



Algorithms and Datastructures

Summer Term 2022

Sample Solution Exercise Sheet 6

Due: Wednesday, June 15th, 4pm

Exercise 1: Binary Search Tree - Range Queries (10 Points)

- (a) Implement the binary search tree (BST) data structure and the `insert` operation. You can use the template `BST.py`. (4 Points)
- (b) Implement the operation `getrange(x_{min}, x_{max})` efficiently on binary search trees which returns all keys x in the tree with $x_{min} \leq x < x_{max}$ (cf. lecture notes week 6 slide 21). (4 Points)
- (c) Use your implementation of BST and your `insert` function to insert all words from the file `inputs.txt` into a BST with respect to the lexicographic ordering on words over the alphabet $\{a, \dots, z\}$ ¹. Use your data structure to output all words from the BST beginning with a certain prefix.² Output all words with prefix “qw”. Copy the result into your `experiences.txt` file. (2 Points)

Sample Solution

Cf. `BST.py` for part (a) and (b). For part (c) it was sufficient to run `getrange('qw', 'qx')` on the BST filled with the words from `input.py`. The correct output is `['qwb', 'qwdjbcsm', 'qweli', 'qwgconj', 'qwgzykg', 'qwivkay', 'qwlybcn', 'qwmwwi', 'qwo', 'qwohudf', 'qwpoth', 'qwqrn', 'qwrmd', 'qwtq', 'qwxpyjl', 'qwxrm', 'qwyiwh']`.

Exercise 2: Binary Search Tree - Operations (10 Points)

- (a) Describe a function which returns the depth of a binary search tree and analyze the runtime. (2 Points)
- (b) Describe a function that for a given binary search tree with n nodes and a given $k \leq n$ returns a list with the k smallest keys from the tree. Analyze the runtime. (4 Points)
- (c) Describe a function that takes a binary search tree B and a key x as input and generates the following output:
- If there is an element v in B with $v.key = x$, return v .
 - Otherwise, return the pair (u, w) where u is the tree element with the next smaller key and w is the element with the next larger key. It should be $u = \text{None}$ if x is smaller than any key in the tree and $w = \text{None}$ if x is larger than any key in the tree.

For your description you can use pseudo code or a sufficiently detailed description in English.

Analyze the runtime of your function. (4 Points)

¹Python supports the comparison of strings with respect to the lexicographic ordering, i.e., you can use “<”, “<=”.

²If you enter `Python3` and `from BST import BST` into the command prompt you can use the class `BST` from the command line. We provided a method for inserting the content of `inputs.txt`.

Sample Solution

- (a) We can do a recursive traversal of the tree where we keep track of the current recursion depth. Then a call of `depth(r)` on the root r of the BST returns its depth.

Algorithm 1 `depth(v, R)`

```
if v = None then
    return -1  $\triangleright$  depth of a childless node must be 0, hence we define the depth of None as -1
else return max(depth(v.left)+1, depth(v.right)+1)
```

The runtime corresponds to the runtime of the traversal of the whole tree which is $\mathcal{O}(n)$ as we have just one recursive call for each node and each recursive call costs $\mathcal{O}(1)$ (c.f., pre-, in-, post-order traversal algorithms given in the lecture).

As an alternative solution, we can run a BFS which takes $\mathcal{O}(n)$. If v is the node visited last by the BFS, do

Algorithm 2 `traverse-up(v)`

```
d ← 0
while v.parent ≠ None do
    d ← d + 1
    v ← v.parent
return d
```

This takes $\mathcal{O}(d)$ where d is the depth of the tree. Since $d \leq n$ the overall runtime is $\mathcal{O}(n+d) = \mathcal{O}(n)$.

- (b) Initialize an empty list K . We roughly do the following. Make an in-order traversal of the tree and each time visiting a node, add it to K . Stop if $|K| \geq k$. The following pseudocode formalizes this.

Algorithm 3 `inorder_variant(node)` \triangleright Assume list K is given globally, initially empty

```
if node ≠ None then
    inorder_variant(node.left)
    if |K| ≥ k then
        return
    K.append(v.key)
    inorder_variant(node.right)
```

The runtime is $\mathcal{O}(d+k)$ where d is the depth of the tree. We prove this in the following.

Let K be the set of k nodes representing the k smallest keys in the BST. Obviously, the in-order traversal must visit all nodes in K once. In accordance with the lecture a call of `inorder_variant(root)` adds all keys in ascending order to K .

Let A be the set of nodes in the BST on which are not in K but in which a recursive call will be made. Since the recursion is aborted (with the `return` statement) after reporting k nodes, the set A contains exactly the nodes which are ancestors of a node in K , but are not in K themselves. Since the runtime of a single recursive call (neglecting subcalls) is (1) the total runtime is $\mathcal{O}(|A| + |K|)$.

By definition we have $|K| = k$, so it remains to determine the size of A . We claim that all nodes in a A are on a path from the root to a leaf, that is, $|A| \leq d$. This is the case if there do not exist two nodes in A so that neither is an ancestor of the other.

For a contradiction, suppose that two such nodes u, v exist so that neither u is ancestor of v nor vice versa. Assume (without loss of generality) that $\text{key}(u) \leq \text{key}(v)$. That means u is in the left and v is in the right subtree of some common ancestor a of u and v .

By definition v has a node $w \in K$ in its subtree. Since v is in the right subtree and u is in the left subtree of a , we have $\text{key}(w) \geq \text{key}(u)$ and w has a higher in-order-position. But then we would have $u \in K$ as well, a contradiction to $u \in A$.

(c) **Algorithm 4** `return-closest(x)`

```
v ← find(x)
if v ≠ None then
  return v
else
  insert(x)
  (p, s) ← (pred(x), succ(x))
  delete(x)
  return (p, s)
```

All subprocedures that we call (`find`, `insert`, `pred`, `succ`) are known from the lecture and take $\mathcal{O}(d)$ with d being the depth of the tree. So the overall runtime is $\mathcal{O}(d)$.