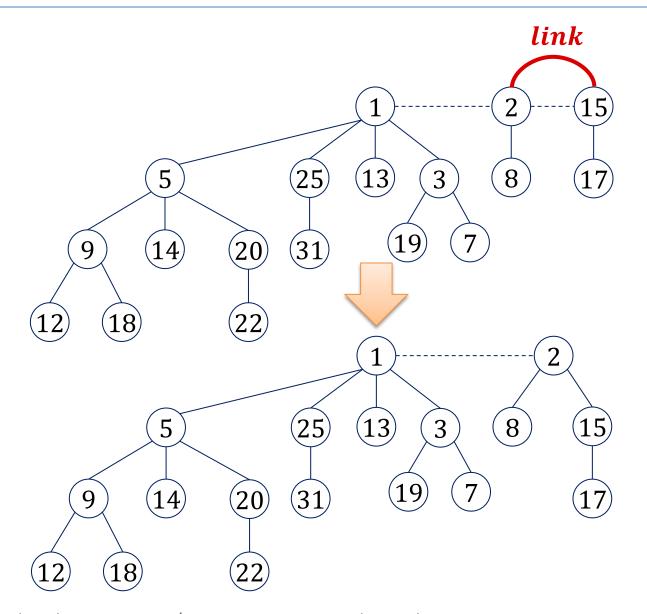












Operation Decrease-Key



Decrease-Key (v, \underline{x}) : (decrease key of node v to new value x)

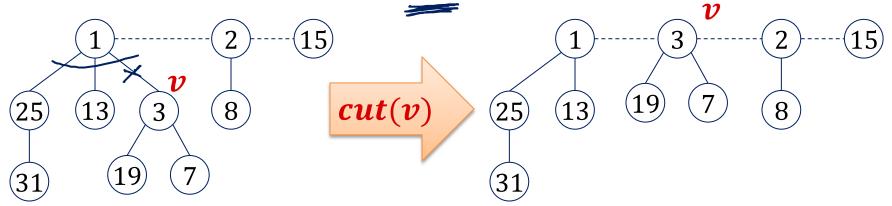
- 1. if $x \ge v$. key then return; 2. v. key := x; update H. min;
- 3. if $v \in H$.rootlist $\lor x \ge v$.parent.key then return
- 4. repeat
- 5. parent = v.parent;
- 6. H.cut(v);
- 7. v = parent;
- 8. until $\neg (v.mark) \lor v \in H.rootlist;$
- 9. if $v \notin H.rootlist$ then v.mark := true;

Operation Cut(v)



Operation H.cut(v):

- Cuts v's sub-tree from its parent and adds v to rootlist
- 1. if $v \notin H$. rootlist then
- 2. // cut the link between v and its parent
- 3. rank(v.parent) = rank(v.parent) 1;
- 4. remove v from v. parent. child (list)
- 5. v.parent = null;
- 6. add v to H.rootlist; v.mark := false;



Decrease-Key Example



Green nodes are marked (13)(8)20**4**8) \triangleright ecrease-Key(v, 8)(13)(8)

Fibonacci Heaps Marks



- Nodes in the root list (the tree roots) are always unmarked
 - The mark of the node is set to false.
- Nodes not in the root list can only get marked when a subtree is cut in a decrease-key operation
- A node v is marked if and only if v is not in the robt list and v has lost a child since v was attached to its current parent
 - a node can only change its parent by being moved to the root list

Fibonacci Heap Marks



History of a node v:

v is being linked to a node



v.mark = false

a child of v is cut



v.mark = true

a second child of v is cut



H.cut(v); v.mark := false

- Hence, the boolean value v.mark indicates whether node v has lost a child since the last time v was made the child of another node.
- Nodes v in the root list always have v. mark = false

Cost of Delete-Min & Decrease-Key



Delete-Min:

- 1. Delete min. root r and add r. child to H. rootlist
 - time: O(1) & O(D(n)) if remove marks

/ before delete-min

- 2. Consolidate *H. rootlist*
 - time: Q(length of H.rootlist + D(n))
- Step 2 can potentially be linear in n (size of H)

Decrease-Key (at node v):

- 1. If new key < parent key, cut sub-tree of node v time: O(1)
- 2. Cascading cuts up the tree as long as nodes are marked time: O(number of consecutive marked nodes)
- Step 2 can potentially be linear in n

Exercises: Both operations can take $\Theta(n)$ time in the worst case!

Cost of Delete-Min & Decrease-Key



- Cost of delete-min and decrease-key can be $\Theta(n)$...
 - Seems a large price to pay to get insert and merge in O(1) time
- Maybe, the operations are efficient most of the time?
 - It seems to require a lot of operations to get a long rootlist and thus,
 an expensive consolidate operation
 - In each decrease-key operation, at most one node gets marked:
 We need a lot of decrease-key operations to get an expensive decrease-key operation
- Can we show that the average cost per operation is small?
- We can → requires amortized analysis

Fibonacci Heaps Complexity



- Worst-case cost of a single delete-min or decrease-key operation is $\Omega(n)$
- Can we prove a small worst-case amortized cost for delete-min and decrease-key operations?

Recall:

- Data structure that allows operations $\underline{O_1}$, ..., $\underline{O_k}$
- We say that operation O_p has amortized cost a_p if for every execution the total time is

$$T \leq \sum_{p=1}^{\kappa} n_p \cdot a_p \,,$$

where n_p is the number of operations of type \mathcal{O}_p

Amortized Cost of Fibonacci Heaps



- Initialize-heap, is-empty, get-min, insert, and merge have worst-case cost O(1) and anothed cost O(1)
- Delete-min has amortized cost $O(\log n)$
- Decrease-key has amortized cost O(1)
- Starting with an empty heap, any sequence of \underline{n} operations with at most n_d delete-min operations has total cost (time)

$$T = O(\underline{n} + n_d \log n).$$

We will now need the marks...

• Cost for Dijkstra: $O(|E| + |V| \log |V|)$

decrease - ay

Fibonacci Heaps: Marks



Cycle of a node:

1. Node v is removed from root list and linked to a node

$$v.mark = false$$

2. Child node *u* of *v* is cut and added to root list

```
v.mark = true
```

3. Second child of v is cut

```
node v is cut as well and moved to root list v. mark := false
```

The boolean value v. mark indicates whether node v has lost a child since the last time v was made the child of another node.

Potential Function



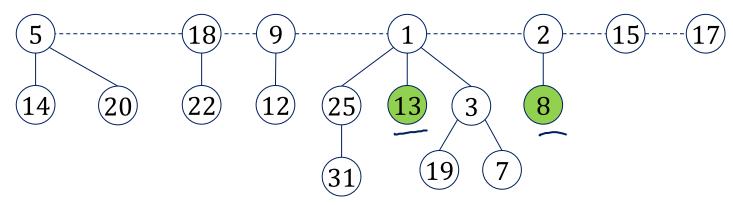
System state characterized by two parameters:

- **R**: number of trees (length of *H*. rootlist)
- M: number of marked nodes (not in the root list)

Potential function:

$$\Phi \coloneqq R + 2M$$

Example:



•
$$R = 7, M = 2 \rightarrow \Phi = 11$$

Actual Time of Operations



Operations: initialize-heap, is-empty, insert, get-min, merge

actual time: O(1)

Normalize unit time such that

 $t_{init}, t_{is-empty}, t_{insert}, t_{get-min}, t_{merge} \leq 1$

- Operation delete-min: Selone delete-min
- - Actual time: O(length of H.rootlist + D(n))
 - Normalize unit time such that

$$t_{del-min} \le D(n) + \text{length of } H.rootlist$$

- Operation **descrease-key**:
 - Actual time: O(length of path to next unmarked ancestor)
 - Normalize unit time such that

 $t_{decr-kev} \leq \text{length of path to next unmarked ancestor}$

Amortized Times

$$\alpha_i = \epsilon_i + \phi_i - \phi_{i-1}$$



Assume operation i is of type:

initialize-heap:

- actual time: $t_i \le 1$, potential: $\Phi_{i-1} = \Phi_i = 0$
- amortized time: $\underline{a_i} = t_i + \Phi_i \Phi_{i-1} \leq 1$

• is-empty, get-min:

- actual time: $t_i \leq 1$, potential: $\Phi_i = \Phi_{i-1}$ (heap doesn't change)
- amortized time: $a_i = t_i + \Phi_i \Phi_{i-1} \le 1$

merge:

- − Actual time: $t_i \le 1$
- combined potential of both heaps: $\Phi_i = \Phi_{i-1}$
- amortized time: $a_i = t_i + \Phi_i \Phi_{i-1} \leq 1$

Amortized Time of Insert



Assume that operation i is an *insert* operation:

• Actual time: $t_i \leq 1$



- Potential function:
 - M remains unchanged (no nodes are marked or unmarked, no marked nodes are moved to the root list)
 - R grows by 1 (one element is added to the root list)

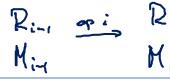
$$\phi = R + 2M$$

$$M_{i} = M_{i-1}, R_{i} = R_{i-1} + 1$$
 $M_{i} = M_{i-1} + 1$

Amortized time:

$$a_i = t_i + \Phi_i - \Phi_{i-1} \le 2$$

Amortized Time of Delete-Min $\frac{\mathcal{R}_{i-1}}{\mathcal{M}_{i-1}}$





Assume that operation i is a *delete-min* operation: / before of

Actual time:
$$t_i \leq D(n) + |H.rootlist|$$

$$\mathbb{R}_i \leq \mathbb{D}(w) + 1$$

Potential function $\Phi = R + 2M$:

- R: changes from |H.rootlist| to at most D(n)+1
- M: (# of marked nodes that are not in the root list)



- no new marks
- if node v is moved away from root list, v. mark is set to false \rightarrow value of M does not increase!

$$\underline{\underline{M_i}} \leq \underline{\underline{M_{i-1}}}, \quad \underline{R_i} \leq \underline{\underline{R_{i-1}}} + D(n) - |H.rootlist| + 1$$

$$\underline{\underline{\Phi_i}} \leq \underline{\underline{\Phi_{i-1}}} + D(n) - |H.rootlist| + 1$$

Amortized Time:

$$a_i = \underbrace{t_i + \Phi_i - \Phi_{i-1}}_{=} \leq \underbrace{2D(n) + 1}_{=}$$

Amortized Time of Decrease-Key



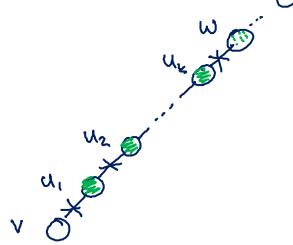
Assume that operation i is a decrease-key operation at node u:

Actual time: $t_i \leq \text{length of path to next unmarked ancestor } v$

Potential function $\Phi = R + 2M$:

- Assume, node u and nodes u_1, \dots, u_k are moved to root list
 - $-u_1, ..., u_k$ are marked and moved to root list, v. mark is set to true

t; ≤ k+1



the cuts

rootlist grows by k+1

thenove z & marks

add I mark

Amortized Time of Decrease-Key



Assume that operation i is a decrease-key operation at node u:

Actual time: $t_i \leq \text{length of path to next unmarked ancestor } v$

Potential function $\Phi = R + \frac{1}{2}M$:

- Assume, node u and nodes u_1, \dots, u_k are moved to root list
 - $-u_1, ..., u_k$ are marked and moved to root list, v. mark is set to true
- $\geq k$ marked nodes go to root list, ≤ 1 node gets newly marked
- R grows by $\leq k+1$, M grows by 1 and is decreased by $\geq k$

$$R_i \le R_{i-1} + k + 1, \qquad M_i \le M_{i-1} + 1 - k$$

 $\Phi_i \le \Phi_{i-1} + (k+1) - 2(k-1) = \Phi_{i-1} + 3 - k$

Amortized time:

$$a_i = t_i + \Phi_i - \Phi_{i-1} \le k+1+3-k=4$$

Complexities Fibonacci Heap



• Initialize-Heap: O(1)

• Is-Empty: O(1)

• Insert: O(1)

• Get-Min: O(1)

• Delete-Min: O(D(n)) \longrightarrow amortized

• Decrease-Key: O(1)

• Merge (heaps of size m and $n, m \le n$): O(1)

• How large can D(n) get?

need to show that D(n) = O(log n)

Rank of Children

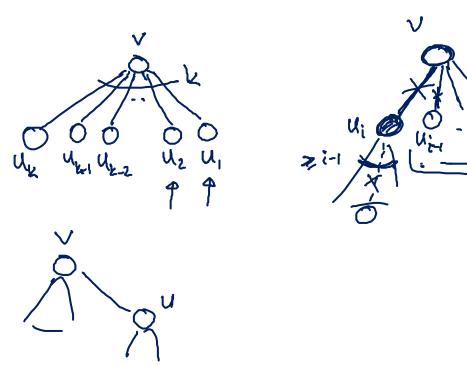


Lemma:

Consider a node v of rank k and let $u_1, ..., u_k$ be the children of v in the order in which they were linked to v. Then,

$$rank(u_i) \geq i-2.$$

Proof:





Fibonacci Numbers:

$$F_0=0,$$

$$F_1=1,$$

$$F_0 = 0$$
, $F_1 = 1$, $\forall k \ge 2$: $F_k = F_{k-1} + F_{k-2}$

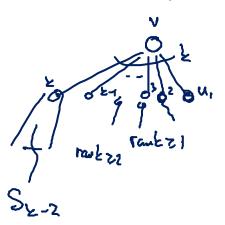
Lemma:

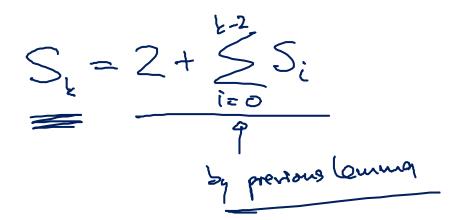
In a Fibonacci heap, the size of the sub-tree of a node \underline{v} with rank k is at least F_{k+2} .

Proof:

• S_k : minimum size of the sub-tree of a node of rank k

$$S_0=1$$
, $S_1=2$





Size of Trees

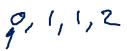


$$S_0 = 1$$
, $S_1 = 2$, $\forall k \ge 2 : S_k \ge 2 + \sum_{i=0}^{n-2} S_i$

Claim about Fibonacci numbers:

$$\forall k \geq 0: F_{k+2} = 1 + \sum_{i=0}^{k} F_{i}$$
lud. on k
base: $F_{z} = 1 + \sum_{i=0}^{k} F_{i} = 1 + 0 = 1$
step:
$$F_{k+2} = F_{k} + F_{k+1}$$
by ind: $1 + \sum_{i=0}^{k-1} F_{i}$

Size of Trees





$$S_0 = 1, S_1 = 2, \forall k \ge 2: S_k \ge 2 + \sum_{i=0}^{k-2} S_i, \qquad F_{k+2} = 1 + \sum_{i=0}^{k-2} S_i$$

• Claim of lemma: $S_k \ge F_{k+2}$

Size of Trees



Lemma:

In a Fibonacci heap, the size of the sub-tree of a node v with rank k is at least F_{k+2} . The property of the size of the sub-tree of a node v with rank k

Theorem:

The maximum rank of a node in a Fibonacci heap of size n is at most

$$D(n) = O(\log n).$$

Proof:

The Fibonacci numbers grow exponentially:

$$F_k = \frac{1}{\sqrt{5}} \cdot \left(\left(\frac{1 + \sqrt{5}}{2} \right)^k - \left(\frac{1 - \sqrt{5}}{2} \right)^k \right)$$

• For $D(n) \ge k$, we need $n \ge F_{k+2}$ nodes.

Summary: Binomial and Fibonacci Heaps



	Binary Heap	Fibonacci Heap
initialize	O (1)	0(1)
insert	$O(\log n)$	0(1)
get-min	O (1)	O (1)
delete-min	$O(\log n)$	$O(\log n)^*$
decrease-key	$O(\log n)$	0 (1) *
merge	$O(m \cdot \log n)$	0(1)
is-empty	0(1)	0(1)

^{*} amortized time