



Algorithms Theory

14 – Dynamic Programming (1)

Very helpful and powerful algorithm design technique.

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Outline



- General approach, differences to a recursive solution
Dynamic Programming = Recursion + Storing computed subproblem-solutions
- Basic example: Computation of the Fibonacci numbers

Method of dynamic programming

Recursive approach: Solve a problem by solving several smaller analogous subproblems of the same type. Then combine these solutions to generate a solution to the original problem.

Drawback: Repeated computation of solutions

Dynamic-programming method: Once a subproblem has been solved, store its solution in a table so that it can be retrieved later by simple table lookup.

Example: Fibonacci numbers

$$f(0) = 0 \quad \checkmark$$

$$f(1) = 1 \quad \checkmark$$

$$f(n) = f(n-1) + f(n-2), \text{ for } n \geq 2 \quad \checkmark$$

Remark:

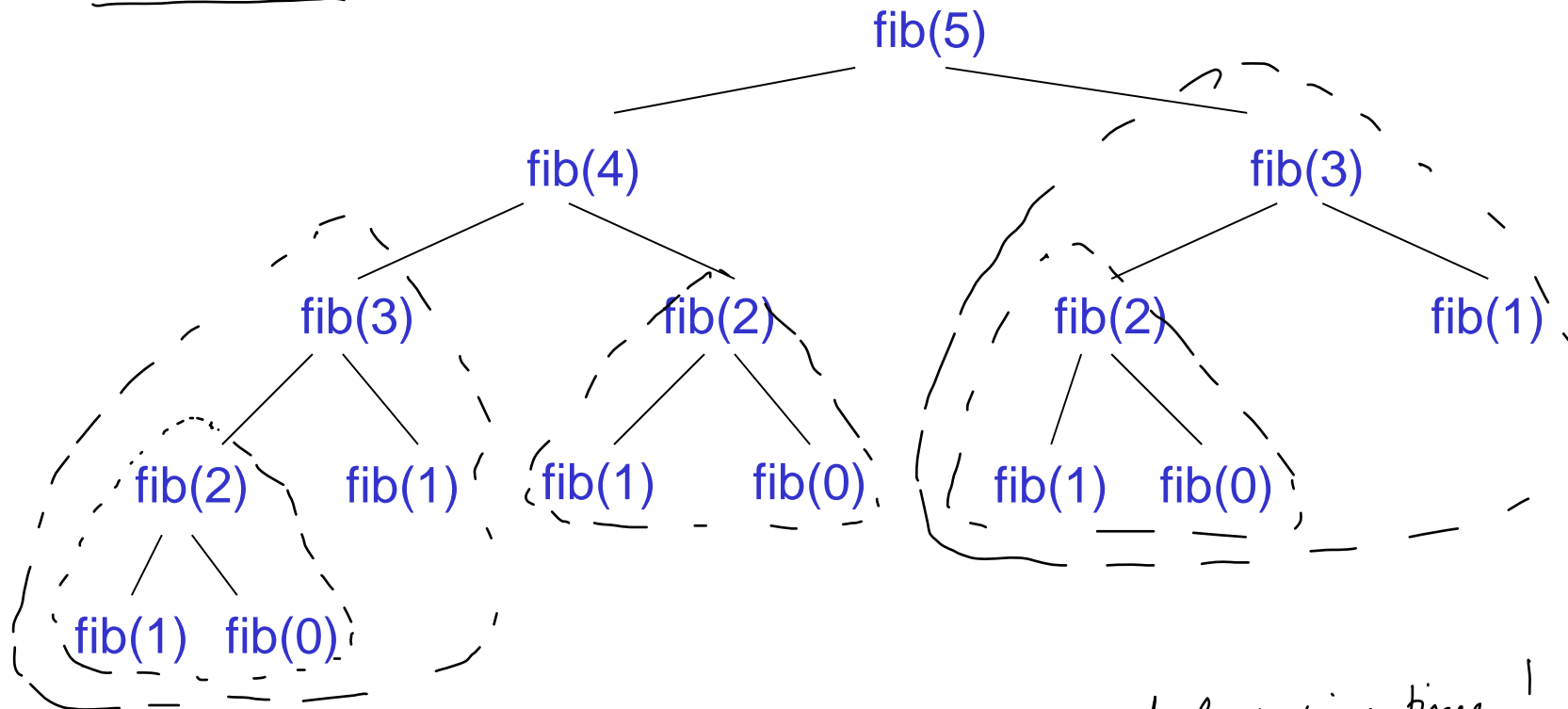
$$f(n) = \left[\frac{1}{\sqrt{5}} (1.618\dots)^n \right]$$

Straightforward implementation:

```
procedure fib (n : integer) : integer  
if (n == 0) or (n == 1)  
  then return n  
  else return fib(n - 1) + fib(n - 2)
```

Example: Fibonacci numbers

Recursion tree:



Repeated computation!

exponential running time!

$$T(n) \approx \left[\left(1 + \frac{1}{\sqrt{5}} \right) \left(\frac{\sqrt{5} + 1}{2} \right)^n - 1 \right] \approx [1.447 \times 1.618^n - 1]$$

Dynamic programming

Approach:

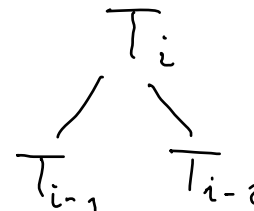
1. Recursively define problem P .
2. Determine a set T consisting of all subproblems that have to be solved during the computation of a solution to P .
$$T = \{ T_0, \dots, T_k \}$$
3. Find an order T_0, \dots, T_k of the subproblems in T such that during the computation of a solution to T_i only subproblems T_j with $j < i$ arise.
4. Solve T_0, \dots, T_k in this order and store the solutions.

Example: Fibonacci numbers

1. Recursive definition of the Fibonacci numbers, based on the standard equation. $f(n)$

2. $T = \{f(0), \dots, f(n-1)\}$

3. $T_i \equiv f(i), \quad i = 0, \dots, n-1$



4. Computation of $fib(i)$, for $i \geq 2$, only requires the results of the last two subproblems $fib(i-1)$ and $fib(i-2)$.

Example: Fibonacci numbers

Computation by dynamic programming, version 1:

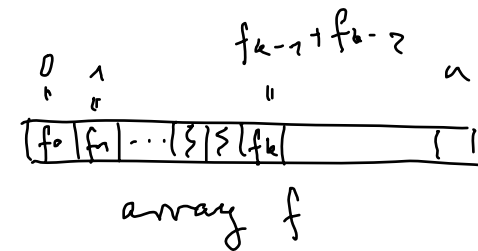
procedure *fib*(*n* : integer) : integer

- 1 $f_0 := 0; f_1 := 1$
- 2 **for** $k := 2$ **to** n **do**
- 3 $f_k := f_{k-1} + f_{k-2}$
- 4 **return** f_n

Running time $O(n)$

Space $O(n)$

Bottom-up



Example: Fibonacci numbers

Computation by dynamic programming, version 2:

```
procedure fib (n : integer) : integer  
1   $f_{secondlast} := 0; f_{last} := 1$   
2  for  $k := 2$  to  $n$  do  
3       $f_{current} := f_{last} + f_{secondlast}$   
4       $f_{secondlast} := f_{last}$   
5       $f_{last} := f_{current}$   
6  if  $n \leq 1$  then return  $n$  else return  $f_{current}$  ;
```

Linear running time, constant space requirement!

Computing Fibonacci numbers with memoization



Recursive approach where we

Compute each number exactly once, store it in an array $F[0...n]$:

procedure *fib* ($n : \text{integer}$) : *integer*

1 $F[0] := 0; F[1] := 1;$

2 **for** $i := 2$ **to** n **do**

3 $F[i] := \infty;$

4 **return** *lookupfib*(n)

$\infty \equiv$ number not yet computed

Top-Down approach

The procedure *lookupfib* is defined as follows:

procedure *lookupfib* ($k : \text{integer}$) : *integer*

1 **if** $F[k] < \infty$

2 **then** **return** $F[k]$

3 **else** $F[k] := \text{lookupfib}(k - 1) + \text{lookupfib}(k - 2);$

4 **return** $F[k]$