



Chapter 1

Divide and Conquer

Algorithm Theory
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Polynomials

Real polynomial p in one variable x :

- **Coefficient representation:** Polynomial $p(x) \in \mathbb{R}[x]$ of degree $n - 1$ is given by n coefficients:

$$p(x) = a_{n-1}x^{n-1} + \dots + a_1x^1 + a_0$$

- Coefficients of p : $a_0, a_1, \dots, a_n \in \mathbb{R}$
 - **Degree** of p : largest power of x in p ($n - 1$ in the above case)
- **Point-value representation:** Polynomial $p(x) \in \mathbb{R}[x]$ of degree $n - 1$ is given by $\geq n$ point-value pairs:

$$p = \{(x_0, p(x_0)), (\underline{x_1}, \underline{p(x_1)}), \dots, (x_{n-1}, p(x_{n-1}))\}$$

where $x_i \neq x_j$ for $i \neq j$

Operations on Polynomials

Cost depending on representation:

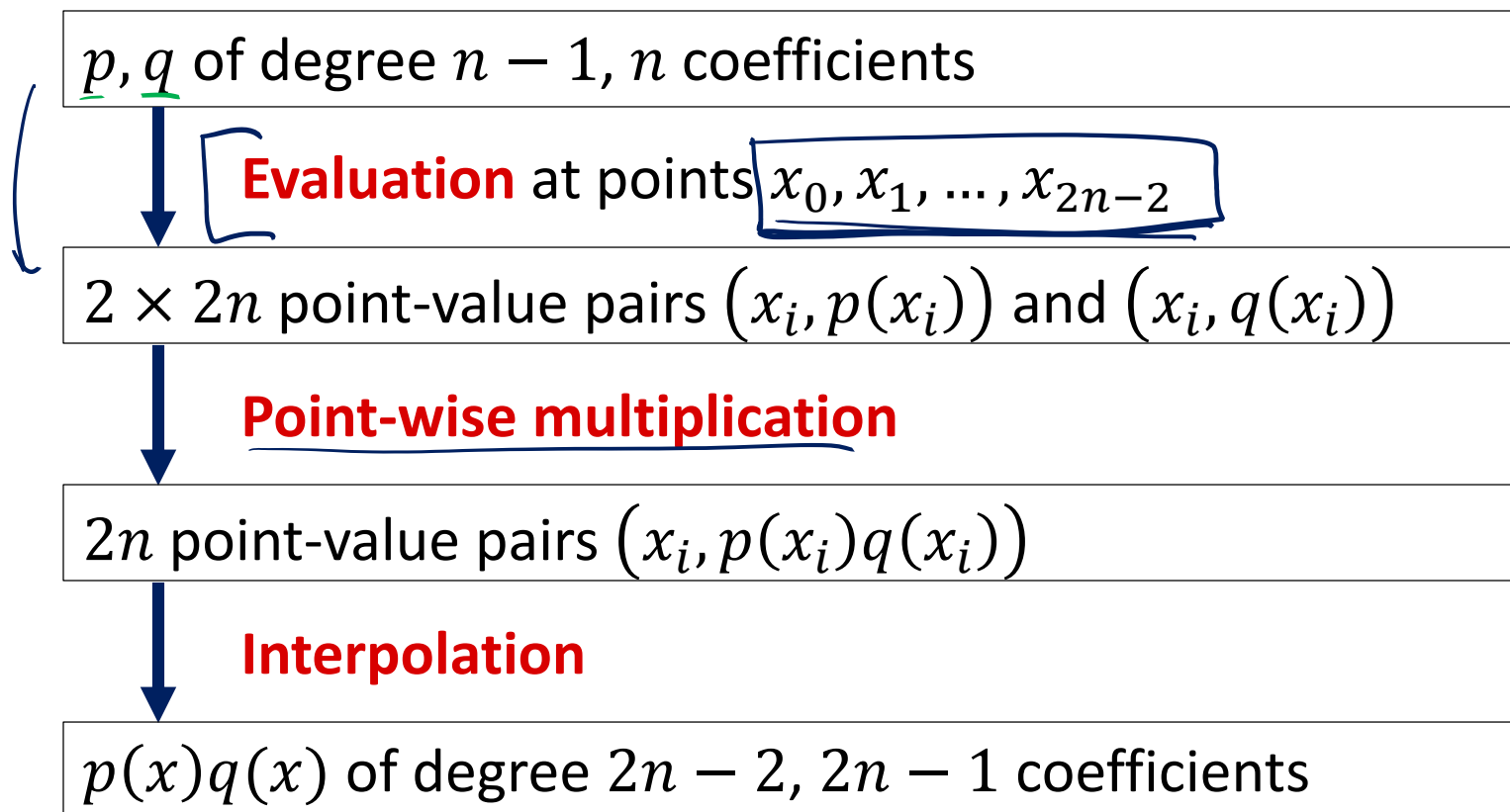
	Coefficient	Roots	Point-Value
Evaluation	<u>$O(n)$</u>	$O(n)$	$O(n^2)$
Addition	<u>$O(n)$</u>	∞	$O(n)$
Multiplication	<u>$O(n^{1.58})$</u>	$O(n)$	$O(n)$



Faster Polynomial Multiplication?

Multiplication is fast when using the **point-value representation**

Idea to compute $p(x) \cdot q(x)$ (for polynomials of degree $< n$):



Coefficients to Point-Value Representation



N is a power of 2

Goal: Compute $p(x)$ for all x in a given set X of size $|X| = \underline{N}$

- Divide $p(x)$ of degr. $N - 1$ into 2 polynomials of degr. $N/2 - 1$

$$\rightarrow p_0(y) = \underline{a_0} + \underline{a_2}y + \underline{a_4}y^2 + \dots + \underline{a_{N-2}}y^{N/2-1} \quad (\text{even coeff.})$$

$$\rightarrow p_1(y) = \underline{a_1} + \underline{a_3}y + \underline{a_5}y^2 + \dots + \underline{a_{N-1}}y^{N/2-1} \quad (\text{odd coeff.})$$

Let's first look at the "combine" step:

X = {ω_Nⁱ}

$$\underline{\forall x \in X} : \underline{p(x)} = \underline{p_0(x^2)} + \underline{x \cdot p_1(x^2)}$$

- Recursively compute $p_0(y)$ and $p_1(y)$ for all $y \in X^2$
 - Where $X^2 := \{x^2 : x \in X\}$

- Generally, we have $|X^2| = |X|$

*it is possible to
get $|X^2| = \frac{|X|}{2}$*

Choice of X

- Select points x_0, x_1, \dots, x_{N-1} to evaluate p and q in a clever way

Consider the N complex roots of unity:

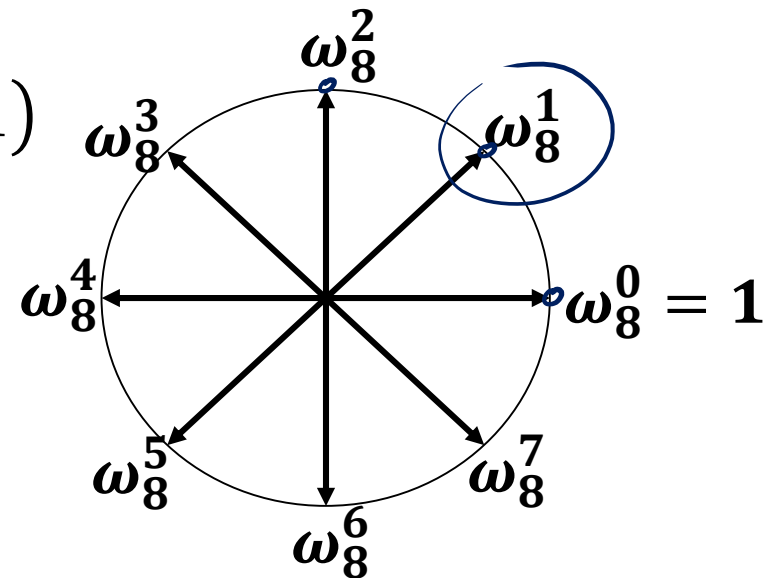


Principle root of unity: $\omega_N = e^{2\pi i/N}$

$$(i = \sqrt{-1}, \quad e^{2\pi i} = 1)$$

Powers of ω_N (roots of unity):

$$1 = \omega_N^0, \omega_N^1, \dots, \omega_N^{N-1}$$



Note: $\omega_N^k = e^{2\pi i k/N} = \cos \frac{2\pi k}{N} + i \cdot \sin \frac{2\pi k}{N}$

Properties of the Roots of Unity

Claim: If $X = \{\omega_{2k}^i : i \in \{0, \dots, 2k - 1\}\}$, we have

$$X^2 = \{\omega_k^i : i \in \{0, \dots, k - 1\}\}, \quad |X^2| = \frac{|X|}{2}$$

$$X, \quad |X^2| = \frac{|X|}{2}, \quad |X^4| = \frac{|X^2|}{2} = \frac{|X|}{4}$$

Faster Polynomial Multiplication?

Idea to compute $p(x) \cdot q(x)$ (for polynomials of degree $< n$):

p, q of degree $n - 1$, n coefficients

Evaluation at points $\omega_{2n}^0, \omega_{2n}^1, \dots, \omega_{2n}^{2n-1}$

$2 \times 2n$ point-value pairs $(\omega_{2n}^k, p(\omega_{2n}^k))$ and $(\omega_{2n}^k, q(\omega_{2n}^k))$

Point-wise multiplication

$2n$ point-value pairs $(\omega_{2n}^k, p(\omega_{2n}^k)q(\omega_{2n}^k))$

Interpolation

$p(x)q(x)$ of degree $2n - 2$, $2n - 1$ coefficients

Recursion

$$p(x) = \underbrace{p_0(x^2)}_{\uparrow} + x \cdot \underbrace{p_1(x^2)}_{\uparrow}$$

polynomial of size N , points X

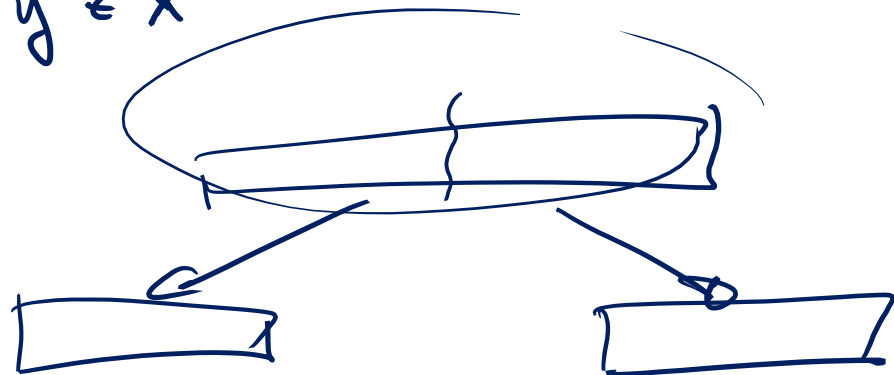
$$T(N, X) = 2 \cdot \underbrace{T\left(\frac{N}{2}, X^2\right)}_{\substack{\uparrow \\ \uparrow}} + O(N + |X|)$$

$$|X^2| = \frac{|X|}{2}$$

recursion solves

$p_0(y)$ for all $y \in X^2$

$p_1(y)$ for all $y \in X^2$



Discrete Fourier Transform

- The values $p(\omega_N^i)$ for $i = 0, \dots, N - 1$ uniquely define a polynomial p of degree $< N$.

Discrete Fourier Transform (DFT): \mathcal{P}

- Assume $a = (a_0, \dots, a_{N-1})$ is the coefficient vector of poly. p

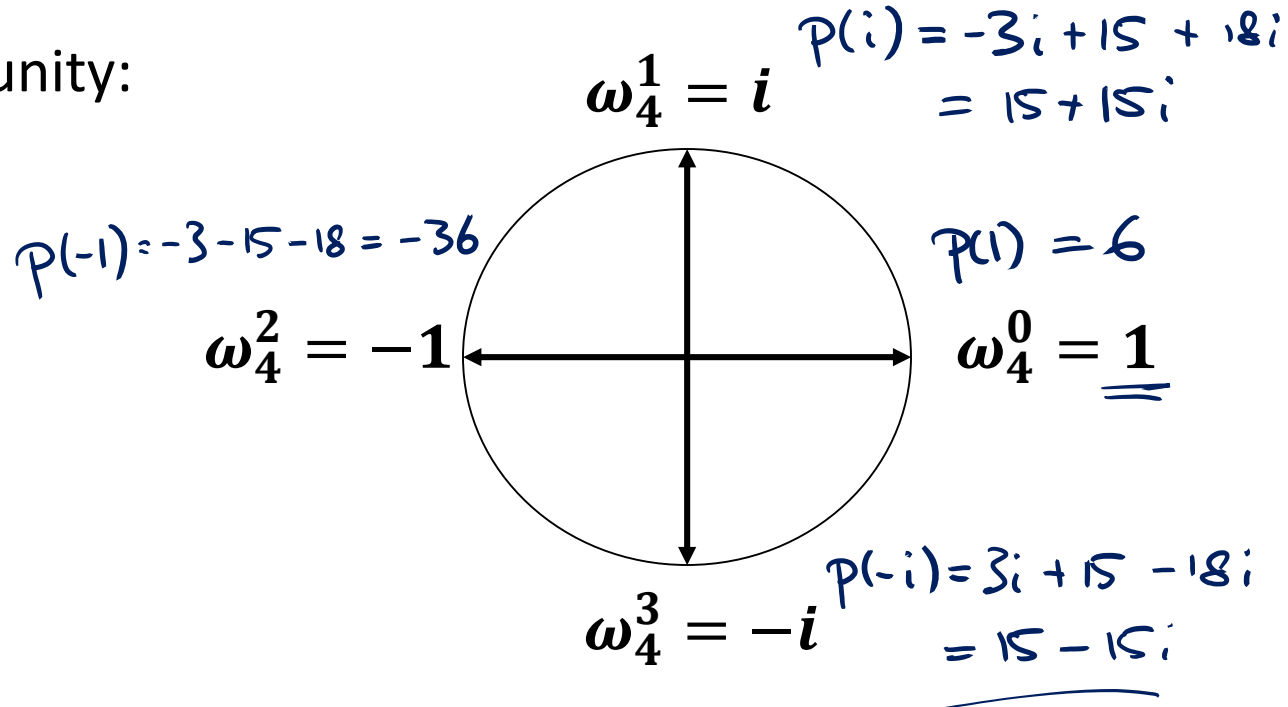
$$p(x) = a_{N-1}x^{N-1} + \dots + a_1x + a_0$$

$$\text{DFT}_N(a) := \left(p(\omega_N^0), p(\omega_N^1), \dots, p(\omega_N^{N-1}) \right)$$

Example

$$a = (0, 18, -15, 3)$$

- Consider polynomial $p(x) = \underline{3x^3 - 15x^2 + 18x}$
- Choose $\underline{N = 4}$
- Roots of unity:



Example

- Consider polynomial $p(x) = 3x^3 - 15x^2 + 18x$
- $N = 4$, roots of unity: $\omega_4^0 = 1, \omega_4^1 = i, \omega_4^2 = -1, \omega_4^3 = -i$
- Evaluate $p(x)$ at ω_4^k :

$$\left(\omega_4^0, p(\omega_4^0)\right) = (1, p(1)) = \underline{(1, 6)}$$

$$\left(\omega_4^1, p(\omega_4^1)\right) = (i, p(i)) = \underline{(i, 15 + 15i)}$$

$$\left(\omega_4^2, p(\omega_4^2)\right) = (-1, p(-1)) = \underline{(-1, -36)}$$

$$\left(\omega_4^3, p(\omega_4^3)\right) = (-i, p(-i)) = \underline{(-i, 15 - 15i)}$$

- For $a = \underline{(0, 18, -15, 3)}$:

$$\underline{\text{DFT}_4(a)} = \underline{(6, 15 + 15i, -36, 15 - 15i)}$$

DFT: Recursive Structure

$$p(x) = p_0(x^2) + x p_1(x^2)$$

Evaluation for $k = 0, \dots, N - 1$:

$$(\omega_N^k)^2 = \omega_N^{2k} = \omega_{N/2}^k$$

$$\begin{aligned} \underline{p(\omega_N^k)} &= p_0(\underline{(\omega_N^k)^2}) + \omega_N^k \cdot p_1(\underline{(\omega_N^k)^2}) \\ &= \begin{cases} \underline{p_0(\omega_{N/2}^k)} + \omega_N^k \cdot \underline{p_1(\omega_{N/2}^k)} & \text{if } k < N/2 \\ \underline{p_0(\omega_{N/2}^{k-N/2})} + \omega_N^k \cdot \underline{p_1(\omega_{N/2}^{k-N/2})} & \text{if } k \geq N/2 \end{cases} \end{aligned}$$

For the coefficient vector a of $p(x)$:

$$\begin{aligned} \underline{\text{DFT}_N(a)} &= \left(\underline{p_0(\omega_{N/2}^0)}, \dots, \underline{p_0(\omega_{N/2}^{N/2-1})}, p_0(\omega_{N/2}^0), \dots, p_0(\omega_{N/2}^{N/2-1}) \right) \\ &+ \left(\omega_N^0 p_1(\omega_{N/2}^0), \dots, \omega_N^{N/2-1} p_1(\omega_{N/2}^{N/2-1}), \omega_N^{N/2} p_1(\omega_{N/2}^0), \dots, \omega_N^{N-1} p_1(\omega_{N/2}^{N/2-1}) \right) \end{aligned}$$

$$p_0(\omega_{N/2}^k), p_1(\omega_{N/2}^k)$$

Example

For the coefficient vector a of $p(x)$:

$$\begin{aligned} \text{DFT}_N(a) = & \left(p_0(\omega_{N/2}^0), \dots, p_0(\omega_{N/2}^{N/2-1}), p_0(\omega_{N/2}^0), \dots, p_0(\omega_{N/2}^{N/2-1}) \right) \\ & + \left(\omega_N^0 p_1(\omega_{N/2}^0), \dots, \omega_N^{N/2-1} p_1(\omega_{N/2}^{N/2-1}), \omega_N^{N/2} p_1(\omega_{N/2}^0), \dots, \omega_N^{N-1} p_1(\omega_{N/2}^{N/2-1}) \right) \end{aligned}$$

$N = 4$:

$$\begin{aligned} \leftarrow p(\omega_4^0) &= p_0(\omega_2^0) + \omega_4^0 p_1(\omega_2^0) \leftarrow \\ p(\omega_4^1) &= p_0(\omega_2^1) + \omega_4^1 p_1(\omega_2^1) \\ p(\omega_4^2) &= p_0(\omega_2^0) + \omega_4^2 p_1(\omega_2^0) \\ p(\omega_4^3) &= p_0(\omega_2^1) + \omega_4^3 p_1(\omega_2^1) \end{aligned}$$

Need: $\left(p_0(\omega_2^0), p_0(\omega_2^1) \right)$ and $\left(p_1(\omega_2^0), p_1(\omega_2^1) \right)$

(DFTs of coefficient vectors of p_0 and p_1)

Summary: Computation of DFT_N

- Divide-and-conquer algorithm for $\text{DFT}_N(p)$:

1. Divide

→ $N \leq 1$: $\text{DFT}_1(p) = a_0$

→ $N > 1$: Divide p into p_0 (even coeff.) and p_1 (odd coeff.).

2. Conquer

Solve $\text{DFT}_{N/2}(p_0)$ and $\text{DFT}_{N/2}(p_1)$ recursively

3. Combine

Compute $\text{DFT}_N(p)$ based on $\text{DFT}_{N/2}(p_0)$ and $\text{DFT}_{N/2}(p_1)$

Small Improvement

Polynomial p of degree $N - 1$:

$$\begin{aligned}
 p(\omega_N^k) &= \left\{ \begin{array}{l} p_0(\omega_{N/2}^k) + \omega_N^k \cdot p_1(\omega_{N/2}^k) \\ p_0(\omega_{N/2}^{k-N/2}) + \omega_N^k \cdot p_1(\omega_{N/2}^{k-N/2}) \end{array} \right\} \begin{array}{l} \text{if } k < N/2 \\ \text{if } k \geq N/2 \end{array} \\
 &= \left\{ \begin{array}{l} p_0(\omega_{N/2}^k) + \omega_N^k \cdot p_1(\omega_{N/2}^k) \\ p_0(\omega_{N/2}^{k-N/2}) - \omega_N^{k-N/2} \cdot p_1(\omega_{N/2}^{k-N/2}) \end{array} \right\} \begin{array}{l} \text{if } k < N/2 \\ \text{if } k \geq N/2 \end{array}
 \end{aligned}$$

Need to compute $p_0(\omega_{N/2}^k)$ and $\omega_N^k \cdot p_1(\omega_{N/2}^k)$ for $0 \leq k < N/2$.

Example $N = 8$

$$p(\omega_8^0) = \underline{p_0(\omega_4^0)} + \underline{\omega_8^0 \cdot p_1(\omega_4^0)}$$

$$p(\omega_8^1) = p_0(\omega_4^1) + \omega_8^1 \cdot p_1(\omega_4^1)$$

$$p(\omega_8^2) = p_0(\omega_4^2) + \omega_8^2 \cdot p_1(\omega_4^2)$$

$$p(\omega_8^3) = p_0(\omega_4^3) + \omega_8^3 \cdot p_1(\omega_4^3)$$

$$p(\omega_8^3) = p_0(\omega_4^0) - \underline{\underline{\omega_8^0 \cdot p_1(\omega_4^0)}}$$

$$p(\omega_8^3) = p_0(\omega_4^1) - \omega_8^1 \cdot p_1(\omega_4^1)$$

$$p(\omega_8^3) = p_0(\omega_4^2) - \omega_8^2 \cdot p_1(\omega_4^2)$$

$$p(\omega_8^3) = p_0(\omega_4^3) - \omega_8^3 \cdot p_1(\omega_4^3)$$

Fast Fourier Transform (FFT) Algorithm

Algorithm FFT(a)

- Input: Array a of length N , where N is a power of 2
- Output: $\text{DFT}_N(a)$

if $n = 1$ **then return** a_0 ; // $a = [a_0]$

$d^{[0]} := \text{FFT}([a_0, a_2, \dots, a_{N-2}]);$

$d^{[1]} := \text{FFT}([a_1, a_3, \dots, a_{N-1}]);$

$\omega_N := e^{2\pi i/N}$; $\omega := 1$;

for $k = 0$ **to** $N/2 - 1$ **do** // $\omega = \omega_N^k$

$x := \omega \cdot d_k^{[1]}$;

$d_k := d_k^{[0]} + x$; $d_{k+N/2} := d_k^{[0]} - x$;

$\omega := \omega \cdot \omega_N$

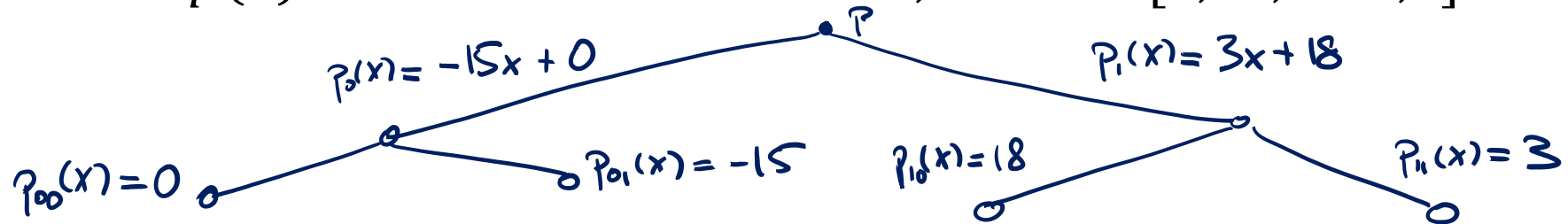
end;

return $d = [d_0, d_1, \dots, d_{N-1}]$;

Example

$$p(x) = 3x^3 - 15x^2 + 18x + 0,$$

$$a = [0, 18, -15, 3]$$



$$\begin{aligned}
 P_0(\omega_2^0) &= P_{00}(\omega_1^0) + \omega_2^0 \cdot P_{01}(\omega_1^0) = 0 + 1 \cdot (-15) = -15 & P_P(\omega_2^0) &= P_{10}(\omega_1^0) + \omega_2^0 \cdot P_{11}(\omega_1^0) = 21 \\
 P_0(\omega_2^1) &= P_{00}(\omega_1^0) - \omega_2^0 \cdot P_{01}(\omega_1^0) = 15 & P_P(\omega_2^1) &= P_{10}(\omega_1^0) - \omega_2^0 \cdot P_{11}(\omega_1^0) = 15
 \end{aligned}$$

$$P(\omega_4^0) = P_0(\omega_2^0) + \omega_4^0 \cdot P_1(\omega_2^0) = -15 + 1 \cdot 21 = 6$$

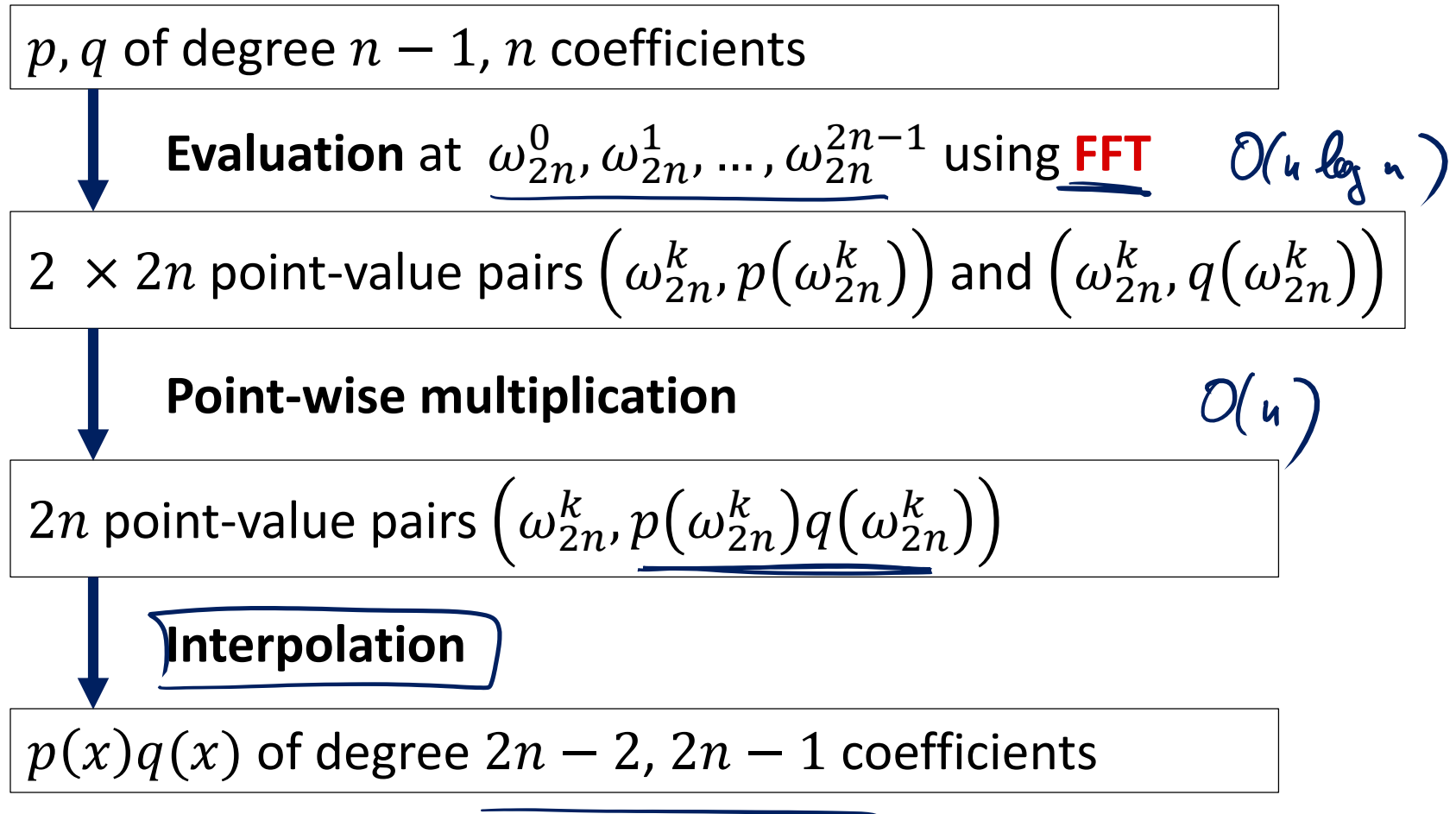
$$P(\omega_4^1) = P_0(\omega_2^1) + \omega_4^1 \cdot P_1(\omega_2^1) = 15 + i \cdot 15$$

$$P(\omega_4^2) = P_0(\omega_2^0) - \omega_4^0 \cdot P_1(\omega_2^0) = -15 - 21 = -36$$

$$P(\omega_4^3) = P_0(\omega_2^1) - \omega_4^1 \cdot P_1(\omega_2^1) = 15 - 15i$$

Faster Polynomial Multiplication?

Idea to compute $p(x) \cdot q(x)$ (for polynomials of degree $< n$):



Interpolation

Convert point-value representation into coefficient representation

Input: $(\underline{x_0}, y_0), \dots, (\underline{x_{n-1}}, y_{n-1})$ with $x_i \neq x_j$ for $i \neq j$

Output:

Degree- $(n - 1)$ polynomial with coefficients $[a_0, \dots, a_{n-1}]$ such that

$$\begin{aligned}
 \rightarrow p(x_0) &= a_0 + a_1 x_0 + a_2 x_0^2 + \dots + a_{n-1} x_0^{n-1} = y_0 \leftarrow \\
 p(x_1) &= a_0 + a_1 x_1 + a_2 x_1^2 + \dots + a_{n-1} x_1^{n-1} = y_1 \leftarrow \\
 &\vdots \\
 p(x_{n-1}) &= a_0 + a_1 x_{n-1} + a_2 x_{n-1}^2 + \dots + a_{n-1} x_{n-1}^{n-1} = y_{n-1} \leftarrow
 \end{aligned}$$

\rightarrow linear system of equations for a_0, \dots, a_{n-1}

Interpolation

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Matrix Notation:

$$\begin{pmatrix} 1 & x_0 & \dots & x_0^{n-1} \\ 1 & x_1 & \dots & x_1^{n-1} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_{n-1} & \dots & x_{n-1}^{n-1} \end{pmatrix} \cdot \begin{pmatrix} a_0 \\ a_1 \\ \vdots \\ a_{n-1} \end{pmatrix} = \begin{pmatrix} y_0 \\ y_1 \\ \vdots \\ y_{n-1} \end{pmatrix}$$

- System of equations solvable iff $x_i \neq x_j$ for all $i \neq j$

Special Case $x_i = \omega_n^i$:

$$\begin{pmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & \omega_n & \omega_n^2 & \dots & \omega_n^{n-1} \\ 1 & \omega_n^2 & \omega_n^4 & \dots & \omega_n^{2(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega_n^{n-1} & \omega_n^{2(n-1)} & \dots & \omega_n^{(n-1)(n-1)} \end{pmatrix} \cdot \begin{pmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_{n-1} \end{pmatrix} = \begin{pmatrix} y_0 \\ y_1 \\ y_2 \\ \vdots \\ y_{n-1} \end{pmatrix}$$

Interpolation

$$X_i^j = \omega_n^{ij}$$

- Linear system:

$$\underline{W \cdot \mathbf{a} = \mathbf{y}} \quad \Rightarrow \quad \underline{\mathbf{a} = W^{-1} \cdot \mathbf{y}}$$

$$\underline{W_{i,j} = \omega_n^{ij}}, \quad \mathbf{a} = \begin{pmatrix} a_0 \\ \vdots \\ a_{n-1} \end{pmatrix}, \quad \mathbf{y} = \begin{pmatrix} y_0 \\ \vdots \\ y_{n-1} \end{pmatrix}$$

Claim:

$$W_{ij}^{-1} = \frac{\omega_n^{-ij}}{n}$$

Proof: Need to show that $\underline{W^{-1}W} = \underline{I_n}$

DFT Matrix Inverse

$$W^{-1}W = \begin{pmatrix} \frac{1}{n} & \frac{\omega_n^{-i}}{n} & \dots & \frac{\omega_n^{-(n-1)i}}{n} \\ \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots \end{pmatrix} \cdot \begin{pmatrix} \dots & 1 & \dots \\ \dots & \omega_n^j & \dots \\ \dots & \omega_n^{2j} & \dots \\ \dots & \vdots & \dots \\ \dots & \omega_n^{(n-1)j} & \dots \end{pmatrix}$$

$$(W^{-1}W)_{ij} = \frac{1}{n} \cdot \sum_{l=0}^{n-1} \omega_n^{-i \cdot l} \cdot \omega_n^{j \cdot l} = \frac{1}{n} \cdot \sum_{l=0}^{n-1} \omega_n^{l(j-i)}$$

we need $(W^{-1}W)_{ij} = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$

DFT Matrix Inverse

$$(W^{-1}W)_{i,j} = \sum_{\ell=0}^{n-1} \frac{\omega_n^{\ell(j-i)}}{n}$$

Need to show $(W^{-1}W)_{i,j} = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$

Case $i = j$:

$$(W^{-1}W)_{i,i} = \frac{1}{n} \cdot \sum_{\ell=0}^{n-1} \underbrace{\omega_n^0}_{=1} = \frac{1}{n} \cdot n = 1$$

DFT Matrix Inverse

$$(W^{-1}W)_{i,j} = \sum_{\ell=0}^{n-1} \frac{\omega_n^{\ell(j-i)}}{n}$$

Case $i \neq j$:

$$(W^{-1}W)_{i,j} = \frac{1}{n} \underbrace{\sum_{\ell=0}^{n-1} (\omega_n^{j-i})^{\ell}}_{\text{geometric series}} = \frac{1}{n} \cdot \frac{1 - (\omega_n^{j-i})^n}{1 - \underbrace{\omega_n^{j-i}}_{\neq 1}} = 0$$

$= \omega_n^{(j-i) \cdot n} = \omega_n^0 = 1$

$$\sum_{\ell=0}^{n-1} q^{\ell} = \frac{1 - q^n}{1 - q}$$

Inverse DFT

- $$W^{-1} = \begin{pmatrix} \frac{1}{n} & \frac{\omega_n^{-k}}{n} & \dots & \frac{\omega_n^{-(n-1)k}}{n} \\ \vdots & \vdots & \ddots & \vdots \\ \dots & \dots & \dots & \dots \end{pmatrix} \quad (W^{-1})_{i,j} = \frac{\omega_n^{-ij}}{n}$$

- We get \mathbf{a} = W^{-1} · \mathbf{y} and therefore

$$\underline{a_k} = \begin{pmatrix} \frac{1}{n} & \frac{\omega_n^{-k}}{n} & \dots & \frac{\omega_n^{-(n-1)k}}{n} \end{pmatrix} \cdot \begin{pmatrix} y_0 \\ y_1 \\ \vdots \\ y_{n-1} \end{pmatrix}$$

$$= \frac{1}{n} \cdot \sum_{j=0}^{n-1} \omega_n^{-kj} \cdot y_j = \frac{1}{n} \cdot \sum_{j=0}^{n-1} \underline{y_j} \cdot (\omega_n^{-k})^j$$

DFT and Inverse DFT

Inverse DFT:

$$a_k = \frac{1}{n} \cdot \sum_{j=0}^{n-1} \omega_n^{-kj} \cdot y_j$$

- Define polynomial $q(x) = \underline{y_0 + y_1z + \dots + y_{n-1}z^{n-1}}$:

$$\underline{a_k} = \frac{1}{n} \cdot \underline{q(\omega_n^{-k})}$$

DFT:

- Polynomial $p(x) = a_0 + a_1x + \dots + a_{n-1}x^{n-1}$:

$$\underline{y_k} = \underline{p(\omega_n^k)}$$

DFT and Inverse DFT

$$q(x) = y_0 + y_1x + \dots + y_{n-1}x^{n-1}, \quad a_k = \frac{1}{n} \cdot q(\omega_n^{-k}):$$

- Therefore:

$$\begin{aligned} & \underline{(a_0, a_1, \dots, a_{n-1})} \\ &= \frac{1}{n} \cdot \left(\underline{q(\omega_n^{-0}), q(\omega_n^{-1}), q(\omega_n^{-2}), \dots, q(\omega_n^{-(n-1)})} \right) \\ &= \frac{1}{n} \cdot \left(\underline{q(\omega_n^0), q(\omega_n^{n-1}), q(\omega_n^{n-2}), \dots, q(\omega_n^1)} \right) \end{aligned}$$

- Recall:

$$\begin{aligned} \underline{\text{DFT}_n(\mathbf{y})} &= \underline{(q(\omega_n^0), q(\omega_n^1), q(\omega_n^2), \dots, q(\omega_n^{n-1}))} \\ &= \underline{n \cdot (a_0, a_{n-1}, a_{n-2}, \dots, a_2, a_1)} \end{aligned}$$

DFT and Inverse DFT

- We have $\text{DFT}_n(\mathbf{y}) = n \cdot (a_0, a_{n-1}, a_{n-2}, \dots, a_2, a_1)$:

$$\underline{a_i} = \begin{cases} \frac{1}{n} \cdot \underline{(\text{DFT}_n(\mathbf{y}))_0} & \text{if } i = 0 \\ \frac{1}{n} \cdot \underline{(\text{DFT}_n(\mathbf{y}))_{n-i}} & \text{if } i \neq 0 \end{cases}$$

- DFT and inverse DFT can both be computed using FFT algorithm in $O(n \log n)$ time.
- 2 polynomials of $\text{degr.} < n$ can be multiplied in time $O(\underline{n \log n})$.

Faster Polynomial Multiplication?

Idea to compute $p(x) \cdot q(x)$ (for polynomials of degree $< n$):

p, q of degree $n - 1$, n coefficients



Evaluation at $\omega_{2n}^0, \omega_{2n}^1, \dots, \omega_{2n}^{2n-1}$ using **FFT** $\mathcal{O}(n \log n)$

$2 \times 2n$ point-value pairs $(\omega_{2n}^k, p(\omega_{2n}^k))$ and $(\omega_{2n}^k, q(\omega_{2n}^k))$



Point-wise multiplication $\mathcal{O}(n)$

$2n$ point-value pairs $(\omega_{2n}^k, p(\omega_{2n}^k)q(\omega_{2n}^k))$



Interpolation using **FFT** $\mathcal{O}(n \log n)$

$p(x)q(x)$ of degree $2n - 2$, $2n - 1$ coefficients

Convolution

- More generally, the polynomial multiplication algorithm computes the convolution of two vectors:

$$\mathbf{a} = (a_0, a_1, \dots, a_{m-1})$$

$$\mathbf{b} = (b_0, b_1, \dots, b_{n-1})$$

$$\mathbf{a} * \mathbf{b} = (\underline{c_0, c_1, \dots, c_{m+n-2}})$$

$$\text{where } \underline{c_k} = \sum_{\substack{(i,j): i+j=k \\ i < m, j < n}} \underline{a_i b_j}$$

- c_k is exactly the coefficient of x^k in the product polynomial of the polynomials defined by the coefficient vectors \mathbf{a} and \mathbf{b}

More Applications of Convolutions

Signal Processing Example:

$$\alpha(m \cdot n)$$

- Assume $\mathbf{a} = (a_0, \dots, a_{n-1})$ represents a sequence of measurements over time
- Measurements might be noisy and have to be smoothed out
- Replace a_i by weighted average of nearby last m and next m measurements (e.g., Gaussian smoothing):

$$\underline{a'_i} = \frac{1}{Z} \cdot \sum_{j=i-m}^{i+m} a_j \underbrace{e^{-(i-j)^2}}_{\uparrow}$$



- New vector \mathbf{a}' is the convolution of \mathbf{a} and the weight vector $\frac{1}{Z} \cdot (e^{-m^2}, e^{-(m-1)^2}, \dots, e^{-1}, 1, e^{-1}, \dots, e^{-(m-1)^2}, e^{-m^2})$
- Might need to take care of boundary points...

More Applications of Convolutions

Combining Histograms:

- Vectors \mathbf{a} and \mathbf{b} represent two histograms
- E.g., annual income of all men & annual income of all women
- Goal: Get new histogram \mathbf{c} representing combined income of all possible pairs of men and women:

$$\mathbf{c} = \mathbf{a} * \mathbf{b}$$

Also, the DFT (and thus the FFT alg.) has many other applications!

DFT in Signal Processing

Assume that $y(0), y(1), y(2), \dots, y(T - 1)$ are measurements of a time-dependent signal.

Inverse DFT_N of $(y(0), \dots, y(T - 1))$ is a vector (c_0, \dots, c_{N-1}) s.t.

$$\begin{aligned}
 \underline{y(t)} &= \sum_{k=0}^{N-1} \underline{c_k} \cdot \underline{e^{\frac{2\pi i \cdot k}{N} \cdot t}} \\
 &= \sum_{k=0}^{T-1} \underline{c_k} \cdot \left(\underline{\cos\left(\frac{2\pi \cdot k}{N} \cdot t\right)} + i \underline{\sin\left(\frac{2\pi \cdot k}{N} \cdot t\right)} \right)
 \end{aligned}$$

$e^{i\varphi} = \cos\varphi + i\sin\varphi$

- Converts signal from time domain to frequency domain
- Signal can then be edited in the frequency domain
 - e.g., setting some $c_k = 0$ filters out some frequencies