

Cut-Based Tree Decompositions

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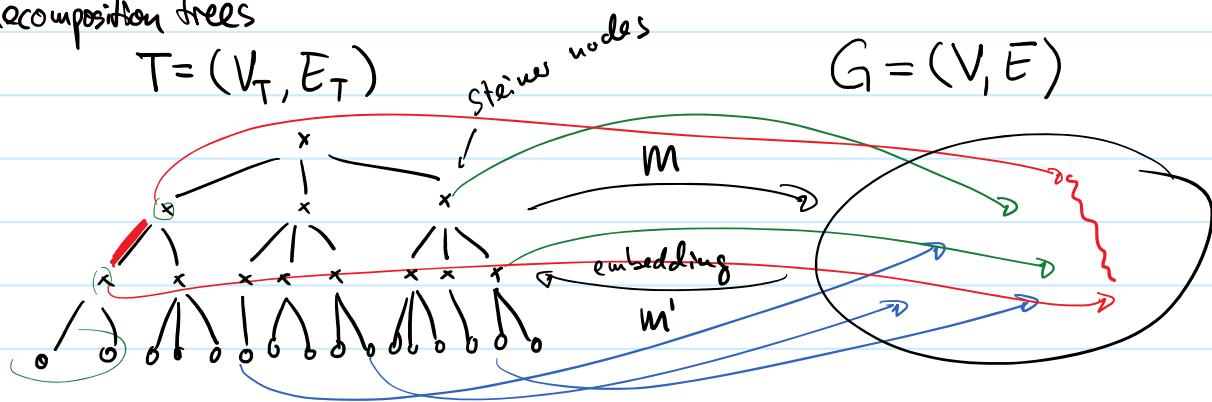
last week: distance-based tree decompositions [Räcke 2008]

decomposition trees

$$T = (V_T, E_T)$$

Steiner nodes

$$G = (V, E)$$



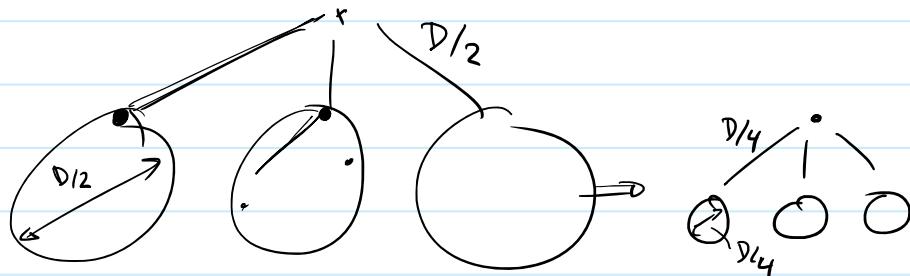
$$m_V : V_T \rightarrow V \quad (\text{one-to-one mapping between the leaves of } T \text{ and } V)$$

$$m_E : E_T \rightarrow 2^E \quad \text{for } \{u_t, v_t\} \in E_T \quad m_E(\{u_t, v_t\}) \rightarrow \text{shortest path between } m_V(u_t) \text{ and } m_V(v_t)$$

$$m'_V : V \rightarrow V_T \quad (\text{maps to leaves in one-to-one manner})$$

$$m'_E : E \rightarrow 2^{E_T} \quad \text{for } \{u, v\} \in E \quad m'_E(\{u, v\}) \rightarrow \text{unique path between } m'_V(u) \text{ and } m'_V(v)$$

from now on: $d_T(u_t, v_t)$: length of corresponding path in G



Mapping Multicommodity Flows

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Given $G = (V, E, c)$

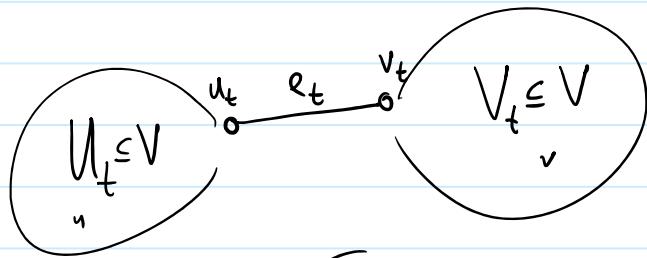
multicom. flow instance given by requirements $r(u, v)$ for $\{u, v\} \in \binom{V}{2}$

when solving a multicom. flow problem on T :

(requirements are only between leaves)

each comm. $\{u, v\}$ is routed on the unique path conn. the 2 leaves

Load of an edge $e \in E$ when mapping the flow from T to G



$$r(e_t) = \sum_{u \in U_t, v \in V_t} r(u, v)$$

$$\text{load}_T(e) := \sum_{\substack{e_t \in E_T : e \in \underbrace{E}_{\text{path repr. } e_t \text{ in } G}} r(e_t)}$$

ultimate goal:

for multicom. flow inst.,
find tree T

s.t. $\max_e \frac{\text{load}_T(e)}{c(e)}$ is minimized

The Minimum Communication Cost Tree (MCCT) Problem

undir. $G = (V, E, l)$ $l(e)$: length of e $l(e) \geq 0$ $d_G(u, v)$: length of shortest path

$\forall \{u, v\} \in \binom{V}{2}$: $r(u, v)$: amount of traffic that has to go between u & v
 requirement

Goal: Find decomp. tree T that minimizes

$$\text{cost}(T) = \sum_{\{u, v\} \in \binom{V}{2}} d_T(u, v) \cdot r(u, v) = \sum_{\{u, v\} \in \binom{V}{2}} d_G(u, v) \cdot r(u, v)$$

Lemma: MCCT can be $O(\log n)$ -approximated.

Proof: use random tree constn. from last lecture:

$$\mathbb{E}[\text{cost}(T)] = \mathbb{E}\left[\sum_{u, v} d_T(u, v) \cdot r(u, v)\right] = \sum_{u, v} r(u, v) \cdot \underbrace{\mathbb{E}[d_T(u, v)]}_{\substack{O(\log n) \cdot d_G(u, v) \\ (\text{last lecture})}} = O(\log n) \cdot \underbrace{\sum_{u, v} d_G(u, v) \cdot r(u, v)}_{\substack{\text{lower bnd. on} \\ \text{opt. cost}}}$$

MCCT Problem

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$$\text{cost}(T) = \sum_{u,v} d_T(u,v) \cdot r(u,v)$$

Alternative formulation of MCCT

Lemma:

$$\text{cost}(T) = \sum_{e \in E} \text{load}_T(e) \cdot l(e)$$

Proof: $\sum_{u,v} d_T(u,v) r(u,v) = \sum_{u,v} r(u,v) \cdot \sum_{e \in P_{uv}} \sum_{e \in M_E(e_t)} l(e)$

↑ path conn. u & v in T

$$= \sum_e l(e) \cdot \sum_{e_t: e \in M_E(e_t)} \sum_{\substack{u,v \text{ s.t.} \\ u,v \text{ are sep. in} \\ T \text{ by } e_t}} r(u,v)$$

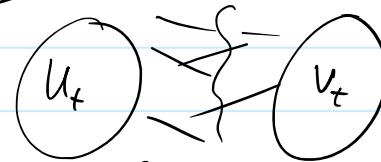
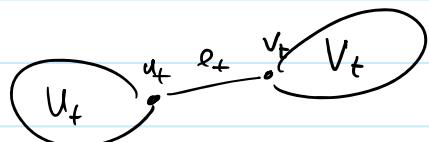
load_T(e)

Approximating Cuts/Bottlenecks of a Graph by a Tree

Given: $G = (V, E, c)$ & $T = (V_T, E_T)$

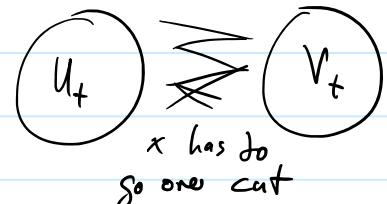
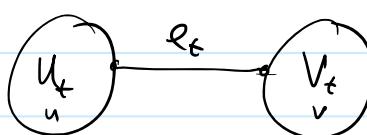
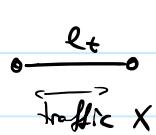
capacity of tree edge $\{u_t, v_t\} \in E_T$

$$\text{cap. } C_T(u_t, v_t) := \sum_{u \in U_t, v \in V_t} c(u, v)$$



$$C_T(u_t, v_t) = \text{total cap. over this cut}$$

Theorem: Given multicom. flow problem, let C_G be the opt. congestion on G and let C_T be the opt. cong. on T . Then, $C_T \leq C_G$.



Load on edge $e \in E$ for tree T

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Assume that each edge $e_t \in E_T$ is fully utilized
 $\hookrightarrow C_T(e_t)$ units of traffic on e_t

$$\text{load}_T(e) = \sum_{e_t \in E_T : e \in m_e(e_t)} C_T(e_t)$$

\hookrightarrow the same as when routing a multicom. flow with $\underline{f(u,v)} = C(u,v)$

$$r\text{load}_T(e) := \frac{1}{C(e)} \cdot \text{load}_T(e)$$

Goal: Find a distribution over trees T s.t. max (overall e) expected $r\text{load}_T(e)$ is minimized.

trees T_1, \dots, T_k and $0 \leq \lambda_1, \dots, \lambda_k \leq 1$ s.t. $\sum \lambda_i = 1$

$$\text{minimize } \underline{\beta} := \max_{e \in E} \left\{ \sum_{i=1}^k \lambda_i r\text{load}_{T_i}(e) \right\}$$

Claim: Given multicom. flow f_i for each T_i s.t. congestion on T_i is $\leq \underline{1}$

When mapping $\sum \lambda_i f_i$ to $G \rightarrow$ cong. on G is $\leq \underline{\beta}$

Proof: f_i uses each $e_t \in E_{T_i}$ at most to its cap. $C_{T_i}(e_t)$

f_i incurs load on $e \in G$ a load of at most $\lambda_i \cdot \text{load}_{T_i}(e)$

$$\text{total load on } e \underset{\text{rel.}}{\leq} \sum_{i=1}^k \lambda_i \text{load}_{T_i}(e) \overset{!}{\leq} \underline{\beta}$$

Why is this what we need?

Multicom. flow instance $\underline{f(u,v)}$, assume opt. cong. on G is C_G
 flow on $e \leq C_G \cdot c(e)$

We showed that for each T_i : opt. cong. on T_i is $C_T \leq C_G$

flow on T_i has cong. $\leq C_G$

Convex comb. of flows on T_i mapped to $G \rightarrow$ cong. $\leq \underline{\beta} \cdot C_G$ on G .

Finding a distribution on trees

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Goal: $\min \beta$

$$\text{s.t. } \forall e \in E : \sum_i \lambda_i \cdot \text{rload}_{T_i}(e) \leq \beta$$

$$\sum_i \lambda_i \geq 1$$

$$\lambda_i \geq 0$$

think of this as a distribution over all possible trees $T_i \in \mathcal{T}$

matrix formulation $|E| \times |\mathcal{T}|$ matrix M , $M_{e,T} = \text{rload}_T(e)$

$$\text{edge const. } M \cdot \vec{\lambda} \leq \beta \cdot \underline{1} \leftarrow \text{all-1-vector}$$

$\max(\vec{x})$: maximum component

$$\max(M\vec{\lambda}) \leq \beta$$

replace \max by a smooth approx.

$$\ln \max(\vec{x}) := \ln \left(\sum_{e \in E} e^{x_e} \right) \geq \max(\vec{x}) = \max_{e \in E} \{x_e\}$$

replace $\max(M\vec{\lambda}) \leq \beta$ by the stronger cond. $\boxed{\ln \max(M\vec{\lambda}) \leq \beta}$

Basic Idea

- start with $\lambda_1 = \lambda_2 = \dots = 0$, $\ln \max(M\vec{\lambda}) = O(\log n)$

- in each step, choose a tree T_i and $\delta_i > 0$ and update $\lambda_i := \lambda_i + \underline{\delta_i}$

$\ln \max(M\vec{\lambda})$ increases by at most $\underline{\delta_i} \cdot \beta$ (for $\beta = O(\log n)$)

- stop when $\sum \lambda_i \geq 1$

Implementing basic idea

need to understand how $\ln \max$ changes when some λ_i

What is $\ln \max(\vec{x} + \vec{\varepsilon}) \approx \ln \max(\vec{x}) + \vec{\varepsilon}^\top \nabla \ln \max(\vec{x}) = \ln \max(\vec{x}) + \sum_e \varepsilon_e \cdot \text{partial}_e(\vec{x})$

$$\text{partial}_e(\vec{x}) := \frac{\partial}{\partial x_e} \ln \max(\vec{x}) = \frac{e^{x_e}}{\sum_e e^{x_e}}$$

Lemma: For $\vec{\varepsilon}$ s.t. $\underline{\varepsilon}_e \in [0, 1]$ for all $e \in E$,

$$\ell_{\max}(\vec{x} + \vec{\varepsilon}) \leq \ell_{\max}(\vec{x}) + 2 \cdot \sum_{e \in E} \varepsilon_e \cdot \text{partial}'_e(\vec{x})$$

Assume, we set $\lambda_i = \lambda_i + \delta_i$ how does $\ell_{\max}(M\vec{\lambda})$ change

$$\ell_{\max}(M(\vec{\lambda} + \vec{\delta}))$$

$$\vec{\delta} = \begin{pmatrix} \delta_1 \\ \vdots \\ \delta_i \\ \vdots \\ \delta_n \end{pmatrix}$$

$$= \ell_{\max}(M\vec{\lambda} + M\vec{\delta}) \quad \checkmark \quad \underline{(M\vec{\delta})}_e \leq 1$$

$$\leq \underline{\ell_{\max}(M\vec{\lambda})} + 2 \sum_{e \in E} M_e \cdot \text{partial}'_e(M\vec{\lambda})$$

$$(M\vec{\delta})_e = \underline{\delta_i \cdot \text{load}_{T_i}(e)}$$

define

$$\underline{\delta_i := \frac{1}{\max_e \text{load}_{T_i}(e)}}$$

$$= \underline{\ell_{\max}(M\vec{\lambda})} + 2 \delta_i \cdot \sum_e \text{load}_{T_i}(e) \cdot \text{partial}'_e(M\vec{\lambda})$$

$$= \underline{\ell_{\max}(M\vec{\lambda})} + 2 \delta_i \cdot \sum_e \text{load}_{T_i}(e) \cdot \frac{e^{(M\vec{\lambda})_e}}{\sum_{e' \in T_i} e^{(M\vec{\lambda})_{e'}}}$$

find a tree that min. this
MCCT problem \leftarrow can find a T_i s.t. this whole thing is $\mathcal{O}(\log n)$

can compute sol. s.t. $\sum_e \text{load}_{T_i}(e) \cdot l(e) \leq \mathcal{O}(\log n) \cdot \sum_{e \in E} l(e) \cdot c(e)$

$$\sum_{e \in E} c(e) \cdot l(e) = \sum_{e \in E} c(e) \cdot \frac{e^{(M\vec{\lambda})_e}}{\sum_{e' \in T_i} e^{(M\vec{\lambda})_{e'}}} = 1$$

Termination / #iterations

Lemma: #iter = $\mathcal{O}(|E| \cdot \log n)$

$$\phi := \sum_e \sum_i \lambda_i \cdot \text{load}_{T_i}(e) \quad \rightarrow \text{we know } \phi = \mathcal{O}(|E| \cdot \log n) \text{ at all times}$$

potential diff. in one step:

$$\delta_i = \frac{1}{\max_e \text{load}_{T_i}(e)}$$

ϕ grows by ≥ 1 in each step.