



Chapter 4

Amortized Analysis

Algorithm Theory
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What is the **average cost** of an operation in a **worst case sequence** of operations?

Amortized Cost

- Sequence of operations $i = \underline{1, 2, 3, \dots, n}$
- Actual cost of op. i : $\underline{t_i}$
- Amortized cost of op. i is $\underline{a_i}$ if for every possible seq. of op.,

$$T = \sum_{i=1}^n t_i \leq \sum_{i=1}^n a_i$$

Example 2: Binary Counter

Incrementing a binary counter: determine the bit flip cost:

Operation	Counter Value	Cost
	<u>00000</u>	
1	0000 1	1
2	000 10	2
3	000 11	1
4	00 100	3
5	0010 1	1
6	001 10	2
7	001 11	1
8	0 1000	4
9	0100 1	1
10	010 10	2
11	010 11	1
12	01 100	3
13	01 101	1

Accounting Method

Observation:

- Each increment flips exactly one 0 into a 1

$$00100\mathbf{0}1111 \Rightarrow 00100\mathbf{1}0000$$

Idea:

- Have a bank account (with initial amount 0)
- Paying x to the bank account costs x
- Take “money” from account to pay for expensive operations

Applied to binary counter:

- Flip from 0 to 1: pay 1 to bank account (cost: 2)
- Flip from 1 to 0: take 1 from bank account (cost: 0)
- Amount on **bank account = number of ones**
→ We always have enough “money” to pay!

Potential Function Method

- Most **generic** and **elegant** way to do amortized analysis!
 - But, also more abstract than the others...

- State of data structure / system: $S \in \mathcal{S}$ (state space)

Potential function $\Phi: \mathcal{S} \rightarrow \mathbb{R}_{\geq 0}$

binary counter

$\Phi(S) = \# \text{ 1's in the bit representation}$

- **Operation i :**

- t_i : actual cost of operation i
- S_i : state after execution of operation i (S_0 : initial state)
- $\Phi_i := \Phi(S_i)$: potential after exec. of operation i
- a_i : **amortized cost** of operation i :

$$a_i := t_i + \Phi_i - \Phi_{i-1}$$

Potential Function Method

Operation i :

actual cost: t_i amortized cost: $a_i := t_i + \Phi_i - \Phi_{i-1}$

Overall cost:

$$T := \sum_{i=1}^n t_i = \left(\sum_{i=1}^n a_i \right) + \Phi_0 - \underbrace{\Phi_n}_{\geq 0} \leq \sum_{i=1}^n a_i + \Phi_0$$

$$\begin{aligned}
 \sum_{i=1}^n a_i &= t_1 - \Phi_0 + \Phi_1 \\
 &+ t_2 - \Phi_1 + \Phi_2 \\
 &+ t_3 - \Phi_2 + \Phi_3 \\
 &\vdots \\
 &+ t_{n-1} - \Phi_{n-2} + \Phi_{n-1} \\
 &+ t_n - \Phi_{n-1} + \Phi_n = \sum_{i=1}^n t_i - \Phi_0 + \Phi_n
 \end{aligned}$$

Binary Counter: Potential Method

- Potential function:

Φ : number of ones in current counter

- Clearly, $\Phi_0 = 0$ and $\Phi_i \geq 0$ for all $i \geq 0$

- Actual cost t_i :

- 1 flip from 0 to 1
- $t_i - 1$ flips from 1 to 0

- Potential difference: $\Phi_i - \Phi_{i-1} = \underline{1} - \underline{(t_i - 1)} = \underline{2 - t_i}$

- Amortized cost: $a_i = \underline{t_i} + \underline{\Phi_i - \Phi_{i-1}} = 2$

Example 3: Dynamic Array

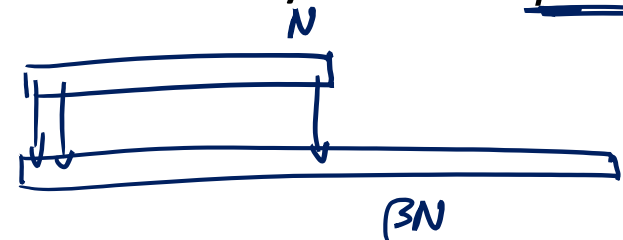
- How to create an array where the size dynamically adapts to the number of elements stored?
 - e.g., Java “ArrayList” or Python “list”

Implementation:

- Initialize with initial size N_0
- Assumptions: Array can only grow by appending new elements at the end
- If array is full, the size of the array is increased by a factor $\beta > 1$

Operations (array of size N):

- read / write: actual cost $O(1)$
- append: actual cost is $O(1)$ if array is not full, otherwise the append cost is $O(\beta \cdot N)$ (new array size)



Example 3: Dynamic Array

Notation:

- n : number of elements stored
- N : current size of array

Cost t_i of i^{th} append operation:
$$t_i = \begin{cases} 1 & \text{if } n < N \\ \beta \cdot N & \text{if } n = N \end{cases}$$

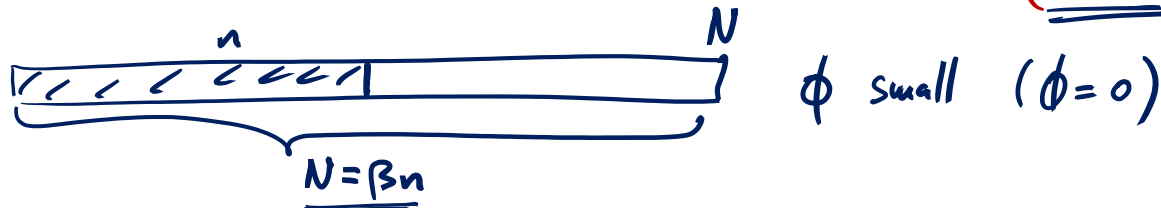
Claim: Amortized append cost is $O(1)$

Potential function Φ ?

- should allow to pay expensive append operations by cheap ones
- when array is full, Φ has to be large
- immediately after increasing the size of the array, Φ should be small again

Dynamic Array: Potential Function

Cost t_i of i^{th} append operation: $t_i = \begin{cases} 1 & \text{if } n < N \\ \beta \cdot N & \text{if } n = N \end{cases}$



at the beginning

$$N = N_0$$

$$n = 0$$



$$\phi(n, N) = c \cdot (\beta n - N) + c N_0$$

$$c(\beta N - N) \geq \beta N$$

$$c(\beta - 1) \geq \beta$$

$$c \geq \frac{\beta}{\beta - 1}$$

$$\phi(n, N) = \frac{\beta}{\beta - 1} (\beta n - N) + \frac{\beta}{\beta - 1} N_0$$

Dynamic Array: Amortized Cost

$$a_i = t_i + \phi_i - \phi_{i-1}$$



Cost t_i of i^{th} append operation: $t_i = \begin{cases} 1 & \text{if } n < N \\ \beta \cdot N & \text{if } n = N \end{cases}$

$$\phi(n, N) = \frac{\beta}{\beta-1} (\beta n - N + N_0)$$

Amortized cost a_i :

Case 1 ($n < N$): $a_i = 1 + \frac{\beta^2}{\beta-1} (n+1 - n) = 1 + \frac{\beta^2}{\beta-1}$

Case 2 ($n = N$):

$$a_i = \beta N + \left[\frac{\beta}{\beta-1} (\beta(N+1) - \beta N) - \frac{\beta}{\beta-1} (\beta N - N) \right] = \frac{\beta^2}{\beta-1}$$

$$\frac{\beta^2}{\beta-1} - \frac{\beta}{\beta-1} (\beta-1) \cdot N$$

$\underbrace{\hspace{10em}}_{\beta N}$

amortized cost:

$$\leq 1 + \frac{\beta^2}{\beta-1}$$